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Certain curvature restrictions on a quasi Einstein manifold

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Abstract. Quasi Einstein manifold is a simple and natural generalization of Einstein manifold. We prove that a quasi-conformally flat quasi Einstein manifold is of quasi-constant curvature, and that a conformally flat pseudo symmetric manifold is a quasi Einstein manifold. Also conditions are found for a quasi Einstein manifold to be quasi conformally conservative.

Introduction

The notion of quasi Einstein manifold was introduced by M. C. CHAKI and R. K. MAITY [1]. A non-flat Riemannian manifold (M^n, g) (n > 2) is defined to be a quasi Einstein manifold if its Ricci tensor S of type (0, 2)is not identically zero and satisfies the condition

$$S(X,Y) = a g(X,Y) + b A(X)A(Y)$$
(1)

where a, b are scalars of which $b \neq 0$ and A is a non-zero 1-form such that

$$g(X,U) = A(X) \tag{2}$$

for all vector fields X; U being a unit vector field. In such a case a, b are called associated scalars. A is called the associated 1-form and U is called

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the generator of the manifold. An *n*-dimensional manifold of this kind is denoted by the symbol $(QE)_n$. If either the 1-form A or the associated scalar b, or both of them are are zero, then the manifold reduces to an Einstein manifold.

A Riemannian manifold of quasi-constant curvature was given by B. Y. CHEN and K. YANO [2] as a conformally flat manifold with the curvature tensor 'R of type (0, 4) which satisfies the condition

$${}^{\prime}R(X,Y,Z,W) = p[g(Y,Z)g(X,W) - g(X,Z)g(Y,W)] + q[g(X,W)T(Y)T(Z) - g(X,Z)T(Y)T(W) + g(Y,Z)T(X)T(W) - g(Y,W)T(X)T(Z)]$$
(3)

where R(X, Y, Z, W) = g(R(X, Y)Z, W), R is the curvature tensor of type (1,3), p, q are scalar functions, T is a non-zero 1-form defined by

$$g(X,\tilde{\rho}) = T(X),\tag{4}$$

and $\tilde{\rho}$ is a unit vector field.

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It can be easily seen that if the curvature tensor 'R is of the form (3), then the manifold is conformally flat. On the other hand, GH. VRANCEANU [3] defined the notion of almost constant curvature. Later A. L. MOCANU [4] pointed out that the manifold introduced by CHEN and YANO and the manifold introduced by GH. VRANCEANU are the same. If q = 0, then it reduces to a manifold of constant curvature.

The notion of quasi-conformal curvature tensor

$$C^{*}(X,Y)Z = a_{1}R(X,Y)Z + b_{1}[S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY]$$

$$- \frac{r}{n} \left[\frac{a_{1}}{n-1} + 2b_{1} \right] [g(Y,Z)X - g(X,Z)Y]$$
(5)

was given by YANO and SAWAKI [5]. Here a_1 and b_1 are constants, R is the Riemannian curvature tensor of type (1,3), S is the Ricci tensor of type (0,2), Q is the Ricci operator and r is the scalar curvature of the manifold. If $a_1 = 1$ and $b_1 = -\frac{1}{n-2}$, then (5) takes the form

$$C^{*}(X,Y)Z = R(X,Y)Z - \frac{1}{n-2}[S(Y,Z)X - S(X,Z)Y]$$

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$$+ g(Y,Z)QX - g(X,Z)QY]$$

$$- \frac{r}{(n-1)(n-2)} [g(Y,Z)X - g(X,Z)Y] = C(X,Y)Z,$$
(6)

where C is the conformal curvature tensor [6]. Thus the conformal curvature tensor C is a particular case of the tensor C^* . For this reason C^* is called the quasi-conformal curvature tensor.

A manifold (M^n, g) (n > 3) shall be called quasi-conformally flat or quasi-conformally conservative according as $C^* = 0$ or div $C^* = 0$. It is known [7] that a quasi-conformally flat space is either conformally flat or Einstein . Since an Einstein manifold need not be conformally flat, a quasi-conformally flat manifold need not be conformally flat.

A non-flat Riemannian manifold (M^n, g) $(n \ge 2)$ is said to be a pseudo symmetric manifold [8] if its curvature tensor R satisfies the condition

$$(\nabla_X R)(Y, Z)W = 2B(X)R(Y, Z)W + B(Y)R(X, Z)W + B(Z)R(Y, X)W$$
$$+ B(W)R(Y, Z)X + g(R(Y, Z)W, X)\tilde{U}$$
(7)

where B is a non-zero 1-form,

$$g(X, \tilde{U}) = B(X) \quad \forall X \tag{8}$$

and ∇ denotes the operator of covariant differentiation with respect to the metric tensor g. Such a manifold is denoted by $(PS)_n$ $(n\geq 2)$. It may be mentioned that CHAKI's pseudo symmetric manifold is different from that of R. DESZCZ [9].

It is known [10, p. 93] that a conformally flat Einstein manifold is of constant curvature. In the present paper we have generalized this result to a quasi-conformally flat quasi Einstein manifold and we prove that a quasiconformally flat $(QE)_n$ (n > 3) is a manifold of quasi-constant curvature. In Section 2 we look for a sufficient condition in order that a $(QE)_n$ (n > 3)may be quasi-conformally conservative. Next we study conformally flat pseudo symmetric manifolds and prove that such a manifold is a quasi-Einstein manifold. Finally we obtain a sufficient condition for a pseudo symmetric manifold to be a quasi-Einstein manifold.

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1. Quasi-conformally flat quasi Einstein manifold

From (5) we get

where $C^*(X, Y, Z, W) = g(C^*(X, Y)Z, W)$ and R(X, Y, Z, W) = g(R(X, Y)Z, W). If the manifold is quasi-conformally flat, then we have

$${}^{\prime}R(X,Y,Z,W) = \frac{b_1}{a_1} [S(X,Z)g(Y,W) - S(Y,Z)g(X,W) + S(Y,W)g(X,Z) - S(X,W)g(Y,Z)] - \frac{r}{n a_1} \left[\frac{a_1}{n-1} + 2b_1\right] [g(Y,Z)g(X,W) - g(X,Z)g(Y,W)].$$
(1.2)

Using (1) in (1.2) we have

$${}^{\prime}R(X,Y,Z,W) = -\left[2b_{1}a + \frac{r}{n}(\frac{a_{1}}{n-1} + 2b_{1})\right] [g(Y,Z)g(X,W) - g(X,Z)g(Y,W)] - b_{1}b[g(X,W)A(Y)A(Z) - g(Y,W)A(X)A(Z) + g(Y,Z)A(X)A(W) - g(X,Z)A(Y)A(W)],$$
(1.3)

which implies that the manifold is a manifold of quasi-constant curvature. Hence we can state that

Theorem 1. A quasi-conformally flat quasi Einstein manifold $(QE)_n$ (n > 3) is a manifold of quasi-constant curvature.

2. $(QE)_n \ (n > 3)$ with divergence free quasi-conformal curvature tensor

In this section we look for a sufficient condition in order that a $(QE)_n$ (n > 3) may be quasi-conformally conservative. Quasi-conformal curvature tensor is said to be conservative [11] if divergence of C^* vanishes, i.e., div $C^* = 0$.

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In a $(QE)_n$ if both a and b are constant, then contracting (1) we have r = an + b, i.e. r = constant, where r is the scalar curvature, i.e., dr = 0. Using this from (5) we obtain

$$(\nabla_W C^*)(X, Y, Z) = a_1(\nabla_W R)(X, Y)Z + b_1[(\nabla_W S)(Y, Z)X - (\nabla_W S)(X, Z)Y + g(Y, Z)(\nabla_W Q)X - g(X, Z)(\nabla_W Q)Y].$$
(2.1)

We know that $(\operatorname{div} R)(X, Y, Z) = (\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z)$ [10], and from (1) we get $(\nabla_X S)(Y, Z) = b[(\nabla_X A)(Y)A(Z) + (\nabla_X A)(Z)A(Y),$ since both *a* and *b* are constant. Hence contracting (2.1)we obtain

$$(\operatorname{div} C^*)(X, Y, Z) = 2b(a_1 + b_1)[(\nabla_X A)(Y)A(Z) + (\nabla_X A)(Z)A(Y) - (\nabla_Y A)(X)A(Z) - (\nabla_Y A)(Z)A(X)] + bb_1[(\nabla_U A)(X)$$
(2.2)
+ $A(X)\operatorname{div} U]g(Y, Z) - bb_1[(\nabla_U A)(Y) + A(Y)\operatorname{div} U]g(X, Z).$

Imposing the condition that the generator U of the manifold is a recurrent vector field [12] with associated 1-form A not being the 1-form of recurrence, gives $\nabla_X U = B(X)U$, where B is the 1-form of recurrence. Hence $g(\nabla_X U, Y) = g(B(X)U, Y)$, that is,

$$(\nabla_X A)(Y) = B(X)A(Y). \tag{2.3}$$

In view of (2.3), (2.2) is expressed as follows

$$(\operatorname{div} C^*)(X, Y, Z) = 2b(a_1 + b_1)[B(X)A(Y)A(Z) - B(Z)A(X)A(Y)] + 2bb_1B(U)A(X)g(Y, Z) - 2bb_1g(X, Z)B(U)A(Y). \quad (2.4)$$

Since $(\nabla_X A)(U) = 0$, it follows from (2.3) that B(X) = 0. Hence from (2.4) it follows that $(\operatorname{div} C^*)(X, Y, Z) = 0$. Thus we can state the following:

Theorem 2. If in a $(QE)_n$ (n > 3) the associated scalars are constants and the generator U of the manifold is a recurrent vector field with the associated 1-form A not being the 1-form of recurrence, then the manifold is quasi-conformally conservative.

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3. Conformally flat pseudo symmetric manifolds

It is known [8] that in a conformally flat $(PS)_n$ $(n \ge 3)$

$$(n-1)B(X)S(Y,Z) - (n-1)B(Y)S(X,Z) - rB(X)g(Y,Z) + rB(Y)g(X,Z) + D(X)g(Y,Z) - D(Y)g(X,Z) = 0, \quad (3.1)$$

where D is a 1-form defined by

$$D(X) = B(QX), \tag{3.2}$$

Q denotes the symmetric endomorphism of the tangent space at each point corresponding to the Ricci tensor S, i.e. g(QX, Y) = S(X, Y) for every vector fields X, Y. Putting $Z = \tilde{U}$ in (3.1), where $g(X, \tilde{U}) = B(X)$ we get

$$B(X)D(Y) - B(Y)D(X) = 0.$$
 (3.3)

Hence
$$D(X) = tB(X),$$
 (3.4)

where t is a scalar. Using (3.4), it follows from (3.1) that

$$S(Y,Z) = \frac{r-t}{n-1}g(Y,Z) + \frac{nt-r}{(n-1)B(\tilde{U})}B(Y)B(Z)$$
(3.5)

which implies that the manifold is a quasi Einstein manifold. Thus we state

Theorem 3. A conformally flat pseudo symmetric manifold $(PS)_n$ $(n \ge 3)$ is a quasi Einstein manifold.

4. Sufficient condition for a pseudo symmetric manifold to be a quasi Einstein manifold

Now contracting (7) we get

$$(\nabla_X S)(Y,Z) = 2B(X)S(Y,Z) + B(Y)S(X,Z) + B(Z)S(Y,X) + B(R(X,Y)Z) + B(R(X,Z)Y).$$
(4.1)

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In a Riemannian manifold, a vector field ρ defined by $g(X, \rho) = A(X)$ for any vector field X is said to be a concircular vector field [12] if

$$(\nabla_X A)(Y) = \alpha g(X, Y) + \omega(X)A(Y), \qquad (4.2)$$

where α is a non-zero scalar and ω is a closed 1-form. If ρ is a unit vector, then the equation (4.2) can be written as

$$(\nabla_X A)(Y) = \alpha[g(X, Y) - A(X)A(Y)]. \tag{4.3}$$

We suppose that a $(PS)_n$ admits a unit concircular vector field defined by (4.3), where α is a non-zero constant. Applying the Ricci idetity to (4.3) we obtain

$$A(R(X,Y)Z) = -\alpha^2 [g(X,Z)A(Y) - g(Y,Z)A(X)].$$
(4.4)

Putting $Y = Z = e_i$ in (4.4), and taking summation over $i, 1 \le i \le n$, where $\{e_i\}$ is an orthonormal basis of the tangent space at each point of the manifold, we get

$$A(QX) = (n-1)\alpha^2 A(X),$$

where Q is the Ricci operator defined by g(QX, Y) = S(X, Y), which implies

$$S(X, \rho) = (n-1)\alpha^2 A(X).$$
 (4.5)

From (4.5) we have

$$(\nabla_Y S)(X,\rho) = (n-1)\alpha^3 g(X,Y) - \alpha S(X,Y).$$
(4.6)

Using (4.4) we obtain

$$g(R(X,Y)Z,\rho) = -\alpha^2 [g(X,Z)A(Y) - g(Y,Z)A(X)]$$

or,
$$g(R(Z,\rho)X,Y) = -\alpha^2 [g(X,Z)g(Y,\rho) - g(Z,Y)A(X)]$$

or,
$$R(Z,\rho)X = -\alpha^2 [g(X,Z)\rho - A(X)Z],$$

which implies

$$B(R(Z,\rho)X) = -\alpha^{2}[g(X,Z)B(\rho) - A(X)B(Z)]$$

i.e.,
$$B(R(X,\rho)Y) = -\alpha^{2}[g(X,Y)B(\rho) - A(Y)B(X)].$$
 (4.7)

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Similarly we have

$$B(R(X,Y)\rho) = -\alpha^{2}[A(Y)B(X) - A(X)B(Y)].$$
 (4.8)

In (4.1) putting $Z = \rho$ and using (4.5),(4.6), (4.7) and (4.8) we have

$$-(\alpha + B(\rho))S(X,Y) = -[\alpha^2 B(\rho) + (n-1)\alpha^3]g(X,Y) + 2(n-1)\alpha^2 B(X)A(Y) + n\alpha^2 B(Y)A(X).$$
(4.9)

Putting $Y = \rho$ in (4.9) and using (4.5) we have

$$B(\rho)A(X) + (n-1)A(X) = 0 \quad \forall X$$

i.e. $B(X) = -\frac{B(\rho)}{n-1}A(X).$ (4.10)

Let us impose the condition

$$\alpha + B(\rho) \neq 0. \tag{4.11}$$

Putting (4.10) in (4.9) we obtain

$$S(X,Y) = \frac{\alpha^2 [B(\rho) + (n-1)\alpha]}{\alpha + B(\rho)} g(X,Y) + \frac{(3n-2)B(\alpha)}{(\alpha + B(\rho))(n-1)} A(X)A(Y)$$

i.e. $S(X,Y) = ag(X,Y) + bA(X)A(Y),$ (4.12)

where $a = \frac{\alpha^2 [B(\rho) + (n-1)\alpha]}{\alpha + B(\rho)}$ and $b = \frac{(3n-2)B(\alpha)}{(\alpha + B(\rho))(n-1)}$. Thus we can state

Theorem 4. If a pseudo symmetric manifold admits a unit concircular vector field whose associated scalar is a non-zero constant and satisfy the condition (4.11), then the manifold reduces to a quasi Einstein manifold.

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