

## The regular prism tilings and their optimal hyperball packings in the hyperbolic $n$ -space

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**Abstract.** In this paper we investigate the  $n$ -dimensional ( $n \geq 3$ ) hyperbolic prism honeycombs, which are generated by the “inscribed hyperspheres”.

The 3-dimensional prism tilings (mosaics) were classified by I. VERMES in [V72] and [V73]. He found infinitely many prism tilings, whose optimal hyperball packings and metric data are determined by the author in [Sz04].

In the hyperbolic 4-space  $\mathbb{H}^4$  there are only 2 analogous honeycombs whose metric data and the densities of their optimal hyperball packings are determined in this paper. In  $\mathbb{H}^5$  there are 3 types of these mosaics, whose analogous problems will be discussed elsewhere. In the hyperbolic  $n$ -space  $\mathbb{H}^n$  ( $n > 5$ ) there are no such regular prism tilings. Our method and computations are based on the projective interpretation of the hyperbolic geometry.

### 1. Introduction

A honeycomb (or solid tessellation, or tiling) is an infinite set of congruent polyhedra fitting together face-to-face to fill all space just once. At present the space is the  $n$ -dimensional hyperbolic space  $\mathbb{H}^n$  ( $n \geq 3$ ) and the polyhedron is a prism.

In hyperbolic space  $\mathbb{H}^n$  ( $n \geq 3$ ) a regular prism is the convex hull of two congruent  $(n - 1)$  dimensional regular polyhedra in ultraparallel hyperplanes, (i.e.  $n - 1$ -planes), related by translation along the line joining

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their centres that is the common perpendicular of the two hyperplanes. Each vertex of such tiling is either proper point or every vertex lies on the absolute quadric of  $\mathbb{H}^n$ , in this case the prism tiling is called totally asymptotic. Thus the prism is a polyhedron having at each vertex one  $(n - 1)$ -dimensional regular polyhedron and some  $(n - 1)$ -dimensional prisms, meeting at this vertex.

In  $\mathbb{H}^3$  (see [Sz04]) the corresponding prisms are called  $p$ -gonal prisms ( $p \geq 3$ ) in which the regular polyhedra (the cover-faces) are regular  $p$ -gons, and the side-faces are rectangles. Figure 1 shows a part of such a prism where  $A_2$  is the centre of a regular  $p$ -gonal face,  $A_1$  is a midpoint of a side of this face, and  $A_0$  is one vertex (end) of that side. Let  $B_0, B_1, B_2$  be the corresponding points of the other  $p$ -gonal face of the prism. These 3-dimensional prism tilings were classified by I. VERMES in [V72] and [V73].

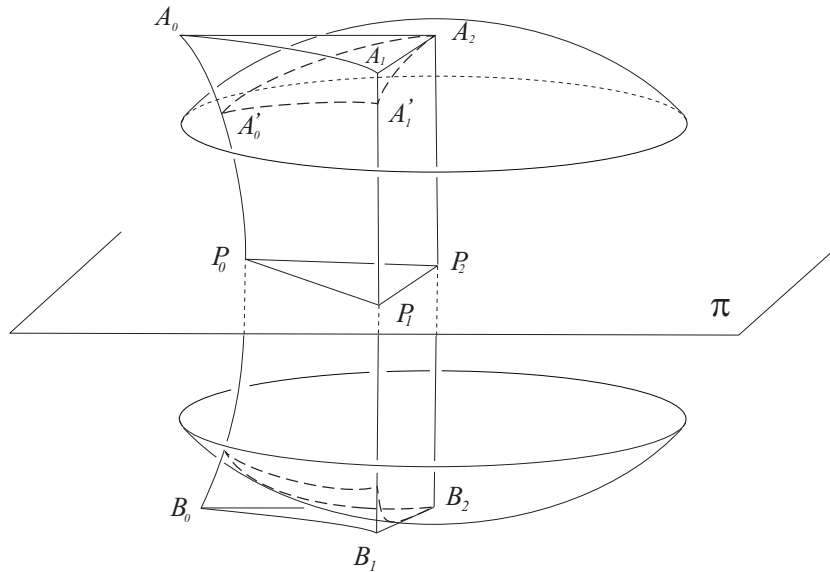


Figure 1

In our case in  $\mathbb{H}^n$  ( $n \geq 4$ ) the hyperspheres form locally optimal hyperball packings whose data can be determined by our method.

The equidistant surface (or hypersphere) is a quadratic surface at a constant distance from a plane in both halfspaces. The infinite body enclosed by the hypersphere is called hyperball.

In [Sz04] the author has investigated these  $p$ -gonal prism tilings and their optimal hyperball packings and determined the densities of each packing.

In this paper we shall investigate the  $n$ -dimensional ( $n \geq 4$ ) hyperbolic prism honeycombs and their optimal hyperball packings. Our main results are summarized in the following Theorems 1.1–4:

**Theorem 1.1.** *The non-uniform compact prism tilings  $\mathcal{P}_{pqrs}$  in  $\mathbb{H}^4$  with parameters  $\{p, | q, r | s\}$  are the following:*

- (1)  $\{3 | 5, 3 | 3\}$  : *the vertex figure of the tiling is “120-cells”:  $\{q, r, s\} = \{5, 3, 3\}$  and the cover faces are cosahedra  $\{p, q, r\} = \{3, 5, 3\}$ .*
- (2)  $\{5 | 3, 4 | 3\}$  : *the vertex figure of the tiling is “24-cells”:  $\{q, r, s\} = \{3, 4, 3\}$  and the cover faces are dodecahedra  $\{p, q, r\} = \{5, 3, 4\}$ .*

*The metric data and the densities of the optimal hyperball packings of these tilings are summarized in Table 1.*

*Remark 1.1.* The uniform compact tiling in  $\mathbb{H}^4$  with parameters  $\{p, q, r, s\}$  is the regular cube honeycomb  $\{4, 3, 3, 5\}$  (according to the notation of H. S. M. COXETER [C56]). Here the prism is a cube but the associated honeycomb tiling is not associated with any hyperball packing. So we do not consider it in this work.

*Remark 1.2.* The optimal ball packing belonging to the 3-dimensional regular Coxeter honeycombs have been investigated in [Sz03-2].

**Theorem 1.2.** *There is no totally asymptotic prism tiling  $\mathcal{P}_{pqrs}$  in  $\mathbb{H}^4$ .*

**Theorem 1.3.** *In the 5-dimensional hyperbolic space  $\mathbb{H}^5$  there are 3 regular prism tilings.*

**Theorem 1.4.** *There is no prism tiling in the hyperbolic space  $\mathbb{H}^n$ , ( $n \geq 6$ ).*

## 2. The projective model and the complete orthoschemes

Let  $X$  denote either the  $n$ -dimensional sphere  $\mathbb{S}^n$ , the  $n$  dimensional Euclidean space  $\mathbb{E}^n$  or the hyperbolic space  $\mathbb{H}^n$ ,  $n \geq 2$ . We use for  $\mathbb{H}^n$  the projective model in the Lorentz space  $\mathbb{E}^{1,n}$  of signature  $(1, n)$ , i.e.  $\mathbb{E}^{1,n}$  denotes the real vector space  $\mathbf{V}^{n+1}$  equipped with the bilinear form of signature  $(1, n)$

$$\langle \mathbf{x}, \mathbf{y} \rangle = -x^0 y^0 + x^1 y^1 + \cdots + x^n y^n \quad (2.1)$$

where the non-zero vectors

$$\mathbf{x} = (x^0, x^1, \dots, x^n) \in \mathbf{V}^{n+1} \quad \text{and} \quad \mathbf{y} = (y^0, y^1, \dots, y^n) \in \mathbf{V}^{n+1},$$

are determined up to real factors, for representing points of  $\mathcal{P}^n(\mathbb{R})$ . Then  $\mathbb{H}^n$  can be interpreted as the interior of the quadric

$$Q = \{[\mathbf{x}] \in \mathcal{P}^n \mid \langle \mathbf{x}, \mathbf{x} \rangle = 0\} =: \partial\mathbb{H}^n \quad (2.2)$$

in the real projective space  $\mathcal{P}^n(\mathbf{V}^{n+1}, \mathbf{V}_{n+1})$ .

The points of the boundary  $\partial\mathbb{H}^n$  in  $\mathcal{P}^n$  are called points at infinity of  $\mathbb{H}^n$ , the points lying outside  $\partial\mathbb{H}^n$  are said to be (ideal) outer points of  $\mathbb{H}^n$  relative to  $Q$ . Let  $P([\mathbf{x}]) \in \mathcal{P}^n$ , a point  $[\mathbf{y}] \in \mathcal{P}^n$  is said to be conjugate to  $[\mathbf{x}]$  relative to  $Q$  if  $\langle \mathbf{x}, \mathbf{y} \rangle = 0$  holds. The set of all points which are conjugate to  $P([\mathbf{x}])$  form a projective (polar) hyperplane

$$\text{pol}(P) := \{[\mathbf{y}] \in \mathcal{P}^n \mid \langle \mathbf{x}, \mathbf{y} \rangle = 0\}. \quad (2.3)$$

Thus the quadric  $Q$  (defined by the symmetric bilinear form or scalar product in (2.1)) induces a bijection (linear polarity  $\mathbf{V}^{n+1} \rightarrow \mathbf{V}_{n+1}$ ) from the points of  $\mathcal{P}^n$  onto its hyperplanes.

The point  $X[\mathbf{x}]$  and the hyperplane  $\alpha[\mathbf{a}]$  are called incident if  $\mathbf{x}\mathbf{a} = 0$  i.e. the value of the linear form  $\mathbf{a}$  on the vector  $\mathbf{x}$  is equal to zero ( $\mathbf{x} \in \mathbf{V}^{n+1} \setminus \{\mathbf{0}\}$ ,  $\mathbf{a} \in \mathbf{V}_{n+1} \setminus \{\mathbf{0}\}$ ). The straight lines of  $\mathcal{P}^n$  are characterized by 2-subspaces of  $\mathbf{V}^{n+1}$  or by  $n - 1$ -spaces of  $\mathbf{V}_{n+1}$ , i.e. by 2 points or dually by  $n - 1$  hyperplane, respectively [M97].

Let  $P \subset \mathbb{H}^n$  denote a convex polytope bounded by finitely many hyperplanes  $H^i$ , which are characterized by unit normal vectors  $\mathbf{b}^i \in \mathbf{V}_{n+1}$  directed inwards with respect to  $P$ :

$$H^i := \{\mathbf{x} \in \mathbb{H}^n \mid \langle \mathbf{x}, \mathbf{b}^i \rangle = 0\} \quad \text{with} \quad \langle \mathbf{b}^i, \mathbf{b}^i \rangle = 1. \quad (2.4)$$

We always assume that  $P$  is acute-angled and of finite volume.

The Gram matrix  $G(P) := (\langle \mathbf{b}^i, \mathbf{b}^j \rangle)_{i, j \in \{0, 1, 2, \dots, n\}}$  of the normal vectors  $\mathbf{b}^i$  associated to  $P$  is an indecomposable symmetric matrix of signature  $(1, n)$  with entries  $\langle \mathbf{b}^i, \mathbf{b}^i \rangle = 1$  and  $\langle \mathbf{b}^i, \mathbf{b}^j \rangle \leq 0$  for  $i \neq j$ , having the following geometrical meaning

$$\langle \mathbf{b}^i, \mathbf{b}^j \rangle = \begin{cases} 0 & \text{if } H^i \perp H^j, \\ -\cos \alpha^{ij} & \text{if } H^i, H^j \text{ intersect on } P \text{ at angle } \alpha^{ij}, \\ -1 & \text{if } H^i, H^j \text{ are parallel,} \\ -\cosh l^{ij} & \text{if } H^i, H^j \text{ admit a common perpendicular} \\ & \text{of length } l^{ij}. \end{cases}$$

A scheme  $\Sigma$  is a weighted graph whose nodes  $n_i, n_j$  are joined by an edge with positive weight  $\sigma^{ij}$  or are not joined at all; the last fact will be indicated by  $\sigma^{ij} = 0$ . The number  $|\Sigma|$  of nodes is called the order of  $\Sigma$ . To every scheme of order  $m$  corresponds a symmetric matrix  $M(\Sigma) = (b^{ij})$  of order  $m$  with  $b^{ii} = 1$  in the diagonal and non-positive entries  $b^{ij} = -\sigma^{ij} \leq 0$ , for  $i$  not equal to  $j$ . The scheme  $\Sigma(P)$  of an acute angled polytope  $P$  is the scheme whose matrix  $M(\Sigma)$  coincides with the Gram matrix  $G(P)$ .

*Definition 2.1.* An orthoscheme  $\mathcal{O}$  in  $X$  is a simplex bounded by  $n + 1$  hyperplanes  $H^0, \dots, H^n$  such that ([K91], [B-H])

$$H^i \perp H^j, \quad \text{for } j \neq i - 1, i, i + 1.$$

*Remark 2.1.* This definition is equivalent to Definition 2.2:

*Definition 2.2.* A simplex  $\mathcal{O}$  in  $X$  is an orthoscheme iff the  $n + 1$  vertices of  $\mathcal{O}$  can be labelled by  $A_0, A_1, \dots, A_n$  in such a way that

$$\text{span}(A_0, \dots, A_i) \perp \text{span}(A_i, \dots, A_n) \quad \text{for } 0 < i < n - 1.$$

Here we have indicated the subspaces spanned by the corresponding vertices. A plane orthoscheme is a right-angled triangle, whose area formula can be expressed by the well known defect formula. For three-dimensional spherical orthoschemes, L. SCHLÄFLI about 1850 found the volume differentials in terms of differential of the 3 variable dihedral angles. Already in 1836, N. I. LOBACHEVSKY found a volume formula for three-dimensional hyperbolic orthoschemes  $\mathcal{O}$  [B-H].

The integration method for orthoschemes of dimension three was generalized by BÖHM in 1962 [B–H] to spaces of constant nonvanishing curvature of arbitrary dimension.

*Definition 2.3.* The complete orthoschemes of degree  $d$  in  $\mathbb{H}^n$  are bounded by  $n + d + 1$  hyperplanes  $H^0, H^1, \dots, H^{n+d}$  such that  $H^i \perp H^j$  for  $j \neq i - 1, i, i + 1$ , where, for  $d = 2$ , indices are taken modulo  $n + 3$ .

For a usual orthoscheme we denote the  $(n + 1)$ -hyperface opposite to the vertex  $A_i$  by  $H^i$  ( $0 \leq i \leq n$ ). An orthoscheme  $\mathcal{O}$  has  $n$  dihedral angles which are not right angles. Let  $\alpha^{ij}$  denote the dihedral angle of  $\mathcal{O}$  between the faces  $H^i$  and  $H^j$ . Then we have

$$\alpha^{ij} = \frac{\pi}{2}, \quad \text{if } 0 \leq i < j - 1 \leq n.$$

The  $n$  remaining dihedral angles  $\alpha^{i,i+1}$ , ( $0 \leq i \leq n - 1$ ) are called the essential angles of  $\mathcal{O}$ .

Geometrically, complete orthoschemes of degree  $d$  can be described as follows:

- (1) For  $d = 0$ , they coincide with the class of classical orthoschemes introduced by SCHLÄFLI (see Definitions 2.1 and 2.3). The initial and final vertices,  $A_0$  and  $A_n$  of the orthogonal edge-path  $A_i A_{i+1}$ ,  $i = 0, \dots, n - 1$ , are called principal vertices of the orthoscheme (see Definition 2.2).
- (2) A complete orthoscheme of degree  $d = 1$  can be interpreted as an ideal orthoscheme with one ideal principal vertex, say  $A_n$ , which is truncated by its polar plane  $\text{pol}(A_n)$  (see Figure 2). (If the vertex lies outside the absolute quadric then this vertex is called *ideal* using the projective model for  $\mathbb{H}^n$ . In this case the orthoscheme is called simply truncated with ideal vertex  $A_n$ .)
- (3) A complete orthoscheme of degree  $d = 2$  can be interpreted as an ideal orthoscheme with two ideal principal vertex,  $A_0, A_n$ , which is truncated by its polar hyperplanes  $\text{pol}(A_0)$  and  $\text{pol}(A_n)$ . In this case the orthoscheme is called doubly truncated. (In this case we distinguish two different types of orthoschemes but I will not enter into the details (see [K89], [K91]).)

For the schemes of complete Coxeter orthoschemes  $P_C \subset X$  we adopt the usual conventions and use them sometimes even in the Coxeter case: If two nodes are related by the weight  $\cos \frac{\pi}{p}$  then they are joined by a  $(p-2)$ -fold line for  $p = 3, 4$  and by a single line marked  $p$  for  $p \geq 5$ . In the hyperbolic case if two bounding hyperplanes of  $P_C$  are parallel, then the corresponding nodes are joined by a line marked  $\infty$ . If they are divergent then their nodes are joined by a dotted line.

Our polyhedron  $A_0A_1A_2P_0P_1P_2$  in  $\mathbb{H}^3$  belongs to the case 2, this is a simple frustum orthoscheme with ideal vertex  $A_3$  (see Figure 1, 2).

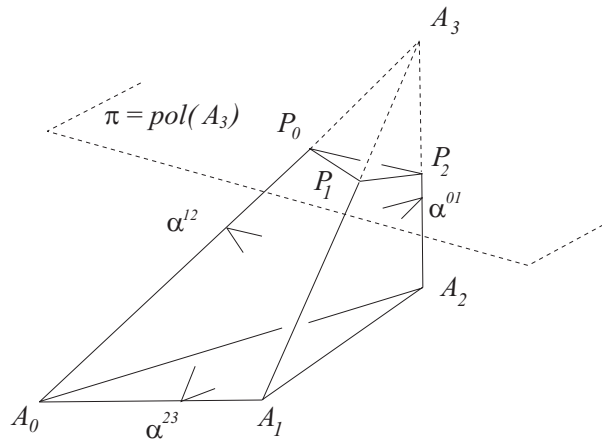


Figure 2

The principal minor matrix  $(c^{ij})$  of  $G(P_C)$  is the so called Coxeter-Schläfli matrix of the orthoscheme  $P_C$  with parameters  $p, q, r, s$ :

$$(c^{ij}) := \begin{pmatrix} 1 & -\cos \frac{\pi}{p} & 0 & 0 & 0 \\ -\cos \frac{\pi}{p} & 1 & -\cos \frac{\pi}{q} & 0 & 0 \\ 0 & -\cos \frac{\pi}{q} & 1 & -\cos \frac{\pi}{r} & 0 \\ 0 & 0 & -\cos \frac{\pi}{r} & 1 & -\cos \frac{\pi}{s} \\ 0 & 0 & 0 & -\cos \frac{\pi}{s} & 1 \end{pmatrix}. \quad (2.5)$$

### 3. Prism tilings and their optimal hyperball packings in $\mathbb{H}^4$

**3.1. The existence of the prism honeycombs.** In this section we consider the 4-dimensional prism honeycombs. The two regular 3-faces of a prism are called cover-polyhedra, and its other 3-dimensional polyhedra are called side-prisms.

Figure 3 shows such a part of our 4-prism where  $A_3$  is the centre of a cover-polyhedron,  $A_2$  is the midpoint of a face of the cover-polyhedron,  $A_1$  is a midpoint of an edge of this face, and  $A_0$  is one vertex (end) of that edge.

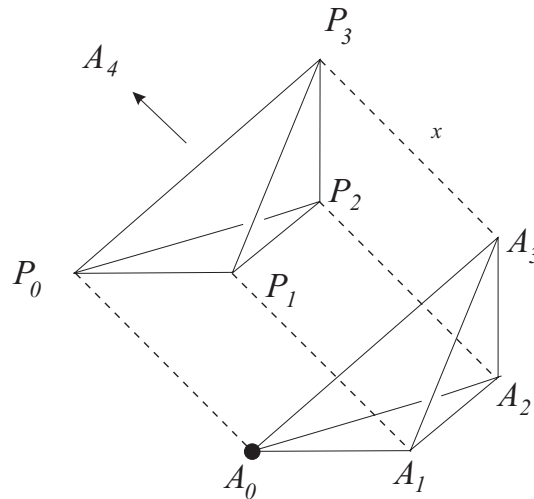


Figure 3

Let  $B_0, B_1, B_2, B_3$  be corresponding points of the other cover-polyhedron of the 4-prism. The midpoints of the edges which do not lie in the cover-polyhedra form a hyperplane denoted by  $\pi$ . The endpoints  $P_i$  ( $i \in \{0, 1, 2, 3\}$ ) of the perpendiculars dropped from the points  $A_i$  on the plane  $\pi$  form the *characteristic (or fundamental) simplex* of the a regular polyhedron with Schläfli symbol  $\{p, q, r\}$  in  $\pi$  (see Figure 3). (3-dimensional case in which  $\pi = [P_0, P_1, P_2]$  the characteristic simplex  $P_0P_1P_2$  was a right-angled triangle with other angles  $\pi/p$  and  $\pi/q$  (see Figure 1).)



Analogously to the 3-dimensional case, it can be seen that  $A_0A_1A_2A_3A_4$  is a complete orthoscheme with degree  $d = 1$  where  $A_4$  is an ideal outer vertex of  $\mathbb{H}^4$  and the points  $P_0P_1P_2P_3$  form its polar 3-plane (Figure 3).

From the definitions of the prism tilings and the complete orthoschemes of degree  $d = 1$ , it follows that prism tilings exist in the  $n$ -dimensional hyperbolic space  $\mathbb{H}^n$ ,  $n \geq 3$  if and only if exist complete Coxeter orthoschemes of degree  $d = 1$  with two divergent faces.

The complete Coxeter orthoschemes were classified by IM HOF [IH85] [IH90] by generalizing the method of COXETER and BÖHM appropriately. He showed that they exist only for dimensions  $\leq 9$ .

R. KELLERHALS in [K89] derived a volume formula in the 3 dimensional hyperbolic space for the *complete orthoschemes of degree  $d$* , ( $d = 0, 1, 2$ ) and she explicitly determined in [K91] the volumes of all complete hyperbolic orthoschemes in even dimensions ( $n \geq 4$ ).

On the other hand, if a prism honeycomb exists, then it has to satisfy the following two requirements:

- (1) The orthogonal projection of the cover-polyhedra on the hyperbolic 3-plane  $\pi$  is a regular Coxeter honeycomb with proper vertices and centres. Using the classical notation of the tessellations, each honeycomb is given by its Schläfli symbol  $\{p, q, r\}$ . Such a tiling exists in the 3-dimensional hyperbolic 3-space if and only if

$$\{p, q, r\} = \{3, 5, 3\}, \{4, 3, 5\}, \{5, 3, 4\}, \{5, 3, 5\}. \quad (3.1)$$

- (2) The vertex figures about a vertex of such a prism tiling has to form a 4-dimensional regular polyhedron which is given by its Schläfli symbol as follows:

$$\{q, r, s\} = \{3, 3, 3\}, \{3, 3, 4\}, \{3, 3, 5\}, \{3, 4, 3\}, \\ \{4, 3, 3\}, \{5, 3, 3\}. \quad (3.2)$$

From the above mentioned works of [IH90] and [K89] it follows that in the 4-dimensional hyperbolic space  $\mathbb{H}^4$  there are two types of the complete orthoschemes of degree  $d = 1$  which have two divergent faces. Thus in  $\mathbb{H}^4$  there are two prism tilings which are given by its schemes  $\Sigma_{3533}$  and  $\Sigma_{5343}$  as follows:

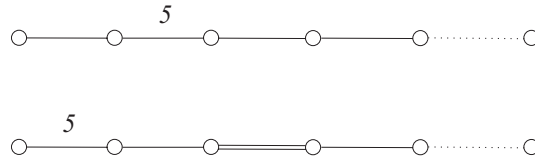


Figure 4

**3.2. The hyperball packings of the prism tilings.** The equidistant surface (or hypersphere) is a quadratic surface at a constant distance from a plane in both halfspaces. The infinite body enclosed by the hypersphere is called hyperball.

The hypersphere with distance  $t$  to the plane  $\pi$  is denoted by  $\mathcal{HS}_\pi^t$ . The optimal hypersphere  $\mathcal{HS}_\pi^{opt}$  touches the cover-faces of our 4-prisms whose union forms an infinite polyhedron denoted by  $\mathcal{F}$ . The optimal distance from the 3-midplane  $\pi$  will be  $t_{pqr s}^{opt} = P_3A_3$  (Figure 3).  $\mathcal{F}$  and its images fill the hyperbolic space  $\mathbb{H}^4$  thus we obtain by the images of  $\mathcal{HS}_\pi^{opt}$  the optimal hyperball packing for the parameters  $\{p \mid q, r \mid s\}$ .

For the density of the packing it is sufficient to relate the volume of the optimal hyperball piece to that of its containing polyhedron  $A_0A_1A_2A_3P_0P_1P_2P_3$  (Figure 3) because the tiling can be constructed of such polyhedron. This polytope and its images in  $\mathcal{F}$  divide the  $\mathcal{HS}_\pi^{opt}$  into congruent pieces whose volume is denoted by  $\text{Vol}(HS_{pqr s})$ . We illustrate in the 3-dimensional case such a hyperball piece  $A_2A'_0A'_1P_0P_1P_2$  in Figure 1.

The volume of the polyhedron  $A_0A_1A_2A_3P_0P_1P_2P_3$  is denoted by  $\text{Vol}(W_{pqr s})$ .

*Definition 3.1.* The density of the optimal hyperball packing to the prism tilings with scheme  $\Sigma_{pqr s}$  is defined by the following formula:

$$\delta_{pqr s}^{opt} := \frac{\text{Vol}(HS_{pqr s})}{\text{Vol}(W_{pqr s})}. \tag{3.3}$$

**3.3. On the volumes.** The volumes  $\text{Vol}(W_{pqr s})$  were determined by R. KELLERHALS in [K91]:

$$\text{Vol}(W_{3533}) = \frac{41\pi^2}{10800} \approx 0.03746794, \quad \text{Vol}(W_{5343}) = \frac{17\pi^2}{4320} \approx 0.03883872.$$

The volume of the hyperball piece  $HS_{pqrs}$  can be determined by the formula (3.4) that follows from the classical method of J. Bolyai:

$$\text{Vol}(HS_{pqrs}) = \frac{1}{8} \text{Vol}(\mathcal{A}_{pqr})k \left( \frac{1}{3} \sinh \frac{3t_{pqrs}^{opt}}{k} + 3 \sinh \frac{t_{pqrs}^{opt}}{k} \right), \quad (3.4)$$

where the volume of the hyperbolic polyhedron  $P_0P_1P_2P_3$  is  $\text{Vol}(\mathcal{A}_{pqr})$  and  $t_{pqrs}^{opt} = P_3A_3$ . (The constant  $k = \sqrt{\frac{-1}{K}}$  is the natural length unit in  $\mathbb{H}^n$ .  $K$  will be the constant negative sectional curvature.) In the following we can take the constant  $k = 1$  (as in Kellerhals' formulas above).

The points  $P_3(\mathbf{p}_3)$  and  $A_3(\mathbf{a}_3)$  are proper points of the hyperbolic 4-space thus their distance  $t_{pqrs}^{opt}$  can be calculated by the following formula [M89]:

$$\cosh P_3A_3 = \frac{-\langle \mathbf{p}_3, \mathbf{a}_3 \rangle}{\sqrt{\langle \mathbf{p}_3, \mathbf{p}_3 \rangle \langle \mathbf{a}_3, \mathbf{a}_3 \rangle}}. \quad (3.5)$$

Inverting the Coxeter–Schläfli matrix  $c^{ij}$  (see (2.5)) of the orthoscheme we get the matrix  $h_{ij}$ . By the machinery of the projective metric geometry [M89] we have obtained the following result:

$$\cosh t_{pqrs}^{opt} = \sqrt{\frac{(h_{34})^2 - h_{33} h_{44}}{h_{33} h_{44}}}. \quad (3.5)$$

The volumes  $\text{Vol}(\mathcal{A}_{pqr})$  have been determined by the classical formula of Lobachevsky in [Sz].

Our main results on the regular prism tilings in the hyperbolic 4-space  $\mathbb{H}^4$  are summarized in the Theorems 1.1–2 in the Introduction with the following Table 1.

Table 1

	$\Sigma_{3533}$	$\Sigma_{5343}$
$\text{Vol}(W_{pqrs})$	$\frac{41\pi^2}{10800}$	$\frac{17\pi^2}{4320}$
$t_{pqrs}^{opt}$	$\approx 0.48958213$	$\approx 0.53063753$
$\text{Vol}(\mathcal{A}_{pqr})$	$\approx 0.03905029$	$\approx 0.03588506$
$\text{Vol}(HS_{pqrs})$	$\approx 0.02161163$	$\approx 0.02200304$
$\delta_{pqrs}^{opt}$	$\approx 0.57680322$	$\approx 0.56652323$

#### 4. Regular prism tilings in higher dimensions

Regular hyperbolic honeycombs exist only up to 5 dimensions [C56]. Therefore regular prism tilings can exist up to 6 dimensions. From the definitions of the prism tilings and the complete orthoschemes of degree  $d = 1$  it follows that prism tilings exist in the  $n$ -dimensional hyperbolic space  $\mathbb{H}^n$ ,  $n \geq 3$  if and only if there exist complete Coxeter orthoschemes of degree  $d = 1$  with two divergent faces. From the paper [IH90] it follows that there are 3-different types of the regular prism tilings in the 5-dimensional hyperbolic space  $\mathbb{H}^5$  which are given by its schemes  $\Sigma_{53333}$ ,  $\Sigma_{53343}$  and  $\Sigma_{53334}$  as follows:

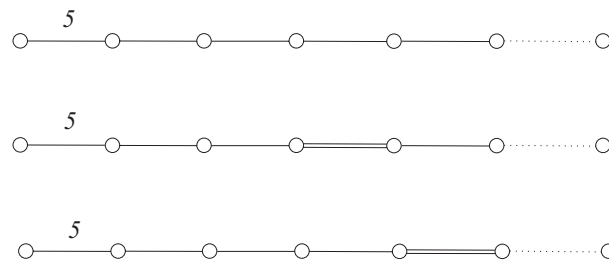


Figure 5

In the 6-dimensional hyperbolic space there is no such Coxeter orthoscheme, thus we obtain Theorems 1.3–4 in the Introduction. The metric data and the optimal hyperball packings of the 5-dimensional regular prism tilings we shall investigate with our projectiv method in a forthcoming work.

*Remark 4.1.* The way of putting any analogous questions for higher dimensions are interesting and timely for determining the optimal ball, horoball and hyperball packings of tilings in hyperbolic  $n$ -space ( $n > 2$ ). Our projective method seems well suited to study and to solve these problems.

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