

On extrinsic geometry of unit normal vector fields of Riemannian hyperfoliations

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Abstract. We consider a unit normal vector field of (local) hyperfoliation on a given Riemannian manifold as a submanifold in the unit tangent bundle with Sasaki metric. We give an explicit expression of the second fundamental form for this submanifold and a rather simple condition its totally geodesic property in the case of a totally umbilic hyperfoliation. A corresponding example shows the non-triviality of this condition. In the 2-dimensional case, we give a complete description of Riemannian manifolds admitting a geodesic unit vector field with totally geodesic property.

Introduction

Let (M, g) be an $(n + 1)$ -dimensional Riemannian manifold with metric g and ξ a fixed unit vector field on M . Consider ξ as a (local) mapping $\xi : M \rightarrow T_1M$. Then the image $\xi(M)$ is a submanifold in the unit tangent sphere bundle T_1M . The Sasaki metric on the tangent bundle TM induces the Riemannian metric on T_1M and on $\xi(M)$ as well. So, one may use notions from the geometry of submanifolds to determine geometrical characteristics of a unit vector field.

A unit vector field ξ is called *minimal* if $\xi(M)$ is a minimal submanifold with respect to the induced metric [5, 4] and *totally geodesic* if $\xi(M)$ is a totally geodesic submanifold in T_1M . A number of examples of locally

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minimal unit vector fields has been produced by J. C. GONZÁLEZ-DÁVILA and L. VANHECKE [6]. Most of their examples belong to a class of unit vector fields with a non-integrable orthogonal distribution ξ^\perp (the so-called *non-holonomic* vector fields). The *holonomic* case has been treated by E. BOECKX and L. VANHECKE [2], [3] and new examples of minimal and harmonic unit vector fields have been produced.

The *totally geodesic* property of the vector field is much more restrictive and allows to give a complete description of the field and the supporting manifold at least for 2-dimensional manifolds of constant curvature [8].

In this paper we treat the case of holonomic unit vector fields, namely, the field of unit normals of a given a Riemannian transversally oriented (local) hyperfoliation. The question is, *What is the connection between the extrinsic geometry of the leaves and the extrinsic (intrinsic) geometry of the submanifold $\xi(M) \in T_1M$?* In this paper we give, to some extent, the answer to this posed question.

1. The results

Let M^{n+1} be a Riemannian manifold admitting a transversally oriented Riemannian (local) hyperfoliation. This means that there exists a unit vector field ξ on M^{n+1} such that the distribution ξ^\perp is integrable, the leaves of the hyperfoliation (the integral submanifolds of ξ^\perp) are equidistant and the integral trajectories of the field ξ are geodesics of M^{n+1} . The principal technical result is contained in Lemma 3.2, which gives an expression for the second fundamental form of $\xi(M)$ in terms of the second fundamental forms of leaves and the curvature tensor of M . As an application of Lemma 3.2 to the case of totally umbilic hyperfoliation, we have the following

Theorem 1.1. *Let ξ be a unit normal vector field of Riemannian transversally orientable totally umbilical (local) hyperfoliation on a Riemannian manifold M . Then $\xi(M)$ is totally geodesic in T_1M if and only if*

$$K_\sigma = \frac{2k^2}{k^2 - 1},$$

where $k = k(s)$ is the value of umbilicity of a leaf and the K_σ are the eigenvalues of the normal Jacobi operator $R(\cdot, \xi)\xi$.

The non-flat spaces of constant curvature evidently drop out from our considerations since the K_σ are constant along each geodesic. A similar property is inherent to all locally symmetric spaces. So, the curvature of the manifold should help the vector field to be totally geodesic and the manifold has to be non-symmetric. Manifolds and vector fields with these desirable properties exist. We completely describe 2-dimensional Riemannian manifolds admitting *geodesic* unit vector fields with *totally geodesic* property.

Theorem 1.2. *Let ξ be a (local) unit geodesic vector field on a 2-dimensional Riemannian manifold M . Then ξ is a totally geodesic vector field if and only if the local expression for the metric of M with respect to a (ξ, ξ^\perp) -orthogonal coordinate system takes the form*

$$ds^2 = \frac{(t^2 - 1)^2}{t^4(t^2 + 1)^2} dt^2 + \frac{a^2 t^2}{(t^2 + 1)^2} dv^2,$$

where t is the geodesic curvature of ξ^\perp -curves, ξ is the normalized vector field ∂_t and a is a parameter.

Moreover, we produce an *explicit example of a surface of revolution* carrying that kind of metric. Let us remark, that the curvature of this surface is non-constant, positive for $t^2 > 1$ and negative for $0 < t^2 < 1$. We also give the multidimensional generalization of this example.

2. Preliminaries

Let (M, g) be an $(n + 1)$ -dimensional Riemannian manifold with metric g . Denote by $\langle \cdot, \cdot \rangle$ a scalar product with respect to g and by ∇ the Levi-Civita connection on M . The *Sasaki metric* on TM is defined by the following scalar product: if $\tilde{X}, \tilde{Y} \in TTM$, then

$$\langle \langle \tilde{X}, \tilde{Y} \rangle \rangle = \langle \pi_* \tilde{X}, \pi_* \tilde{Y} \rangle + \langle K\tilde{X}, K\tilde{Y} \rangle \tag{1}$$

where $\pi_* : TTM \rightarrow TM$ is the differential of the projection $\pi : TM \rightarrow M$ and $K : TTM \rightarrow TM$ is the *connection map*.

Let ξ be a unit vector field on M . A vector field $\tilde{X} \in TTM$ is tangent to $\xi(M)$ if and only if [7]

$$\tilde{X} = (\pi_*\tilde{X})^h + (\nabla_{\pi_*\tilde{X}}\xi)^v,$$

where $(\cdot)^h$ and $(\cdot)^v$ mean *horizontal* and *vertical* lifts of fields into the tangent bundle.

Introduce a *shape operator* A_ξ for the field ξ by

$$A_\xi X = -\nabla_X \xi,$$

where X is an arbitrary vector field on M . Define a *conjugate shape operator* A_ξ^* by

$$\langle A_\xi^* X, Y \rangle = \langle X, A_\xi Y \rangle. \quad (2)$$

Applying standard singular decomposition of the operator (matrix) A_ξ , one can find orthonormal local frames e_0, e_1, \dots, e_n and $f_0 = \xi, f_1, \dots, f_n$ on M such that

$$A_\xi e_0 = 0, \quad A_\xi e_\alpha = \lambda_\alpha f_\alpha, \quad A_\xi^* f_0 = 0, \quad A_\xi^* f_\alpha = \lambda_\alpha e_\alpha, \quad \alpha = 1, \dots, n,$$

where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq 0$ are real-valued functions.

The frames e_0, e_1, \dots, e_n and $f_0 = \xi, f_1, \dots, f_n$ are called *left* and *right* singular frames respectively for the operator A_ξ .

Remark that one may use if necessary the signed singular values fixing the directions of the vectors of the singular frame. Setting $\lambda_0 = 0$, we may rewrite the relations on singular frames in a unified form

$$A_\xi e_i = \lambda_i f_i, \quad A_\xi^* f_i = \lambda_i e_i, \quad i = 0, 1, \dots, n, \quad (3)$$

$$\lambda_0 = 0, \quad \lambda_1, \dots, \lambda_n \geq 0.$$

The following lemma is easy to prove using (2) and (3).

Lemma 2.1 ([7]). *At each point of $\xi(M) \subset TM$ the orthonormal frames*

$$\begin{aligned} \tilde{e}_i &= \frac{1}{\sqrt{1 + \lambda_i^2}} (e_i^h - \lambda_i f_i^v), & i &= 0, 1, \dots, n, \\ \tilde{n}_{\sigma|} &= \frac{1}{\sqrt{1 + \lambda_\sigma^2}} (\lambda_\sigma e_\sigma^h + f_\sigma^v), & \sigma &= 1, \dots, n \end{aligned} \quad (4)$$

form orthonormal frames in the tangent space of $\xi(M)$ and in the normal space of $\xi(M)$, respectively.

Introduce a half tensor of Riemannian curvature as

$$r(X, Y)\xi = \nabla_X \nabla_Y \xi - \nabla_{\nabla_X Y} \xi. \tag{5}$$

Now we are able to formulate a lemma, basic for our considerations.

Lemma 2.2 ([7]). *The components of the second fundamental form of $\xi(M) \subset T_1M$ with respect to the frame (4) are given by*

$$\begin{aligned} \tilde{\Omega}_{\sigma|ij} = & \frac{1}{2} \Lambda_{\sigma ij} \{ \langle r(e_i, e_j)\xi + r(e_j, e_i)\xi, f_\sigma \rangle \\ & + \lambda_\sigma [\lambda_j \langle R(e_\sigma, e_i)\xi, f_j \rangle + \lambda_i \langle R(e_\sigma, e_j)\xi, f_i \rangle] \}, \end{aligned}$$

where $\Lambda_{\sigma ij} = [(1 + \lambda_\sigma^2)(1 + \lambda_i^2)(1 + \lambda_j^2)]^{-1/2}$ ($i, j = 0, 1, \dots, n; \sigma = 1, \dots, n$).

3. The case of Riemannian hyperfoliation

Let M^{n+1} be a Riemannian manifold admitting a transversally oriented Riemannian hyperfoliation. In this case $A_\xi X = -\nabla_X \xi$ is a self-adjoint linear operator on ξ^\perp and for all $X \in \xi^\perp$ it is a shape operator of the corresponding leaf. Remark that $A_\xi \xi = 0$.

Denote by ∇^F the induced connection on each leaf. Denote by $B_\xi(X, Y)$ the second fundamental forms of the leaf, i.e.

$$B_\xi(X, Y) = \langle A_\xi X, Y \rangle_F$$

where $\langle \cdot, \cdot \rangle_F$ means scalar product with respect to the induced metric on each leaf and X, Y are tangent to the corresponding leaf.

Let e_α ($\alpha = 1, \dots, n$) be an orthonormal frame consisting of eigenvectors of the shape operator, i.e.

$$A_\xi e_\alpha = k_\alpha e_\alpha,$$

where k_α are the principal curvatures of the corresponding leaf. Since A_ξ is self-adjoint, in our notations we have

$$f_0 = e_0 = \xi, \quad f_\alpha = \text{sign}(k_\alpha) e_\alpha, \quad \lambda_\alpha = |k_\alpha| \quad (\alpha = 1, \dots, n),$$

where f_α are the vectors of the left singular frame and λ_α are the corresponding singular values. We may simplify notations, if we set

$$f_0 = e_0 = \xi, \quad f_\alpha = e_\alpha, \quad \lambda_\alpha = k_\alpha \quad (\alpha = 1, \dots, n), \quad (6)$$

letting λ_α to be not necessarily positive. So, the framing of $\xi(M)$ for the case under consideration obtains the form

$$\begin{aligned} \tilde{e}_0 &= \xi^h, & \tilde{e}_\alpha &= \frac{1}{\sqrt{1+k_\alpha^2}}(e_\alpha^h - k_\alpha e_\alpha^v), \\ \tilde{n}_{|\alpha|} &= \frac{1}{\sqrt{1+k_\alpha^2}}(k_\alpha e_\alpha^h + e_\alpha^v). \end{aligned} \quad (7)$$

Now, the following simplification can be done.

Lemma 3.1. *Let ξ be a unit vector field of Riemannian transversally orientable hyperfoliation on a given Riemannian manifold M^{n+1} . Denote by X, Y, Z the vector fields tangent to the leaf. Then*

$$\begin{aligned} \langle r(X, Y)\xi, Z \rangle &= \langle r(X, Z)\xi, Y \rangle = -(\nabla_X^F B_\xi)(Y, Z), \\ \langle r(X, \xi)\xi, Z \rangle &= -\langle A_\xi X, A_\xi Z \rangle_F \\ \langle r(\xi, X)\xi, Z \rangle &= -\langle A_\xi X, A_\xi Z \rangle_F - \langle R(X, \xi)\xi, Z \rangle. \end{aligned}$$

PROOF. Indeed, standard computation yields

$$\langle (\nabla_X^F A_\xi)Y, Z \rangle_F = (\nabla_X^F B_\xi)(Y, Z).$$

Consider now $\langle r(X, Y)\xi, Z \rangle$. Keeping in mind that ξ is a *geodesic* vector field, we have

$$\begin{aligned} \langle r(X, Y)\xi, Z \rangle &= \langle \nabla_X \nabla_Y \xi - \nabla_{\nabla_X Y} \xi, Z \rangle \\ &= \langle -\nabla_X (A_\xi Y) - \nabla_{\nabla_X^F Y + B_\xi(X, Y)} \xi, Z \rangle \\ &= \langle -\nabla_X^F (A_\xi Y) - B_\xi(A_\xi Y, X) - \nabla_{\nabla_X^F Y} \xi, Z \rangle \\ &= -\langle (\nabla_X^F A_\xi)Y, Z \rangle - \langle A_\xi \nabla_X^F Y, Z \rangle + \langle A_\xi \nabla_X^F Y, Z \rangle \\ &= -\langle (\nabla_X^F A_\xi)Y, Z \rangle. \end{aligned}$$

Thus

$$\langle r(X, Y)\xi, Z \rangle = -(\nabla_X^F B_\xi)(Y, Z) = -(\nabla_X^F B_\xi)(Z, Y) = \langle r(X, Z)\xi, Y \rangle.$$

Consider $\langle r(X, \xi)\xi, Z \rangle$. We have

$$\begin{aligned} \langle r(X, \xi)\xi, Z \rangle &= \langle \nabla_X \nabla_\xi \xi - \nabla_{\nabla_X \xi} \xi, Z \rangle = -\langle \nabla_{-A_\xi X} \xi, Z \rangle \\ &= -\langle A_\xi^2 X, Z \rangle_F = -\langle A_\xi X, A_\xi Z \rangle_F. \end{aligned}$$

Finally,

$$\langle r(\xi, X)\xi, Z \rangle = \langle r(X, \xi)\xi, Z \rangle - \langle R(X, \xi)\xi, Z \rangle,$$

which completes the proof. \square

The following Lemma gives useful information on the relation between extrinsic geometry of the leaves of hyperfoliation and extrinsic geometry of the submanifold $\xi(M)$ and is a principal tool for further study.

Lemma 3.2. *Let ξ be a unit normal vector field of Riemannian transversally orientable (local) hyperfoliation on a given Riemannian manifold M^{n+1} . The components of the second fundamental form of the submanifold $\xi(M) \in T_1M$ with respect to some orthonormal frame are given by*

$$\begin{aligned} \tilde{\Omega}_{\sigma|00} &= 0 \\ \tilde{\Omega}_{\sigma|\alpha 0} &= \frac{1}{2} \Lambda_{\sigma\alpha 0} \{ [(k_\sigma^2 - 1)K_\sigma - 2k_\sigma^2] \delta_{\sigma\alpha} - (1 - k_\alpha k_\sigma)(1 - \delta_{\sigma\alpha}) \langle R(e_\alpha, \xi)\xi, e_\sigma \rangle \} \\ \tilde{\Omega}_{\sigma|\alpha\beta} &= \frac{1}{2} \Lambda_{\sigma\alpha\beta} \{ -2(\nabla_{e_\sigma}^F B_\xi)(e_\alpha, e_\beta) \\ &\quad + (1 - k_\sigma k_\alpha) \langle R(\xi, e_\alpha)e_\beta, e_\sigma \rangle + (1 - k_\sigma k_\beta) \langle R(\xi, e_\beta)e_\alpha, e_\sigma \rangle \}, \end{aligned}$$

where K_σ are the eigenvalues of the normal Jacobi operator $R(\cdot, \xi)\xi$ and $\delta_{\sigma\alpha}$ is the Kronecker symbol.

Note that Lemma 3.2 can be applied to the case of a local foliation such as a family of distance spheres, tubes etc. As an immediate corollary we see that if the leaves are totally geodesic or even totally umbilic then $\xi(M)$ is a *minimal* submanifold but it is not totally geodesic in general.

PROOF. (a) Since ξ is a geodesic vector field, we may set $e_0 = \xi$ and therefore we have $\langle r(e_0, e_0)\xi, e_\sigma \rangle = 0$. Applying Lemma 2.2, we get $\tilde{\Omega}_{\sigma|00} = 0$.

(b) From Lemma 2.2

$$\tilde{\Omega}_{\sigma|\alpha 0} = \frac{1}{2}\Lambda_{\sigma\alpha 0}\{\langle r(e_\alpha, e_0)\xi, f_\sigma \rangle + \langle r(e_0, e_\alpha)\xi, f_\sigma \rangle + \lambda_\sigma\lambda_\alpha\langle R(e_\sigma, e_0)\xi, f_\alpha \rangle\}.$$

Taking into account (6) and applying Lemma 3.1, we get

$$\langle r(e_\alpha, e_0)\xi, f_\sigma \rangle = \langle r(e_\alpha, \xi)\xi, e_\sigma \rangle = -k_\alpha k_\sigma \langle e_\alpha, e_\sigma \rangle = -k_\sigma^2 \delta_{\sigma\alpha}$$

$$\langle r(e_0, e_\alpha)\xi, f_\sigma \rangle = \langle r(\xi, e_\alpha)\xi, e_\sigma \rangle = -k_\sigma^2 \delta_{\sigma\alpha} - \langle R(e_\sigma, \xi)\xi, e_\alpha \rangle.$$

On the other hand, setting $K_\alpha = \langle R(e_\alpha, \xi)\xi, e_\alpha \rangle$, we have

$$\langle R(e_\sigma, \xi)\xi, e_\alpha \rangle = K_\sigma \delta_{\sigma\alpha} + (1 - \delta_{\sigma\alpha})\langle R(e_\sigma, \xi)\xi, e_\alpha \rangle.$$

After substitutions, we get

$$\tilde{\Omega}_{\sigma|\alpha 0} = \frac{1}{2}\Lambda_{\sigma\alpha 0}\{[(k_\sigma^2 - 1)K_\sigma - 2k_\sigma^2]\delta_{\sigma\alpha} - (1 - k_\alpha k_\sigma)(1 - \delta_{\sigma\alpha})\langle R(e_\alpha, \xi)\xi, e_\sigma \rangle\}.$$

(c) From Lemma 2.2 and (6)

$$\begin{aligned} \tilde{\Omega}_{\sigma|\alpha\beta} &= \frac{1}{2}\Lambda_{\sigma\alpha\beta}\{\langle r(e_\alpha, e_\beta)\xi, e_\sigma \rangle + \langle r(e_\beta, e_\alpha)\xi, e_\sigma \rangle \\ &\quad + k_\sigma [k_\alpha \langle R(e_\sigma, e_\beta)\xi, e_\alpha \rangle + k_\beta \langle R(e_\sigma, e_\alpha)\xi, e_\beta \rangle]\}, \end{aligned}$$

Lemma 3.1 and the Codazzi equation yield

$$r(e_\alpha, e_\beta)\xi, e_\sigma \rangle = -(\nabla_{e_\alpha}^F B_\xi)(e_\beta, e_\sigma),$$

$$r(e_\beta, e_\alpha)\xi, e_\sigma \rangle = -(\nabla_{e_\beta}^F B_\xi)(e_\alpha, e_\sigma),$$

$$\langle R(e_\sigma, e_\beta)\xi, e_\alpha \rangle = -(\nabla_{e_\sigma}^F B_\xi)(e_\beta, e_\alpha) - \langle r(e_\beta, e_\alpha)\xi, e_\sigma \rangle,$$

$$\langle R(e_\sigma, e_\alpha)\xi, e_\beta \rangle = -(\nabla_{e_\sigma}^F B_\xi)(e_\alpha, e_\beta) - \langle r(e_\alpha, e_\beta)\xi, e_\sigma \rangle.$$

So we have

$$\begin{aligned} &\langle r(e_\alpha, e_\beta)\xi, e_\sigma \rangle + \langle r(e_\beta, e_\alpha)\xi, e_\sigma \rangle \\ &= -2(\nabla_{e_\sigma}^F B_\xi)(e_\alpha, e_\beta) - \langle R(e_\sigma, e_\alpha)\xi, e_\beta \rangle - \langle R(e_\sigma, e_\beta)\xi, e_\alpha \rangle. \end{aligned}$$

After substitutions, we get

$$\begin{aligned} \tilde{\Omega}_{\sigma|\alpha\beta} &= \frac{1}{2}\Lambda_{\sigma\alpha\beta}\{-2(\nabla_{e_\sigma}^F B_\xi)(e_\alpha, e_\beta) + (1 - k_\sigma k_\alpha)\langle R(\xi, e_\alpha)e_\beta, e_\sigma \rangle \\ &\quad + (1 - k_\sigma k_\beta)\langle R(\xi, e_\beta)e_\alpha, e_\sigma \rangle\}, \end{aligned}$$

which completes the proof. \square

Now we can characterize the totally umbilic foliations as follows.

Theorem 3.1. *Let ξ be a unit normal vector field of Riemannian transversally orientable totally umbilical (local) hyperfoliation on a Riemannian manifold M . Then $\xi(M)$ is totally geodesic in T_1M if and only if*

$$K_\sigma = \frac{2k^2}{k^2 - 1}, \tag{8}$$

where $k = k(s)$ is the value of umbilicity of a leaf and K_σ are the eigenvalues of the normal Jacobi operator $R(\cdot, \xi)\xi$.

PROOF. The result of Lemma 3.2 means that the extrinsic geometry of holonomic, i.e. with integrable distribution ξ^\perp , geodesic vector fields depends on the extrinsic geometry of leaves and the normal Jacobi operator $R_\xi = R(\cdot, \xi)\xi$. A submanifold $F \subset M$ is said to be *curvature adapted* [1] if for every normal vector ξ to F at a point $p \in F$ the following conditions hold:

$$\begin{aligned} R_\xi(T_pF) &\subset T_pF \\ A_\xi \circ R_\xi &= R_\xi \circ A_\xi, \end{aligned}$$

where A_ξ is the shape operator of F . The first condition is always fulfilled for a hypersurface. The second means that there exists a basis of T_pF consisting of eigenvectors of both R_ξ and A_ξ . Every totally umbilical submanifold is curvature adapted and has parallel second fundamental form. These facts immediately imply

Proposition 3.1. *Let ξ be a unit normal vector field of Riemannian transversally orientable totally umbilical hyperfoliation on a given Riemannian manifold M^{n+1} . The non-zero components of the second fundamental form for $\xi(M) \in T_1M$ are given by*

$$\tilde{\Omega}_{\sigma|\sigma 0} = \frac{1}{2} \frac{1}{1+k^2} [(k^2 - 1)K_\sigma - 2k^2],$$

where $k = k(s)$ is the value of umbilicity of a leaf F_s^n and K_σ are the eigenvalues of the normal Jacobi operator $R(\cdot, \xi)\xi$.

Now the main result follows immediately from Proposition 3.1. □

Remark that $K_\sigma = K_{\xi \wedge e_\sigma}$, where $K_{\xi \wedge e_\sigma}$ means a sectional curvature along the plane $\xi \wedge e_\sigma$ and e_σ are the eigenvectors of the normal Jacobi operator. A similar condition is necessary for the totally geodesic property in the case of curvature adapted foliation (even a local one), namely

$$K_\sigma = \frac{2k_\sigma^2}{k_\sigma^2 - 1}.$$

This condition fails if M^{n+1} is locally symmetric and the leaves are homogeneous. In this case K_σ are constant along ξ -geodesics while k_σ are the functions of its natural parameter. Typical examples are provided by the field of unit normals of a family of geodesic spheres or by the tubes around a totally geodesic submanifold. These vector fields are minimal [2] but never totally geodesic.

As a direct application of Lemma 3.2 to the case of a 2-dimensional Riemannian manifold, we are able to describe completely the totally geodesic unit vector fields belonging to the class under consideration and the supporting manifold in the following terms.

Theorem 3.2. *Let ξ be a (local) unit geodesic vector field on a 2-dimensional Riemannian manifold M . Then ξ is a totally geodesic vector field if and only if the local expression for the metric of M with respect to a (ξ, ξ^\perp) -orthogonal coordinate system takes the form*

$$ds^2 = \frac{(t^2 - 1)^2}{t^4(t^2 + 1)^2} dt^2 + \frac{a^2 t^2}{(t^2 + 1)^2} dv^2, \tag{9}$$

where t is the geodesic curvature of ξ^\perp -curves, ξ is the normalized vector field ∂_t and a is a parameter.

PROOF. Let ξ be a (local) geodesic unit vector field on a 2-dimensional Riemannian manifold M of Gaussian curvature K . The result of Lemma 3.2 allows to simplify the matrix of the second fundamental form of $\xi(M) \in T_1M$ to

$$\Omega = \begin{pmatrix} 0 & \frac{1}{2} \frac{(k^2 - 1)K - 2k^2}{1 + k^2} \\ \frac{1}{2} \frac{(k^2 - 1)K - 2k^2}{1 + k^2} & -\frac{e_1(k)}{(1 + k^2)^{3/2}} \end{pmatrix},$$

where k is the geodesic curvature of the integral trajectories of the unit vector field $e_1 = \xi^\perp$.

Taking ξ -integral trajectories as the first family of coordinate lines and $e_1 = \xi^\perp$ -integral trajectories as the second one, we can express the metric of M^2 in the form

$$ds^2 = du^2 + g^2(u, v) dv^2,$$

where $g(u, v)$ is some (positive) function. Remark that the geodesic curvature of e_1 -curves with respect to our coordinate system takes the form

$$k = -\frac{g_u}{g}. \tag{10}$$

Suppose now that $\xi(M)$ is totally geodesic in T_1M . Then $e_1(k) = 0$ and hence k does not depend on the v -parameter. Solving (10) with respect to g , we get

$$g(u, v) = C(v) \exp\left(-\int k(u) du\right).$$

After v -parameter change, we reduce the metric to the form of metric of a surface of revolution

$$ds^2 = du^2 + f^2(u) dv^2.$$

So the curves $u = \text{const}$ (the parallels) give us a totally umbilical foliation on M^2 . The *value of umbilicity* is the geodesic curvature of parallels, the vector field $\xi = \partial_u$ is a unit vector field tangent to meridians, the Gaussian curvature K of M^2 for this depends only on u – the natural parameter on meridians – and $K = k'(u) - k^2(u)$. To satisfy the totally geodesic property, the geodesic curvature k has to be a solution of the differential equation

$$k' = \frac{k^2(k^2 + 1)}{k^2 - 1}.$$

The implicit solution is $u = 2 \arctan k + \frac{1}{k} + u_0$. The inverse function $k = k(u)$ exists on intervals where $k(u) \neq 1$.

To produce an explicit solution, we proceed as follows. Choose k as a parameter, say t . Since $k = -f^{-1}f'_u$, we can write two relations

$$\frac{f'_u}{f} = -t, \quad \frac{dt}{du} = \frac{t^2(t^2 + 1)}{t^2 - 1}. \tag{11}$$

Making a parameter change, we obtain a differential equation on $f(t)$ of the form $\frac{f'_t}{f} = \frac{1-t^2}{t(1+t^2)}$ with a general solution $f(t) = \frac{at}{t^2+1}$, where a is the constant of integration. From (11) we can also find $du = \frac{t^2-1}{t^2(t^2+1)} dt$ and therefore the metric under consideration takes the form (9) with respect to the parameters (t, v) . \square

Indeed, we are able to get an isometric immersion of the metric constructed into Euclidean 3-space as a *surface* of revolution. Some additional considerations show that we get the most regular surface for $a = 1$.

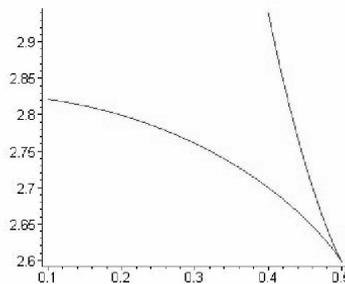
Example. Let $\{x(t), z(t)\}$ be a profile curve, generating a surface with the metric (9) with $a = 1$. Then, evidently, $x(t) = \frac{t}{(t^2+1)}$ and $(x'_t)^2 + (z'_t)^2 = \frac{(t^2-1)^2}{t^4(t^2+1)^2}$. From this we find

$$z'_t = \pm \frac{(t^2-1)\sqrt{2t^2+1}}{t^2(t^2+1)^2}.$$

Choose one branch, say with a positive sign. A relatively simple calculation gives $z(t) = \frac{(2t^2+1)^{3/2}}{t(t^2+1)}$ (up to an additive constant). Thus, finally, we have a parametric curve

$$x(t) = \frac{t}{(t^2+1)}, \quad z(t) = \frac{(2t^2+1)^{3/2}}{t(t^2+1)}$$

parametrized with the geodesic curvature of the meridians of the associated surface of revolution and having one singular point corresponding to $t = 1$. The following picture gives a graph.



Remark that $K < 0$ for $t^2 \in (0, 1)$ and $K > 0$ for $t^2 \in (1, +\infty)$. The point $(0, 0, 2\sqrt{2})$ is an umbilical one at infinity (for given parameterization).

The example is not essentially 2-dimensional. Consider a metric of revolution of the form

$$ds^2 = du^2 + f^2(u) \sum_{\alpha=1}^n (dv^\alpha)^2.$$

Then the leaves of hyperfoliation $u = \text{const}$ are all totally umbilic with a value of umbilicity $k = -f^{-1}f'_u$. To make the vector field $\xi = \partial_u$ totally geodesic, this value should satisfy the same differential equation, namely

$$k' = \frac{k^2(k^2 + 1)}{k^2 - 1},$$

which has the same solution as in 2-dimensional example.

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