# On a certain application of Patterson's curvature identity 

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#### Abstract

We present curvature properties of four-dimensional semi-Riemannian manifolds satisfying some condition of pseudosymmetry type. We prove that every such manifold with non-zero associated function $L$ is pseudosymmetric, its scalar curvature does not vanish and $L$ must be equal to $\frac{1}{3}$. We also describe non-trivial example of a manifold realizing all these coditions.


## 1. Introduction

Let $(M, g)$ be a connected $n$-dimensional, $n \geq 3$, semi-Riemannian manifold of class $C^{\infty}$. We denote by $\nabla, R, C, S$ and $\kappa$ the Levi-Civita connection, the Riemann-Christoffel curvature tensor, the Weyl conformal curvature tensor, the Ricci tensor and the scalar curvature of $(M, g)$, respectively.
E. M. Patterson [13] has given (among others algebraic identities satisfied by the curvature tensor) the following result

Proposition 1.1. The Weyl conformal curvature tensor $C$ of every 4-dimensional Riemannian manifold satisfies the identity

$$
\begin{aligned}
g_{h m} C_{l i j k} & +g_{l m} C_{i h j k}+g_{i m} C_{h l j k}+g_{h j} C_{l i k m}+g_{l j} C_{i h k m} \\
& +g_{i j} C_{h l k m}+g_{h k} C_{l i m j}+g_{l k} C_{i h m j}+g_{i k} C_{h l m j}=0 .
\end{aligned}
$$

The above identity plays an important role in investigations of the curvature properties of 4-dimensional semi-Riemannian manifolds. Among

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others, the authors of the present paper have used the Patterson's identity during the study of 4-dimensional manifolds of pseudosymmetry type ([3], [8]).

A semi-Riemannian manifold $(M, g)$ is said to be semisymmetric [14] if $R \cdot R=0$ holds on $M$. As a proper generalization of locally symmetric spaces $(\nabla R=0)$ semisymmetric manifolds were studied by many authors. In the Riemannian case, Z. I. Szabó obtained in the early eighties a full intrinsic classification of semisymmetric Riemannian manifolds [14]. Very recently a theory of Riemannian semisymmetric manifolds has been presented in the monograph [1].

The profound investigation of several properties of semisymmetric manifolds, gave rise to their next generalization: the pseudosymmetric manifolds.

A semi-Riemannian manifold $(M, g)$ is said to be pseudosymmetric ([6], Section 3.1) if at every point of $M$ the following condition is satisfied:
$(*)_{1} \quad$ the tensors $R \cdot R$ and $Q(g, R)$ are linearly dependent.
This condition is equivalent to the relation $R \cdot R=L_{R} Q(g, R)$ on the set $\mathcal{U}_{R}=\left\{x \in M \left\lvert\, R-\frac{\kappa}{n(n-1)} G \neq 0\right.\right.$ at $\left.x\right\}$, where $L_{R}$ is some function on $\mathcal{U}_{R}$. The definitions of the tensors used will be given in Section 2. There exist various examples of pseudosymmetric manifolds which are nonsemisymmetric and a review of results on pseudosymmetric manifolds is given in [6] (see also [15]).

It is easy to see that if $(*)_{1}$ holds on a semi-Riemannian manifold $(M, g)$, then at every point of $M$ the following condition is satisfied:
$(*)_{2} \quad$ the tensors $R \cdot S$ and $Q(g, S)$ are linearly dependent.
The converse statement is not true ([6], Section 8.1). A semi-Riemannian manifold $(M, g)$ is called Ricci-pseudosymmetric ([6], Section 4.1) if at every point of $M$ the condition $(*)_{2}$ is fulfilled. If a manifold $(M, g)$ is Ricci-pseudosymmetric then the relation $R \cdot S=L_{S} Q(g, S)$ holds on the set $\mathcal{U}_{S}=\left\{x \in M \left\lvert\, S \neq \frac{\kappa}{n} g\right.\right.$ at $\left.x\right\}$, where $L_{S}$ is a certain function on $\mathcal{U}_{S}$.

It is easy to verify that if $(*)_{1}$ holds on a semi-Riemannian manifold $(M, g), n \geq 4$, then at every point of $M$ the following condition is satisfied:
$(*)_{3} \quad$ the tensors $R \cdot C$ and $Q(g, C)$ are linearly dependent.

The converse statement is not true (cf. Example 4.1; see also [6], Section 9.3).

A semi-Riemannian manifold $(M, g), n \geq 4$, is called Weyl-pseudosymmetric if at every point of $M$ the condition $(*)_{3}$ is fulfilled. If a manifold $(M, g)$ is Weyl-pseudosymmetric then the relation $R \cdot C=L_{C} Q(g, C)$ holds on the set $\mathcal{U}_{C}=\{x \in M \mid C \neq 0$ at $x\}$, where $L_{C}$ is some function on $\mathcal{U}_{C}$.

Evidently, every semi-Riemannian semisymmetric manifold realizes trivially at every point the following condition ([9])
(*) the tensors $R \cdot C$ and $Q(S, C)$ are linearly dependent.
This condition is equivalent to the relation

$$
\begin{equation*}
R \cdot C=L Q(S, C) \tag{1}
\end{equation*}
$$

on the set $\mathcal{U}=\{x \in M \mid Q(S, C) \neq 0$ at $x\}$, for a certain function $L$ on $\mathcal{U}$. There exist non-semisymmetric manifolds realizing ( $*$ ) ([9], [10]).

Semi-Riemannian manifolds realizing $(*)_{1},(*)_{2},(*)_{3}$ and $(*)$ or other conditions of this kind, are called manifolds of pseudosymmetry type.

Recently 4-dimensional warped product manifolds $M \times{ }_{F} N, \operatorname{dim} M=1$, satisfying the condition $(*)$ have been considered in [10]. In the present paper we investigate arbitrary 4-dimensional semi-Riemannian manifolds fulfilling (*). In Section 2 we fix the notations and present auxiliary lemmas. In Section 3 we consider 4-dimensional manifolds satisfying the equality $Q(S, C)=0$ and we prove that such manifolds are semisymmetric and their scalar curvature is equal to zero. In Section 4 we investigate 4-dimensional manifolds satisfying (1) with $L \neq 0$. We prove, among others, that every such manifold is pseudosymmetric with $L_{R}=\frac{\kappa}{12}$, its scalar curvature does not vanish and the associated function $L$ must be equal to $\frac{1}{3}$. Finally, we describe an example of a manifold having all these properties.

## 2. Preliminaries

Let $(M, g)$ be an $n$-dimensional, $n \geq 3$, semi-Riemannian manifold. The Ricci operator $\mathcal{S}$ is defined by $g(\mathcal{S} X, Y)=S(X, Y)$, where $X, Y \in$ $\Xi(M), \Xi(M)$ being the Lie algebra of vector fields on $M$. Next, we define
the endomorphisms $\mathcal{R}(X, Y), \mathcal{C}(X, Y)$ and $X \wedge Y$ of $\Xi(M)$ by

$$
\begin{aligned}
\mathcal{R}(X, Y) Z & =\left[\nabla_{X}, \nabla_{Y}\right] Z-\nabla_{[X, Y]} Z \\
\mathcal{C}(X, Y) Z & =\mathcal{R}(X, Y) Z-\frac{1}{n-2}\left(X \wedge \mathcal{S} Y+\mathcal{S} X \wedge Y-\frac{\kappa}{n-1} X \wedge Y\right) Z, \\
(X \wedge Y) Z & =g(Y, Z) X-g(X, Z) Y
\end{aligned}
$$

respectively, where $X, Y, Z \in \Xi(M)$. Now the Riemann-Christoffel curvature tensor $R$, the Weyl conformal curvature tensor $C$ and the ( 0,4 )-tensor $G$ of $(M, g)$ are defined by

$$
\begin{aligned}
& R\left(X_{1}, X_{2}, X_{3}, X_{4}\right)=g\left(\mathcal{R}\left(X_{1}, X_{2}\right) X_{3}, X_{4}\right), \\
& C\left(X_{1}, X_{2}, X_{3}, X_{4}\right)=g\left(\mathcal{C}\left(X_{1}, X_{2}\right) X_{3}, X_{4}\right), \\
& G\left(X_{1}, X_{2}, X_{3}, X_{4}\right)=g\left(\left(X_{1} \wedge X_{2}\right) X_{3}, X_{4}\right),
\end{aligned}
$$

respectively. A tensor $\mathcal{B}$ of type $(1,3)$ on $M$ is said to be a generalized curvature tensor if

$$
\begin{gathered}
\mathbb{X}_{1}, X_{2}, X_{3} \\
\mathcal{B}\left(X_{1}, X_{2}\right) X_{3}=0, \quad \mathcal{B}\left(X_{1}, X_{2}\right)+\mathcal{B}\left(X_{2}, X_{1}\right)=0, \\
B\left(X_{1}, X_{2}, X_{3}, X_{4}\right)=B\left(X_{3}, X_{4}, X_{1}, X_{2}\right),
\end{gathered}
$$

where $B\left(X_{1}, X_{2}, X_{3}, X_{4}\right)=g\left(\mathcal{B}\left(X_{1}, X_{2}\right) X_{3}, X_{4}\right)$.
For an ( 0,2 )-tensor field $A$ on $(M, g)$ we define the endomorphism $X \wedge_{A} Y$ of $\Xi(M)$ by $\left(X \wedge_{A} Y\right) Z=A(Y, Z) X-A(X, Z) Y$, where $X, Y, Z \in$ $\Xi(M)$. In particular we have $X \wedge_{g} Y=X \wedge Y$.

For an ( $0, k$ )-tensor field $T, k \geq 1$, an ( 0,2 )-tensor field $A$ and a generalized curvature tensor $\mathcal{B}$ on $(M, g)$ we define the tensors $B \cdot T$ and $Q(A, T)$ by

$$
\begin{aligned}
(B \cdot T)\left(X_{1}, \ldots, X_{k} ; X, Y\right)= & -T\left(\mathcal{B}(X, Y) X_{1}, X_{2}, \ldots, X_{k}\right) \\
& -\cdots-T\left(X_{1}, \ldots, X_{k-1}, \mathcal{B}(X, Y) X_{k}\right), \\
Q(A, T)\left(X_{1}, \ldots, X_{k} ; X, Y\right)= & -T\left(\left(X \wedge_{A} Y\right) X_{1}, X_{2}, \ldots, X_{k}\right) \\
& -\cdots-T\left(X_{1}, \ldots, X_{k-1},\left(X \wedge_{A} Y\right) X_{k}\right),
\end{aligned}
$$

where $X, Y, Z, X_{1}, X_{2}, \ldots \in \Xi(M)$. Putting in the above formulas $\mathcal{B}=\mathcal{R}$ or $\mathcal{B}=\mathcal{C}, T=R$ or $T=C$ or $T=S, A=g$ or $A=S$, we obtain the tensors
$R \cdot R, R \cdot C, R \cdot S, C \cdot S, Q(g, R), Q(g, C), Q(g, S)$ and $Q(S, C)$, respectively. Let $(M, g)$ be a semi-Riemannian manifold covered by a system of charts $\left\{W ; x^{k}\right\}$.
We denote by $g_{i j}, R_{h i j k}, S_{i j}, G_{h i j k}=g_{h k} g_{i j}-g_{h j} g_{i k}$ and

$$
\begin{align*}
C_{h i j k}= & R_{h i j k}-\frac{1}{n-2}\left(g_{h k} S_{i j}-g_{h j} S_{i k}+g_{i j} S_{h k}-g_{i k} S_{h j}\right)  \tag{2}\\
& +\frac{\kappa}{(n-1)(n-2)} G_{h i j k}
\end{align*}
$$

the local components of the metric tensor $g$, the Riemann-Christoffel curvature tensor $R$, the Ricci tensor $S$, the tensor $G$ and the Weyl tensor $C$, respectively. Further, we denote by $S_{i j}^{2}=S_{i r} S_{j}{ }^{r}$ and $S_{i}{ }^{j}=g^{j r} S_{i r}$ the local components of the tensor $S^{2}$ defined by $S^{2}(X, Y)=S(\mathcal{S} X, Y)$, and of the Ricci operator $\mathcal{S}$, respectively.

At the end of this section we present some results which will be used in the next sections.

Lemma 2.1 ([5], Lemma 1). Let a tensor $A_{l m h s_{1} \ldots s_{N}}$ of type $(0, N+3)$ be symmetric in $(l, m)$ and skew-symmetric in $(m, h)$. Then $A_{l m h s_{1} \ldots s_{N}}=0$.

Lemma 2.2 ([11], Lemma 2). Let $A$ and $D$ be two symmetric ( 0,2 )tensors at a point $x$ of a semi-Riemannian manifold $(M, g)$. If the condition $Q(A, D)=0$ is fulfilled at $x$, then the tensors $A$ and $D$ are linearly dependent at $x$.

Lemma 2.3 ([7], Theorem 1). Let $\mathcal{B}$ be a generalized curvature tensor at $x \in M$ such that the condition

$$
{ }_{X, Y, Z}^{\mathfrak{S}} \omega(X) \mathcal{B}(Y, Z)=0
$$

is satisfied for $\mathcal{B}$ and a covector $\omega$ at $x$, where $X, Y, Z \in T_{x}(M)$ and $\mathfrak{S}$ denotes the cyclic sum. If $\omega \neq 0$ then the following relation holds at $x: B \cdot B=Q(\operatorname{Ric}(\mathcal{B}), B)$.

Lemma 2.4 ([2], Proposition 4.1). Let $(M, g), \operatorname{dim} M \geq 3$, be a semiRiemannian manifold. Let $A$ be a non-zero symmetric ( 0,2 )-tensor and $\mathcal{B}$ a generalized curvature tensor at a point $x$ of $M$ satisfying the condition $Q(A, B)=0$.

Moreover, let $V$ be a vector at $x$ such that the scalar $\rho=a(V)$ is nonzero, where $a$ is the covector defined by $a(X)=A(X, V), X \in T_{x}(M)$.
(i) If the tensor $A-\frac{1}{\rho} a \otimes a$ vanishes then the relation

$$
\underset{X, Y, Z}{\mathfrak{S}} a(X) \mathcal{B}(Y, Z)=0
$$

holds at $x$, where $X, Y, Z \in T_{x}(M)$.
(ii) If the tensor $A-\frac{1}{\rho} a \otimes a$ is non-zero then the relation

$$
\rho B(X, Y, Z, W)=\lambda(A(X, W) A(Y, Z)-A(X, Z) A(Y, W))
$$

holds at $x$, where $\lambda \in \mathbb{R}$ and $X, Y, Z, W \in T_{x}(M)$.
Moreover, in both cases the following condition $B \cdot B=Q(\operatorname{Ric}(\mathcal{B}), B)$ holds at $x$.

Lemma 2.5 ([12], Theorems 1 and 2). Let ( $M, g$ ) be a Weyl-pseudosymmetric semi-Riemannian manifold satisfying the following condition

$$
{ }_{X, Y, Z}^{\mathfrak{S}} a(X) \mathcal{C}(Y, Z)=0,
$$

where $a$ is a 1 -form on $M$.
If $a \neq 0$ and $C \neq 0$ at a point $x \in M$, then the following relations are satisfied at $x$ :

$$
\begin{array}{ll}
L_{C}=\frac{\kappa}{n(n-1)}, & S(W, \mathcal{C}(X, Y) Z)=\frac{\kappa}{n} C(X, Y, Z, W), \\
Q\left(S-\frac{\kappa}{n} g, C\right)=0, & R \cdot R=L_{C} Q(g, R) .
\end{array}
$$

## 3. Manifolds with vanishing tensor field $Q(S, C)$

Theorem 3.1. Let $(M, g), \operatorname{dim} M=4$, be a semi-Riemannian manifold satisfying at a point $x$ of $M$ the equality $Q(S, C)=0$. If $S \neq 0$ and $C \neq 0$ at $x$, then the following relations

$$
\kappa=0, \quad R \cdot R=0
$$

hold at $x$. Moreover, there exists a non-zero covector $a$ at $x$ such that

$$
{ }_{X, Y, Z}^{\mathfrak{S}} a(X) \mathcal{C}(Y, Z)=0 .
$$

Proof. It is easy to verify that the following identity is satisfied on $M$

$$
\begin{align*}
& (C \cdot C)_{h i j k l m}=(R \cdot C)_{h i j k l m}  \tag{3}\\
& \quad+\frac{1}{n-2}\left(\frac{\kappa}{n-1} Q(g, C)_{h i j k l m}-Q(S, C)_{h i j k l m}\right) \\
& \quad-\frac{1}{n-2}\left(g_{h l} S_{m r} C^{r}{ }_{i j k}-g_{h m} S_{l r} C^{r}{ }_{i j k}-g_{i l} S_{m r} C^{r}{ }_{h j k}\right. \\
& \quad+g_{i m} S_{l r} C^{r}{ }_{h j k}+g_{j l} S_{m r} C^{r}{ }_{k h i}-g_{j m} S_{l r} C^{r}{ }_{k h i} \\
& \left.\quad-g_{k l} S_{m r} C^{r}{ }_{j h i}+g_{k m} S_{l r} C^{r}{ }_{j h i}\right) .
\end{align*}
$$

According to Lemma 2.4, we may consider two cases (we will use the notations of the mentioned lemma):
(i) $S=\frac{1}{\rho} a \otimes a$. In this case we have

$$
\begin{equation*}
a_{l} C_{h i j k}+a_{h} C_{i l j k}+a_{i} C_{l h j k}=0, \tag{4}
\end{equation*}
$$

which implies $a_{r} C^{r}{ }_{i j k}=0$ and consequently $S_{i r} C^{r}{ }_{h j k}=0$. Thus the equation $C \cdot C=0$, which follows from Lemma 2.3, and our assumption turn (3) into $R \cdot C=-\frac{\kappa}{(n-1)(n-2)} Q(g, C)$. Applying now Lemma 2.5 we obtain $\kappa=0$ and $R \cdot R=0$.

Now we consider the case:
(ii) $S-\frac{1}{\rho} a \otimes a \neq 0$. In this case we have

$$
\begin{equation*}
\rho C_{h i j k}=\lambda\left(S_{h k} S_{i j}-S_{h j} S_{i k}\right) . \tag{5}
\end{equation*}
$$

Contracting (5) with $g^{i j}$ we get $S_{h k}^{2}=\kappa S_{h k}$. On the other hand transvecting (5) with $S_{p}{ }^{h}$ and using the last equality we obtain

$$
\begin{equation*}
S_{p}^{r} C_{r i j k}=\kappa C_{p i j k} . \tag{6}
\end{equation*}
$$

Transvecting now the Patterson's identity with $S^{h m}$, in virtue of (6), we immediately have $\kappa C_{l i j k}=0$. Thus we have $\kappa=0$, which turns (6) into $S_{p}{ }^{r} C_{r i j k}=0$. Transvecting the Patterson's identity with $S_{p}{ }^{h}$, in view of the last equality we get $S_{p m} C_{l i j k}+S_{p j} C_{l i k m}+S_{p k} C_{l i m j}=0$, which immediately implies (4). Semisymmetry of $M$ follows in the same manner as in the case (i). This completes the proof.

## 4. Manifolds satisfying the condition (1)

First we observe that if $L=0$ at $x$ then the relation (1) reduces to $R \cdot C=0$. This shows that $(M, g)$ is a so called Weyl-semisymmetric manifold. Such a manifold need not be semisymmetric, as is shown by the example below.

Example 4.1. Let $(M, g)$ be the 4-dimensional manifold defined in [4] (Lemme 1.1). As was shown in [4] (see Lemme 1.1 and Remarqué 1.5), $(M, g)$ is a non-conformally flat and non-semisymmetric, Weyl-semisymmetric manifold, i.e. the tensors $C$ and $R \cdot R$ are non-zero and the condition $R \cdot C=0$ holds on $M$.

Thus we restrict our considerations in this section to the open subset $\mathcal{U}_{L} \subset \mathcal{U}$ on which the associated function $L$ does not vanish.

Lemma 4.1. Let $(M, g)$ be a 4-dimensional semi-Riemannian manifold satisfying the condition (1). If $L \neq 0$ at $x$, then the following relations are fulfilled at $x$ :

$$
\begin{align*}
S_{m}^{r} C_{r i j k}+S_{j}^{r} C_{r i k m}+S_{k}^{r} C_{r i m j} & =0,  \tag{7}\\
C \cdot S & =0,  \tag{8}\\
S_{p}^{r} C_{r i k j} & =S_{k}^{r} C_{r j p i} . \tag{9}
\end{align*}
$$

Proof. Applying to the Patterson's identity the operation $R$. and using (1), in view of $L \neq 0$, we get

$$
\begin{align*}
& g_{h m} Q(S, C)_{l i j k p t}+g_{l m} Q(S, C)_{i h j k p t}+g_{i m} Q(S, C)_{h l j k p t} \\
& \quad+g_{h j} Q(S, C)_{l i k m p t}+g_{l j} Q(S, C)_{i h k m p t}+g_{i j} Q(S, C)_{h l k m p t}  \tag{10}\\
& \quad+g_{h k} Q(S, C)_{l i m j p t}+g_{l k} Q(S, C)_{i h m j p t}+g_{i k} Q(S, C)_{h l m j p t}=0 .
\end{align*}
$$

Using the definition of the tensor $Q(S, C)$, by a standard calculation, we obtain

$$
\begin{aligned}
& Q(S, C)_{l i j k p m}+Q(S, C)_{l i k m p j}+Q(S, C)_{l i m j p k} \\
& \quad=2\left(S_{p m} C_{l i k j}+S_{p j} C_{l i m k}+S_{p k} C_{l i j m}\right) \\
& \quad-\left(S_{m l} C_{p i j k}+S_{i m} C_{l p j k}+S_{j l} C_{p i k m}+S_{i j} C_{l p k m}+S_{k l} C_{p i m j}+S_{i k} C_{l p m j}\right)
\end{aligned}
$$

$$
g^{r s} Q(S, C)_{r l j k p s}=-\kappa C_{p l j k}+S_{p}^{r} C_{r l j k}-S_{l}^{r} C_{r p j k}-S_{j}^{r} C_{r l p k}-S_{k}^{r} C_{r l j p} .
$$

Contracting (10) with $g^{h t}$ and using the above relations, we have

$$
\begin{aligned}
& 2\left(S_{p m} C_{l i k j}+S_{p j} C_{l i m k}+S_{p k} C_{l i j m}\right)-\left(S_{l m}-\kappa g_{l m}\right) C_{p i j k} \\
& \quad-\left(S_{l j}-\kappa g_{l j}\right) C_{p i k m}-\left(S_{l k}-\kappa g_{l k}\right) C_{p i m j}-\left(S_{i m}-\kappa g_{i m}\right) C_{l p j k} \\
& \quad-\left(S_{i j}-\kappa g_{i j}\right) C_{l p k m}-\left(S_{i k}-\kappa g_{i k}\right) C_{l p m j} \\
& \quad+S_{i}^{r}\left(g_{l m} C_{r p j k}+g_{l j} C_{r p k m}+g_{l k} C_{r p m j}\right) \\
& \quad+S_{l}^{r}\left(g_{i m} C_{r p k j}+g_{i j} C_{r p m k}+g_{i k} C_{r p j m}\right) \\
& \quad+g_{i m}\left(S_{p}^{r} C_{r l j k}-S_{j}^{r} C_{r l p k}-S_{k}^{r} C_{r l j p}\right) \\
& \quad+g_{i j}\left(S_{p}^{r} C_{r l k m}-S_{k}^{r} C_{r l p m}-S_{m}^{r} C_{r l k p}\right) \\
& \quad+g_{i k}\left(S_{p}^{r} C_{r l m j}-S_{m}^{r} C_{r l p j}-S_{j}^{r} C_{r l m p}\right) \\
& \quad+g_{l m}\left(S_{j}^{r} C_{r i p k}+S_{k}^{r} C_{r i j p}-S_{p}^{r} C_{r i j k}\right) \\
& \quad+g_{l j}\left(S_{k}^{r} C_{r i p m}+S_{m}^{r} C_{r i k p}-S_{p}^{r} C_{r i k m}\right) \\
& \quad+g_{l k}\left(S_{m}^{r} C_{r i p j}+S_{j}^{r} C_{r i m p}-S_{p}^{r} C_{r i m j}\right)=0 .
\end{aligned}
$$

Hence, by contraction with $g^{l p}$, we obtain (7). In local coordinates the relation (1) takes the form

$$
\begin{aligned}
& C_{r i j k} R^{r}{ }_{h l m}+C_{h r j k} R_{i l m}^{r}+C_{h i r k} R_{j l m}^{r}+C_{h i j r} R_{k l m}^{r} \\
&= L\left(S_{h l} C_{m i j k}-S_{h m} C_{l i j k}+S_{i l} C_{h m j k}-S_{i m} C_{h l j k}+S_{j l} C_{h i m k}\right. \\
&\left.-S_{j m} C_{h i l k}+S_{k l} C_{h i j m}-S_{k m} C_{h i j l}\right) .
\end{aligned}
$$

Contracting this equality with $g^{h k}$, in virtue of (7) and the assumption $L \neq 0$, we get $S_{i}{ }^{r} C_{r j l m}+S_{j}{ }^{r} C_{\text {rilm }}=0$, i.e., (8). Applying (7) to (11) we find

$$
\begin{align*}
& 2\left(S_{m p} C_{l i k j}+S_{j p} C_{l i m k}+S_{k p} C_{l i j m}\right)-\left(S_{l m}-\kappa g_{l m}\right) C_{p i j k} \\
& \quad-\left(S_{l j}-\kappa g_{l j}\right) C_{p i k m}-\left(S_{l k}-\kappa g_{l k}\right) C_{p i m j}-\left(S_{i m}-\kappa g_{i m}\right) C_{l p j k} \\
& \quad-\left(S_{i j}-\kappa g_{i j}\right) C_{l p k m}-\left(S_{i k}-\kappa g_{i k}\right) C_{l p m j}  \tag{12}\\
& \quad+S_{i}^{r}\left(g_{l m} C_{r p j k}+g_{l j} C_{r p k m}+g_{l k} C_{r p m j}\right) \\
& \quad+S_{l}^{r}\left(g_{i m} C_{r p k j}+g_{i j} C_{r p m k}+g_{i k} C_{r p j m}\right)=0 .
\end{align*}
$$

Contracting (12) with $g^{l m}$, we obtain $2 S_{p}^{r} C_{r i k j}=S_{j}^{r} C_{r k i p}+S_{k}^{r} C_{r j p i}$ and next, in view of (8), we get (9). This completes the proof.

Proposition 4.1. Let $(M, g), \operatorname{dim} M=4$, be a semi-Riemannian manifold satisfying the condition (1). If $L \neq 0$ at $x$, then the following relations are fulfilled at $x$ :

$$
\begin{gather*}
S(W, \mathcal{C}(X, Y) Z)=\frac{\kappa}{4} C(X, Y, Z, W)  \tag{13}\\
T(U, X) C(W, V, Y, Z)+T(U, Y) C(W, V, Z, X)  \tag{14}\\
+T(U, Z) C(W, V, X, Y)-T(V, X) C(W, U, Y, Z) \\
-T(V, Y) C(W, U, Z, X)-T(V, Z) C(W, U, X, Y)=0,
\end{gather*}
$$

where $T=S-\frac{\kappa}{4} g$ and $X, Y, Z, W, U, V \in T_{x}(M)$,

$$
\begin{equation*}
S^{2}=\frac{\kappa}{2} S-\frac{\kappa^{2}}{16} g . \tag{15}
\end{equation*}
$$

Moreover, $(M, g)$ is Ricci-pseudosymmetric at $x$ and

$$
\begin{equation*}
R \cdot S=\frac{\kappa}{12} Q(g, S) . \tag{16}
\end{equation*}
$$

Proof. Transvecting the Patterson's identity with $S^{h m}$ and using the equality $S^{r s} C_{r i j s}=0$, which is an obvious consequence of (8), we get

$$
\kappa C_{l i j k}=S_{l}^{r} C_{r i j k}-S_{i}^{r} C_{r l j k}-S_{j}^{r} C_{r k i l}-S_{k}^{r} C_{r j l i} .
$$

This relation, in virtue of (9) takes the form $\kappa C_{l i j k}=2 S_{l}{ }^{r} C_{r i j k}-2 S_{i}{ }^{r} C_{r l j k}$ whence, in view of (8), we obtain (13). Using (13) we have

$$
\begin{aligned}
& S_{i}^{r}\left(g_{l m} C_{r p j k}+g_{l j} C_{r p k m}+g_{l k} C_{r p m j}\right)+S_{l}{ }^{r}\left(g_{i m} C_{r p k j}+g_{i j} C_{r p m k}+g_{i k} C_{r p j m}\right) \\
& =\frac{\kappa}{4}\left(g_{l m} C_{i p j k}+g_{l j} C_{i p k m}+g_{l k} C_{i p m j}+g_{i m} C_{l p k j}+g_{i j} C_{l p m k}+g_{i k} C_{l p j m}\right) .
\end{aligned}
$$

Substituting this equality into (12) we obtain

$$
\begin{align*}
& 2\left(S_{m p} C_{l i k j}+S_{j p} C_{l i m k}+S_{k p} C_{l i j m}\right)=\left(S_{l m}-\frac{3}{4} \kappa g_{l m}\right) C_{p i j k}  \tag{17}\\
& \quad+\left(S_{l j}-\frac{3}{4} \kappa g_{l j}\right) C_{p i k m}+\left(S_{l k}-\frac{3}{4} \kappa g_{l k}\right) C_{p i m j} \\
& \quad+\left(S_{i m}-\frac{3}{4} \kappa g_{i m}\right) C_{l p j k}+\left(S_{i j}-\frac{3}{4} \kappa g_{i j}\right) C_{l p k m} \\
& \quad+\left(S_{i k}-\frac{3}{4} \kappa g_{i k}\right) C_{l p m j} .
\end{align*}
$$

On the other hand, transvecting the Patterson's identity with $S_{p}{ }^{h}$ and using (13) we get

$$
\begin{aligned}
S_{p m} C_{l i j k} & +S_{p j} C_{l i k m}+S_{p k} C_{l i m j}+\frac{\kappa}{4}\left(g_{i m} C_{p l j k}+g_{i j} C_{p l k m}+g_{i k} C_{p l m j}\right. \\
& \left.-g_{l m} C_{p i j k}-g_{l j} C_{p i k m}-g_{l k} C_{p i m j}\right)=0
\end{aligned}
$$

Substituting this equality into (17) we have (14).
Transvecting now (14) with $T_{h}{ }^{m}$ and using (13) we obtain $T_{h l}^{2} C_{p i j k}=$ $T_{h i}^{2} C_{p l j k}$.

Applying now Lemma 2.1 for $A_{l p i s_{1} s_{2} s_{3}}=T_{s_{1} l}^{2} C_{p i s_{2} s_{3}}$, in virtue of $C \neq 0$, we get $T^{2}=0$. Thus we have (15). Finally, taking into account the equality (2), we have

$$
\begin{aligned}
S_{l}^{r} C_{r i j k}= & S_{l}^{r} R_{r i j k}-\frac{1}{2}\left(S_{l k} S_{i j}-S_{l j} S_{i k}\right) \\
& -\frac{1}{2}\left(g_{i j} S_{l k}^{2}-g_{i k} S_{l j}^{2}\right)+\frac{\kappa}{6}\left(S_{l k} g_{i j}-S_{l j} g_{i k}\right)
\end{aligned}
$$

This equality, in virtue of (15) takes the form

$$
\begin{aligned}
S_{l}^{r} C_{r i j k}= & S_{l}^{r} R_{r i j k}-\frac{1}{2}\left(S_{l k} S_{i j}-S_{l j} S_{i k}\right) \\
& -\frac{\kappa}{12}\left(g_{i j} S_{l k}-g_{i k} S_{l j}\right)+\frac{\kappa^{2}}{32}\left(g_{i j} g_{l k}-g_{i k} g_{l j}\right)
\end{aligned}
$$

Symmetrizing this relation in $i, l$ and using (8) we have

$$
S_{l}^{r} R_{r i j k}+S_{i}^{r} R_{r l j k}=\frac{\kappa}{12}\left(g_{l j} S_{i k}-g_{l k} S_{i j}+g_{i j} S_{l k}-g_{i k} S_{l j}\right),
$$

i.e., equality (16). This completes the proof.

Theorem 4.1. Let $(M, g), \operatorname{dim} M=4$, be a semi-Riemannian manifold satisfying the condition (1). If $L \neq 0$ and $S \neq \frac{\kappa}{4} g$ at $x$, then the following relations hold at $x$ :
(i) $\kappa \neq 0$,
(ii) $\mathfrak{S}_{X, Y, Z} a(X) \mathcal{C}(Y, Z)=0$ for a certain non-zero covector a at $x$,
(iii) $L=\frac{1}{3}$,
(iv) $Q(T, C)=0$.

Consequently, $(M, g)$ is pseudosymmetric at $x$ and $L_{R}=\frac{\kappa}{12}$.
Proof. Since $T \neq 0$ at $x$, we may choose a vector $V$ at $x$ (with local components $V^{r}$, such that the scalar $\rho=a(V)$ is non-zero, where $a$ is the covector defined by $a(X)=T(V, X)$. We also put $F_{i j}=V^{r} V^{s} C_{r i j s}$, $E_{i j k}=V^{r} C_{r i j k}$. Transvecting (14) with $V^{l} V^{m}$ we get

$$
\begin{equation*}
\rho C_{p i j k}+a_{j} E_{k i p}+a_{k} E_{j p i}+a_{i} E_{p j k}+T_{i j} F_{p k}-T_{i k} F_{p j}=0, \tag{18}
\end{equation*}
$$

which by transvection with $V^{p}$, leads to

$$
\begin{equation*}
E_{i j k}=\frac{1}{\rho}\left(a_{k} F_{i j}-a_{j} F_{i k}\right) . \tag{19}
\end{equation*}
$$

Symmetrizing (18) with respect to $p, i$ we obtain

$$
a_{i} E_{p j k}+a_{p} E_{i j k}+T_{i j} F_{p k}-T_{i k} F_{p j}+T_{p j} F_{i k}-T_{p k} F_{i j}=0,
$$

which, in view of (19), leads to $Q\left(F, T-\frac{1}{\rho} a \otimes a\right)=0$. Applying now Lemma 2.2, in view of $F \neq 0$, we have $T-\frac{1}{\rho} a \otimes a=\omega F, \omega \in \mathbb{R}$.

We consider two cases: (I) $\omega=0$ and (II) $\omega \neq 0$.
(I) $\omega=0$. Then we have $T_{i j}=\frac{1}{\rho} a_{i} a_{j}$ and substituting this into (18) and using (19) we have

$$
\begin{equation*}
\rho^{2} C_{p i j k}=a_{p} a_{k} F_{i j}-a_{p} a_{j} F_{i k}+a_{i} a_{j} F_{p k}-a_{i} a_{k} F_{p j} . \tag{20}
\end{equation*}
$$

This implies

$$
\begin{equation*}
a_{l} C_{p i j k}+a_{p} C_{i l j k}+a_{i} C_{l p j k}=0 \tag{21}
\end{equation*}
$$

and, in view of Lemma 2.3 also $C \cdot C=0$. Taking into account the relation (3) and using (13) and (1) we have ( $n=4$ )

$$
\begin{equation*}
(1-2 L) Q(S, C)=\frac{\kappa}{12} Q(g, C) \tag{22}
\end{equation*}
$$

This implies $\kappa=0$ if and only if $L=\frac{1}{2}$. We assert that $\kappa \neq 0$ at $x$. Suppose that $\kappa=0$ at $x$. Then $T=S=\frac{1}{\rho} a \otimes a$ and using (20) we easily obtain $Q(S, C)=0$, a contradiction. Now (22) implies $Q(S, C)=\frac{\kappa}{12(1-2 L)} Q(g, C)$ whence, in virtue of (1), we have $R \cdot C=\frac{\kappa L}{12(1-2 L)} Q(g, C)$. But $(M, g)$ is Ricci-pseudosymmetric with $L_{S}=\frac{\kappa}{12}$. So we get $\frac{\kappa L}{12(1-2 L)}=\frac{\kappa}{12}$ and we
have (iii). It is easy to see that for $L=\frac{1}{3}$ the equality (22) takes the form (iv).

Now we consider the second case:
(II) $\omega \neq 0$. Then

$$
\begin{align*}
F_{i j} & =\frac{1}{\omega}\left(T_{i j}-\frac{1}{\rho} a_{i} a_{j}\right), \\
E_{i j k} & =\frac{1}{\rho \omega}\left(a_{k} T_{i j}-a_{j} T_{i k}\right) . \tag{23}
\end{align*}
$$

Substituting these relations into (18) we get

$$
\begin{align*}
\rho^{2} \omega C_{l i j k}= & \rho\left(T_{i k} T_{l j}-T_{i j} T_{l k}\right)  \tag{24}\\
& +2\left(a_{l} a_{k} T_{i j}-a_{l} a_{j} T_{i k}+a_{i} a_{j} T_{l k}-a_{i} a_{k} T_{l j}\right) .
\end{align*}
$$

Contracting (23) with $g^{i j}$ we have $a_{r} a^{r}=0$. Using this equality and (15), after contraction of (24) with $g^{i j}$, we get $a_{i} a^{r} T_{r j}+a_{j} a^{r} T_{r i}=0$ which immediately implies $a^{r} T_{r j}=0$. Transvecting now (24) with $a^{l}$ and using the above equality we obtain $a^{r} C_{r i j k}=0$. This implies, by transvection of the Patterson's identity with $a^{h}, a_{m} C_{l i j k}+a_{j} C_{l i k m}+a_{k} C_{l i m j}=0$. Substituting (24) to this equality we have

$$
\begin{equation*}
a_{m}\left(T_{l k} T_{i j}-T_{l j} T_{i k}\right)+a_{j}\left(T_{l m} T_{i k}-T_{l k} T_{i m}\right)+a_{k}\left(T_{l j} T_{i m}-T_{l m} T_{i j}\right)=0 \tag{25}
\end{equation*}
$$

We assert that $\kappa \neq 0$ at $x$. Suppose that $\kappa=0$ at $x$. Then $T=S$ and

$$
\rho \omega C_{l i j k}=\left(S_{i k} S_{l j}-S_{i j} S_{l k}\right)+\frac{2}{\rho}\left(a_{l} a_{k} S_{i j}-a_{l} a_{j} S_{i k}+a_{i} a_{j} S_{l k}-a_{i} a_{k} S_{l j}\right) .
$$

Using this relation and (25), after standard but somewhat lenghty calculations we obtain $Q(S, C)=0$, a contradiction. The proof of (iii) and (iv) is the same as in the case (I). This completes the proof.

The existence of manifolds satisfying all relations of the above theorem can be established (see [10], Example 5.1) as follows

Example 4.2. Let $(N, \tilde{g}), \operatorname{dim} N=3$, be a semi-Riemannian manifold such that its Ricci tensor $\tilde{S}$ is of rank one and its scalar curvature $\tilde{\kappa}$ vanishes identically on $N$. An example of such manifold is presented in [10] (Example 5.1 (ii)). Furthermore, let $F$, defined by $F\left(x^{1}\right)=a \exp \left(b x^{1}\right)$,
$a=$ const. $\neq 0, b=$ const. $\neq 0$, be a function on a 1-dimensional manifold $\left(\bar{M}, g_{1}\right)$. It is shown in [10] that warped product $\bar{M} \times{ }_{F} N$ satisfies (1) with $L=\frac{1}{3}$ and is a pseudosymmetric manifold with $L_{R}=\frac{\kappa}{12}$, where $\kappa$ is the scalar curvature of $\bar{M} \times{ }_{F} N$. Moreover, it is easy to verify that $\kappa=-3 b^{2} \neq 0$ and one can see that the condition (ii) of the last theorem is satisfied at every point $x$ of $\bar{M} \times{ }_{F} N$ by arbitrary covector $a$ at $x$ such that the only non-zero component of $a$ is $a_{2}$.

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