# On the torsion-free connections on higher order frame bundles 

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#### Abstract

Using the $r$-jets of flows of vector fields, we show that every torsion-free linear $r$-th order connection $\Gamma$ on the tangent bundle of a manifold $M$ determines a reduction of the $(r+1)$-st order frame bundle of $M$ to the general linear group. We deduce that this reduction coincides with the well known reduction determined by the principal connection induced by $\Gamma$ on the $r$-th order frame bundle of $M$.


## Introduction

Our starting point is the fact that the principal connections on the $r$-th order frame bundle $P^{r} M$ of a manifold $M$ are in bijection with the linear $r$-th order connections on the tangent bundle $T M$, i.e. with the linear splittings

$$
\begin{equation*}
\Gamma: T M \rightarrow J^{r} T M \tag{1}
\end{equation*}
$$

of the jet projection $J^{r} T M \rightarrow T M$. We shall write

$$
\begin{equation*}
\widetilde{\Gamma}: P^{r} M \rightarrow J^{1} P^{r} M \tag{2}
\end{equation*}
$$

[^0]for the principal connection corresponding to (1). Its lifting map, denoted by the same symbol,
$$
\widetilde{\Gamma}: P^{r} M \times_{M} T M \rightarrow T P^{r} M
$$
is determined by
\[

$$
\begin{equation*}
\widetilde{\Gamma}(u, A)=\mathcal{P}^{r} X(u), \quad u \in P^{r} M, A \in T_{x} M, x \in M, \tag{3}
\end{equation*}
$$

\]

where $\mathcal{P}^{r} X$ is the flow prolongation of a vector field $X: M \rightarrow T M$ satisfying $j_{x}^{r} X=\Gamma(A)$, [3].

The structure group of $P^{r} M$ is $G_{m}^{r}, m=\operatorname{dim} M$. There is a canonical $\mathbb{R}^{m} \times \mathfrak{g}_{m}^{r-1}$-valued one-form $\Theta_{r}$ on $P^{r} M$. P. C. Yuen, [5], introduced the torsion of $\widetilde{\Gamma}$ as the exterior covariant differential

$$
\begin{equation*}
D_{\widetilde{\Gamma}} \Theta_{r}, \tag{4}
\end{equation*}
$$

see also [1]. On the other hand, the $(r-1)$-jet at $x$ of the bracket $[X, Y]$ of two vector fields $X, Y$ on $M$ depends on $j_{x}^{r} X$ and $j_{x}^{r} Y$ only. This defines a map

$$
\begin{equation*}
[,]_{r-1}: J^{r} T M \times_{M} J^{r} T M \rightarrow J^{r-1} T M . \tag{5}
\end{equation*}
$$

The torsion of $\Gamma$ can be introduced, [6], as a map

$$
\tau_{\Gamma}: T M \times_{M} T M \rightarrow J^{r-1} T M
$$

defined by

$$
\begin{equation*}
\tau_{\Gamma}(A, B)=[\Gamma(A), \Gamma(B)]_{r-1}, \quad A, B \in T_{x} M \tag{6}
\end{equation*}
$$

In [3] we deduced that the torsions $D_{\widetilde{\Gamma}} \Theta_{r}$ and $\tau_{\Gamma}$ coincide in a natural way.
There is a canonical injection $i_{r+1}: P^{r+1} M \rightarrow J^{1} P^{r} M$, see formula (13) below. If $\widetilde{\Gamma}$ is torsion-free, there is a well-known map $\varrho(\widetilde{\Gamma}): P^{1} M \rightarrow$ $P^{r+1} M$ defined by the induction

$$
\begin{equation*}
i_{r+1} \circ \varrho(\widetilde{\Gamma})=\widetilde{\Gamma} \circ \varrho\left(\widetilde{\Gamma}_{r-1}\right), \tag{7}
\end{equation*}
$$

where $\widetilde{\Gamma}_{r-1}$ is the underlying connection on $P^{r-1} M$, so that $\varrho\left(\widetilde{\Gamma}_{r-1}\right)$ : $P^{1} M \rightarrow P^{r} M$ by the induction hypothesis. If we consider the canonical injection $G L(m, \mathbb{R}) \hookrightarrow G_{m}^{r+1},[4]$, p. 130, then $\varrho(\widetilde{\Gamma})\left(P^{1} M\right)$ is a reduction of
$P^{r+1} M$ to $G L(m, \mathbb{R})$. This establishes the well-known bijection between the torsion-free connections on $P^{r} M$ and the reductions of $P^{r+1} M$ to $G L(m, \mathbb{R}),[2],[3]$.

In Section 1 of the present paper we use the $r$-jets of flows of vector fields to construct a map $\sigma(\Gamma): P^{1} M \rightarrow P^{r+1} M$ for every torsion-free linear $r$-th order connection $\Gamma$ on $T M$. Our proof of the fact that $\sigma(\Gamma)\left(P^{1} M\right)$ is a reduction of $P^{r+1} M$ to $G L(m, \mathbb{R})$ is based on two interesting lemmas concerning the $r$-jets of the bracket of vector fields, the proofs of which we postpone to Section 3. In Section 2 we deduce $\sigma(\Gamma)=\varrho(\widetilde{\Gamma})$, i.e. both constructions of a reduction of $P^{r+1} M$ to $G L(m, \mathbb{R})$ coincide.

All manifolds and maps are assumed to be infinitely differentiable. Unless otherwise specified, we use the terminology and notation from the book [4].

## 1. The reduction $\sigma(\Gamma)$

Consider $\Gamma: T M \rightarrow J^{r} T M$. For a linear frame $u \in P_{x}^{1} M, u=$ $\left(A_{1}, \ldots, A_{m}\right), A_{i} \in T_{x} M$, we take vector fields $X_{i}$ satisfying $j_{x}^{r} X_{i}=\Gamma\left(A_{i}\right)$, $i=1, \ldots, m$. Then

$$
\left(F l_{t^{1}}^{X_{1}} \circ \cdots \circ F l_{t^{m}}^{X_{m}}\right)(x)
$$

is a local map $\mathbb{R}^{m} \rightarrow M$ and we define

$$
\begin{equation*}
\sigma(\Gamma)(u)=j_{0}^{r+1}\left(F l_{t^{1}}^{X_{1}} \circ \cdots \circ F l_{t^{m}}^{X_{m}}\right)(x) \in P_{x}^{r+1} M \tag{8}
\end{equation*}
$$

where $0 \in \mathbb{R}^{m}$. One verifies easily that $\sigma(\Gamma)(u)$ depends on $u$ and $\Gamma$ only.
Proposition 1. If $\Gamma$ is torsion-free, then $\sigma(\Gamma)\left(P^{1} M\right)$ is a reduction of $P^{r+1} M$ to $G L(m, \mathbb{R})$.

The proof will be based on the following two lemmas, the proofs of which we postpone to the last section.

Consider two vector fields $X$ and $Y$ on $M$. Then $\left(F l_{t}^{X} \circ F l_{\tau}^{Y}\right)(x)$ is a local map $\mathbb{R}^{2} \rightarrow M$, so that $j_{0,0}^{r+1}\left(F l_{t}^{X} \circ F l_{\tau}^{Y}\right)(x) \in\left(T_{2}^{r+1} M\right)_{x}$ is a $(2, r+1)$-velocity on $M$.

Lemma 1. If $j_{x}^{r-1}[X, Y]=0$, then

$$
\begin{equation*}
j_{0,0}^{r+1}\left(F l_{t}^{X} \circ F l_{\tau}^{Y}\right)(x)=j_{0,0}^{r+1}\left(F l_{\tau}^{Y} \circ F l_{t}^{X}\right)(x) \tag{9}
\end{equation*}
$$

Further, $\left(F l_{t}^{X} \circ F l_{t}^{Y}\right)(x)$ is a local map $\mathbb{R} \rightarrow M$, so that $j_{0}^{r+1}\left(F l_{t}^{X} \circ\right.$ $\left.F l_{t}^{Y}\right)(x) \in\left(T_{1}^{r+1} M\right)_{x}$ is a $(1, r+1)$-velocity on $M$.

Lemma 2. If $j_{x}^{r-1}[X, Y]=0$, then

$$
\begin{equation*}
j_{0}^{r+1}\left(F l_{t}^{X} \circ F l_{t}^{Y}\right)(x)=j_{0}^{r+1}\left(F l_{t}^{X+Y}\right)(x) . \tag{10}
\end{equation*}
$$

Now we prove Proposition 1 by using Lemmas 1 and 2 . We shall also use the well known formula

$$
\begin{equation*}
F l_{a t}^{X}=F l_{t}^{a X}, \quad a \in \mathbb{R} . \tag{11}
\end{equation*}
$$

Take $g=\left(a_{j}^{i}\right) \in G L(m, \mathbb{R}), u=\left(A_{i}\right) \in P_{x}^{1} M$ and consider $u g=\left(a_{i}^{j} A_{j}\right)$. Write $\Gamma\left(A_{i}\right)=j_{x}^{r} X_{i}$. Since $\Gamma$ is torsion-free, by (10), (11) and (9) we obtain gradually

$$
\begin{aligned}
\sigma(\Gamma)(u g) & =j_{0}^{r+1}\left(F l_{t^{1}}^{a_{1}^{1} X_{1}+\cdots+a_{1}^{m} X_{m}} \circ \cdots \circ F l_{t^{m}}^{a_{m}^{1} X_{1}+\cdots+a_{m}^{m} X_{m}}\right) \\
& =j_{0}^{r+1}\left(F l_{t_{1}^{1}}^{a_{1}^{1} X_{1}} \circ \cdots \circ F l_{t_{1}^{1}}^{a_{1}^{m} X_{m}} \circ \cdots \circ F l_{t_{m}^{2}}^{a_{m}^{1} X_{1}} \circ \cdots \circ F l_{t_{m}^{m}}^{a_{m}^{m} X_{m}}\right) \\
& =j_{0}^{r+1}\left(F l_{a_{1}^{1} t^{1}}^{X_{1}} \circ \cdots \circ F l_{a_{1}^{m} t^{1}}^{X_{m}} \circ \cdots \circ F l_{a_{m}^{1} t^{m}}^{X_{1}} \circ \cdots \circ F l_{a_{m}^{m} t^{m}}^{X_{m}}\right) \\
& =j_{0}^{r+1}\left(F l_{a_{1}^{1} t^{1}+\cdots+a_{m}^{1} t^{m}}^{X_{1}} \circ \cdots \circ F l_{a_{1}^{m} t^{1}+\cdots+a_{m}^{m} t^{m}}^{X_{m}}\right) .
\end{aligned}
$$

This proves Proposition 1.

## 2. The main result

We shall use the following form of the canonical injection $i_{r+1}: P^{r+1} M \rightarrow J^{1} P^{r} M$. We have $P^{r} M \subset T_{m}^{r} M$, where $T_{m}^{r}$ is the functor of ( $m, r$ )-velocities. Clearly, $j_{0}^{r} f \in T_{m}^{r} M, f: \mathbb{R}^{m} \rightarrow M$, can be expressed in the form

$$
\begin{equation*}
j_{0}^{r} f=\left(T_{m}^{r} f\right)(e), \quad e=j_{0}^{r} \mathrm{id}_{\mathbb{R}^{m}} \tag{12}
\end{equation*}
$$

Write $E_{i}=\left.\frac{\partial}{\partial t}\right|_{0} j_{0}^{r} \tau_{t}^{i} \in T_{e} T_{m}^{r} \mathbb{R}^{m}$, where $\tau_{t}^{i}: \mathbb{R}^{m} \rightarrow \mathbb{R}^{m}$ is the translation $\bar{t}^{1}=t^{1}, \ldots, \bar{t}^{i}=t^{i}+t, \ldots, \bar{t}^{m}=t^{m}$. If we consider $j_{0}^{r+1} \psi \in P^{r+1} M$, then

$$
\begin{equation*}
\left(T T_{m}^{r} \psi\right)\left(E_{i}\right) \tag{13}
\end{equation*}
$$

is an $m$-tuple of tangent vectors at $j_{0}^{r} \psi \in P^{r} M$. The linear span of these vectors defines $i_{r+1}\left(j_{0}^{r+1} \psi\right) \in J^{1} P^{r} M$.

Proposition 2. If $\Gamma$ is a torsion-free linear $r$-th order connection on $T M$ and $\widetilde{\Gamma}$ is the corresponding principal connection on $P^{r} M$, then $\sigma(\Gamma)=\varrho(\widetilde{\Gamma})$.

Proof. We proceed by induction. If $\Gamma_{r-1}$ and $\widetilde{\Gamma}_{r-1}$ are the underlying connections in the order $r-1$, then

$$
\begin{equation*}
\sigma\left(\Gamma_{r-1}\right)=\varrho\left(\widetilde{\Gamma}_{r-1}\right) \tag{14}
\end{equation*}
$$

by the induction hypothesis. Consider $u=\left(A_{1}, \ldots, A_{m}\right) \in P_{x}^{1} M$ and write

$$
v=\sigma\left(\Gamma_{r-1}\right)(u)=\varrho\left(\widetilde{\Gamma}_{r-1}\right)(u)
$$

By $(13), i_{r+1}\left(j_{0}^{r+1}\left(F l_{t^{1}}^{X_{1}} \circ \cdots \circ F l_{t^{m}}^{X_{m}}\right)(x)\right)$ is the linear span of the vectors

$$
\begin{equation*}
T T_{m}^{r}\left(F l_{t^{1}}^{X_{1}} \circ \cdots \circ F l_{t^{m}}^{X_{m}}\right)\left(E_{i}\right) \tag{15}
\end{equation*}
$$

Using the basic properties of flows, Lemma 1 and (12), we deduce that (15) is equal to

$$
\begin{aligned}
& \left.\frac{\partial}{\partial t}\right|_{0} T_{m}^{r}\left(F l_{t^{1}}^{X_{1}} \circ \cdots \circ F l_{t+t^{i}}^{X_{i}} \circ \cdots \circ F l_{t^{m}}^{X_{m}}\right)(e) \\
& \quad=\left.\frac{\partial}{\partial t}\right|_{0}\left(F l_{t}^{\mathcal{T}_{m}^{r} X_{i}} \circ F l_{t^{1}}^{\mathcal{T}_{m}^{r} X_{1}} \circ \cdots \circ F l_{t^{m}}^{\mathcal{T}_{m}^{r} X_{m}}\right)(e) \\
& \quad=\mathcal{T}_{m}^{r} X_{i}\left(T_{m}^{r}\left(F l_{t^{1}}^{X_{1}} \circ \cdots \circ F l_{t_{m}}^{X_{m}}\right)(e)\right)=\mathcal{T}_{m}^{r} X_{i}(v)
\end{aligned}
$$

where $\mathcal{T}_{m}^{r} X_{i}$ denotes the flow prolongation of $X_{i}$. By (3) and by the induction hypothesis, this $m$-tuple spans $\varrho(\widetilde{\Gamma})(v)$.

## 3. The proofs of Lemmas 1 and 2

In general, if we have two maps $f, g: \mathbb{R}^{m} \rightarrow \mathbb{R}^{m}$, it suffices to verify the condition $j_{0}^{r} f=j_{0}^{r} g$ on all curves of the form $x^{i}=a^{i} t, i=1, \ldots, m,[4]$. By the flow property (11), Lemma 1 follows from the fact that $j_{x}^{r-1}[X, Y]=0$ implies

$$
\begin{equation*}
j_{0}^{r+1}\left(F l_{t}^{X} \circ F l_{t}^{Y}\right)(x)=j_{0}^{r+1}\left(F l_{t}^{Y} \circ F l_{t}^{X}\right)(x) \in T_{1}^{r+1} M \tag{16}
\end{equation*}
$$

But this is a direct consequence of Lemma 2. So it suffices to prove Lemma 2. We have the following 3 cases.
I. If $X(x)=Y(x)=0$, then the $(r+1)$-jets of the flows of $X$ and $Y$ are in the group of all invertible $(r+1)$-jets of $M$ into $M$ with source $x$ and target $x$ and we have a well known result concerning Lie groups.
II. If $X(x) \neq 0$, we can consider such local coordinates on $M$ that $X=\frac{\partial}{\partial x^{1}}$. Then $j_{x}^{r-1}\left[\frac{\partial}{\partial x^{1}}, Y\right]=0$ means

$$
\begin{equation*}
D_{\alpha} \frac{\partial Y^{i}(x)}{\partial x^{1}}=0, \quad 0 \leq\|\alpha\| \leq r-1 \tag{17}
\end{equation*}
$$

where $Y^{i}$ are the coordinate components of $Y$ and $D_{\alpha}$ denotes the partial derivative with respect to a multiindex $\alpha$ of the range $m$.

The flow $\psi^{i}(t, x)$ of the vector field $\frac{\partial}{\partial x^{1}}+Y$ satisfies

$$
\begin{equation*}
\frac{\partial \psi^{i}(t, x)}{\partial t}=\delta_{1}^{i}+Y^{i}(\psi(t, x)) \tag{18}
\end{equation*}
$$

If $\eta^{i}(t, x)$ denotes the flow of $Y$, then the coordinate expression of $F l_{t}^{X} \circ F l_{t}^{Y}$ is

$$
\begin{equation*}
\mu^{i}(t, x)=\delta_{1}^{i} t+\eta^{i}(t, x) \tag{19}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\frac{\partial \mu^{i}(t, x)}{\partial t}=\delta_{1}^{i}+\frac{\partial \eta^{i}(t, x)}{\partial t}=\delta_{1}^{i}+Y^{i}(\eta(t, x)) \tag{20}
\end{equation*}
$$

From (19) we obtain

$$
\begin{equation*}
\frac{\partial^{k} \mu^{i}(t, x)}{\partial t^{k}}=\frac{\partial^{k} \eta^{i}(t, x)}{\partial t^{k}}, \quad k \geq 2 \tag{21}
\end{equation*}
$$

For $t=0$, (18) and (20) yield directly $\frac{\partial \psi^{i}(0, x)}{\partial t}=\frac{\partial \mu^{i}(0, x)}{\partial t}$. Then we find by direct evaluation

$$
\begin{align*}
& \frac{\partial^{2} \psi^{i}(t, x)}{\partial t^{2}}=\frac{\partial Y^{i}(\psi(t, x))}{\partial x^{j}} \frac{\partial \psi^{j}(t, x)}{\partial t}  \tag{22}\\
& \frac{\partial^{2} \mu^{i}(t, x)}{\partial t^{2}}=\frac{\partial Y^{i}(\eta(t, x))}{\partial x^{j}} \frac{\partial \eta^{j}(t, x)}{\partial t} \tag{23}
\end{align*}
$$

Hence (17) implies

$$
\begin{equation*}
\frac{\partial^{2} \psi^{i}(0, x)}{\partial t^{2}}=\frac{\partial^{2} \mu^{i}(0, x)}{\partial t^{2}} \tag{24}
\end{equation*}
$$

By iteration we deduce (10) for every $r$.
III. The case $Y(x) \neq 0$ can be reduced to II by using $F l_{t}^{X} \circ F l_{t}^{Y}=\left(F l_{-t}^{Y} \circ\right.$ $\left.F l_{-t}^{X}\right)^{-1}$.

This proves Lemmas 1 and 2.

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