# (Para)quaternionic geometry, harmonic forms, and stochastical relaxation 

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This paper is dedicated to Professor Lajos Tamássy on the occasion of his ninetieth birthday


#### Abstract

Both quaternionic and para-quaternionic geometry are important when studying harmonic forms and stochastical relaxation with the help of Fokker-Plancktype or Oguchi-type parabolic equations. In a recent paper the first-named author and H. M. Polatoglou (2012) have shown that the five-dimensional case is the simplest case that the use of para-quaternions is more convenient that the use of quaternions. Now we discuss that case in some detail.


## 1. Introduction and preliminaries

Quaternionic geometry was studied e.g. in [1], [8], [18]-[22], including the twistor aspect; para-quaternionic geometry was investigated e.g. in [27]-[29], [7], [17]. The initial difference is due to the replacement of matrix units $\mathbf{1}, i \sigma_{1}, i \sigma_{2}, i \sigma_{3}$ of the usual quaternions, where

$$
\sigma_{1}=\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right), \quad \sigma_{2}=\left(\begin{array}{cc}
0 & -i \\
i & 0
\end{array}\right), \quad \sigma_{3}=\left(\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right)
$$

[^0]are generators of the Pauli algebra, by the units
$$
\mathbf{1}, \tilde{\mathbf{i}}=i \sigma_{2}, \quad \tilde{\mathbf{j}}=\sigma_{1}, \quad \tilde{\mathbf{k}}=\sigma_{3}
$$
of para-quaternions, so that our $\tilde{\mathbf{i}} \tilde{\mathbf{j}}$, and $\tilde{\mathbf{k}}$ mean $\mathbf{j},(1 / i) \mathbf{i}$, and $(1 / i) \mathbf{k}$ in $[8]$, respectively. This is due to our definition of the real Clifford algebra $\tilde{\mathbb{H}}$ of paraquaternions as generated by 1 and imaginary units $\tilde{i}, \tilde{j}, \tilde{k}$ satisfying
\[

$$
\begin{equation*}
-\tilde{i}^{2}=\tilde{j}^{2}=\tilde{k}^{2}=1, \quad \tilde{i} \tilde{j}=-\tilde{j} \tilde{i}=\tilde{k} . \tag{1}
\end{equation*}
$$

\]

For a para-quaternionic structure the left module structure is defined up to conjugation in $\tilde{\mathbb{H}}$.

In a more general setting, let $V$ be a real vector space. A complex structure on $V^{2 n}$ is an endomorphism $J \in \operatorname{End}(V)$ such that $J^{2}=-$ Id. A hypercomplex structure H on $V^{4 n}$ is a triple $\left(J_{\alpha}\right)=\left(J_{1}, J_{2}, J_{3}\right)$ of anticommuting complex structures on $V$ satisfying $J_{1} J_{2}=J_{3}$; it defines on $V$ the structure of left vector space over quaternions $\mathbb{H}=\operatorname{span}_{\mathbb{R}}\{1, i, j, k\}$ such that multiplications by $i, j$ and $k$ are given by $J_{1}, J_{2}$ and $J_{3}$. A quaternionic structure on $V^{4 n}$ is the 3dimensional subspace $Q \subset \operatorname{End}(V)$ spanned by a hypercomplex structure H, i.e. $Q=\operatorname{span}_{\mathbb{R}}\left\{J_{1}, J_{2}, J_{3}\right\}$.

A triple $\tilde{J}_{1}, \tilde{J}_{2}, \tilde{J}_{3}$ of anticommuting endomorphisms of $V$ satisfying the relations

$$
-\tilde{J}_{1}^{2}=\tilde{J}_{2}{ }^{2}=\tilde{J}_{3}{ }^{2}=\mathrm{Id}, \quad \tilde{J}_{1} \tilde{J}_{2}=\tilde{J}_{3}
$$

is called a para-hypercomplex structure on $V$. Observe that ( $\tilde{J}_{1}$ is a complex structure and) $\tilde{J}_{2}$ and $\tilde{J}_{3}$ are para-complex structures on $V$. A Lie subalgebra $\tilde{Q} \subset \mathfrak{g l}(V)$ is called a para-quaternionic structure on $V$ if there exists a basis $\tilde{J}_{1}$, $\tilde{J}_{2}, \tilde{J}_{3}$ satisfying the above relations. A para-hypercomplex structure $\left(\tilde{J}_{1}, \tilde{J}_{2}, \tilde{J}_{3}\right)$ defines on $V$ the structure of a left module over the Clifford algebra generated by unity 1 and generators $\tilde{,}, \tilde{j}, \tilde{k}$ satisfying (1).

The Hurwitz twistors are deduced from quaternions and Clifford structures as follows. Let $\mathbb{C}^{4}\left(I_{2}, I_{2}\right)$ be the 4 -dimensional complex space with the indefinite hermitian metric

$$
\kappa=I_{2,2}=\operatorname{diag}^{*}\left(I_{2},-I_{2}\right)=\left(\begin{array}{cc}
0 & -I_{2} \\
I_{2} & 0
\end{array}\right), I_{2}=\mathbf{1},
$$

and $\mathbb{R}^{5}\left(I_{2,3}\right)$ - the 5 -dimensional real space with the indefinite symmetric metric $I_{2,3}=\operatorname{diag}\left(I_{2},-I_{3}\right)$. Let $\left(e_{1}, \ldots, e_{4}\right)$ and $\left(e_{1}, \ldots, e_{5}\right)$ denote the corresponding
canonical bases, and $\circ$ the multiplication acting from $\mathbb{R}^{3}\left(I_{2,3}\right) \otimes_{\mathbb{R}} \mathbb{C}^{4}\left(I_{2,2}\right)$ to $\mathbb{C}^{4}\left(I_{2,2}\right)$. Let us set

$$
\epsilon_{\alpha} \circ \epsilon_{k}=C_{\alpha k}^{1} \epsilon_{1}+\cdots+C_{\alpha k}^{4} \epsilon_{4}, \quad C_{\alpha}+\left(C_{\alpha k}^{j}\right), \quad j=1, \ldots, 5
$$

Consider the algebra $\mathcal{A}_{2,3}$ generated by $\left\{C_{\alpha}^{\#} C_{\beta}: \alpha \leq \beta\right\}$ where $C_{\alpha}^{\#}=\kappa C_{j}^{*} \kappa^{-1}$.
An element $x \in \mathcal{A}_{2,3}$ is called Hurwitz twistor [12], [13] whenever $x$ has the form

$$
\begin{equation*}
x=\sum_{\alpha<\beta} \xi_{\alpha, \beta} C_{\alpha}^{\#}, \quad \xi_{\alpha, \beta} \in \mathbb{C} \tag{2}
\end{equation*}
$$

and $\operatorname{im} x^{2}=0$, where $x \in \mathcal{A}_{2,3}$ is defined in the following manner: $x \in \mathcal{A}_{2,3}$ can be written uniquely as

$$
\begin{equation*}
x=\sum_{k=0}^{4} x_{k}, \quad x=\sum_{\alpha_{1}<\beta_{1}<\ldots<\alpha_{k}<\beta_{k}} \xi_{\alpha_{1}, \beta_{1}, \ldots, \alpha_{k}, \beta_{k}} C_{\alpha_{1}}^{\#} C_{\beta_{1}} \ldots C_{\alpha_{k}}^{\#} C_{\beta_{k}} \tag{3}
\end{equation*}
$$

with $x_{0}=\xi_{0} I_{4}$ for $k=0$. We set $\operatorname{im} x:=x-x_{0}$ and denote the collection of Hurwitz twistors by H :

$$
\mathrm{H}=\left\{x=\sum_{\alpha<\beta} \xi_{\alpha, \beta} C_{\alpha}^{\#} C_{\beta}: \operatorname{im} x^{2}=0\right\}
$$

Traditionally, the 5 -dimensional space-time is $\mathbb{R}^{5}\left(I_{1,4}\right)$; when speaking on Hurwitz twistors, it seems convenient to associate them with $\mathbb{R}^{5}\left(I_{3,2}\right)$ instead of $\mathbb{R}^{5}\left(I_{2,3}\right)$. It appears that the expression (2) is an element of $H$, if and only if the following $\binom{5}{4}$ equations hold:

$$
\begin{aligned}
& \xi_{12} \xi_{34}-\xi_{13} \xi_{24}+\xi_{14} \xi_{23}=0 \\
& \xi_{12} \xi_{35}-\xi_{13} \xi_{25}+\xi_{15} \xi_{23}=0 \\
& \xi_{12} \xi_{45}-\xi_{14} \xi_{25}+\xi_{15} \xi_{24}=0 \\
& \xi_{13} \xi_{45}-\xi_{14} \xi_{35}+\xi_{15} \xi_{34}=0 \\
& \xi_{23} \xi_{45}-\xi_{24} \xi_{35}+\xi_{25} \xi_{34}=0
\end{aligned}
$$

In analogous way the anti-objects, called anti-Hurwitz twistors, correspond to $\mathbb{R}^{5}(1,4)$ and are determined by $\binom{5}{4}$ similar equations as well; we denote the collection of those anti-objects by aH. Still in analogy we consider $\mathbb{C}^{16}\left(I_{8,8}\right)$ and $\mathbb{R}^{9}(8,1)$ replacing it by $\mathbb{R}^{9}(1,8)$ which leads to pseudotwistors [15]:

$$
\mathrm{p}=\left\{x=\sum_{\alpha<\beta<9} \xi_{\alpha, \beta} C_{\alpha}^{\#} C_{\beta}: \operatorname{im} x^{2}=0\right\}
$$

determined by $\binom{9}{4}=126$ algebraic equations; we denote the collection of corresponding anti-objects by ap. We may also consider $\mathbb{C}^{64}\left(I_{32,32}\right)$ and $\mathbb{R}^{13}(6,7)$ replaced by $\mathbb{R}^{13}(7,6)$ which leads to bitwistors determined by $\binom{13}{4}=715$ algebraic equations; we denote their collection by $b$ and the collection of their anti-objects - by ab. The above leads to the so-called Cartan-like triality [6].


Figure 1. Double Cartan-like triality of Hurwitz twistors, pseudotwistors, and bitwistors.

## 2. Some relationship with traditional harmonicity and holomorphy

Before we start to use quaternions or para-quaternions for investigating parabolic equations responsible for relaxation, we recall some known results on relations with traditional harmonicity and holomorphy.
2.1. Relationship with harmonic forms. Let $Z_{\mathcal{A}}^{(n)}(U)$ be the space of realanalytic solutions of the structure spinor equations (of $\operatorname{spin} \frac{1}{2} n$ ) on an open set $U \subset \mathbb{C}^{2 k}, k=1,2$. Then [14] they can be written as harmonic forms, i.e., there exists a one-to-one correspondence between spinor solutions and harmonic forms
with respect to:
the ( 1,1 )-metric

$$
d s^{2}:=d z^{1} d \bar{z}^{1}-d z^{2} d \bar{z}^{2} \text { for } k=1 \text { (Hurwitz twistors); }
$$

the $(0,4)$-metric

$$
d s^{2}:=-d z^{1} d \bar{z}^{1}-d z^{2} d \bar{z}^{2}-d z^{3} d \bar{z}^{3}-d z^{4} d \bar{z}^{4} \quad \text { for } k=2 \text { (pseudotwistors). }
$$

This correspondence can be expressed as:

$$
\mathrm{Z}_{\mathcal{A}}^{(n)}(U) \simeq \mathbb{H}^{1}\left(U, \mathbb{C}^{2^{2 k-1}(n-1)}\right) \quad \text { for } k=1,2
$$

where

$$
\mathbb{H}^{1}\left(U, \mathbb{C}^{2^{2 k-1}(n-1)}\right)=\left\{\phi \in \Gamma^{1,0}\left(U, \mathbb{C}^{2^{2 k-1}(n-1)}\right): \partial \phi=0 \text { and } \vartheta \phi=0\right\}
$$

and $\vartheta$ is the formally adjoint operator of $\partial$ with respect to the indefinite fibre $\left(2^{2 k-1}, 0\right)$-metric

$$
d \rho^{2}:=d \zeta^{1} d \bar{\zeta}^{1}+d \zeta^{2} d \bar{\zeta}^{2}+\ldots+d \zeta^{2 k-1} d \bar{\zeta}^{2 k-1}
$$

### 2.2. Relationship with the one-dimensional Dolbeault cohomology group. Set

$$
\begin{aligned}
\mathcal{P}^{1} & :=\left\{L_{1}^{1}: L_{1}^{1} \subset \mathbb{C}^{4}, \text { linear subspace, } \operatorname{dim} L_{1}^{1}=1\right\}\left(\simeq \mathbb{P}^{3}(\mathbb{C})\right) \\
\mathcal{U}^{1} & :=\left\{L_{2}^{1}: L_{2}^{1} \subset \mathbb{C}^{4}, \text { linear subspace, } \operatorname{dim} L_{2}^{1}=2\right\}(\simeq \mathrm{G}(2,4), \\
\mathcal{P}^{2} & :=\left\{L_{1}^{2}: L_{1}^{2} \subset \mathbb{C}^{8}, \text { linear subspace, } \operatorname{dim} L_{1}^{2}=1\right\}\left(\simeq \mathbb{P}^{7}(\mathbb{C})\right) \\
\mathcal{U}^{2} & :=\left\{L_{2}^{2}: L_{2}^{2} \subset \mathbb{C}^{8}, \text { linear subspace, } \operatorname{dim} L_{2}^{2}=2\right\}(\simeq \mathrm{G}(2,8)),
\end{aligned}
$$

where $\mathbb{P}^{3}(\mathbb{C}), \mathbb{P}^{7}(\mathbb{C}), G(2,4), G(2,8)$ are the corresponding complex projective and Grassmannian spaces, respectively. Then we have the following correspondences:


Let $Z_{\mathcal{H}}^{n}\left(U_{k}\right)$ be the space of holomorphic solutions of the structure spinor equations (of spin $\frac{1}{2} n$ ) on an open set $U_{k}$, whereas $\mu_{k}$ and $\nu_{k}$ be the related fibre bundles forming the diagrams (4). We set

$$
U_{k}^{\prime}=\nu_{k}^{-1}\left(U_{k}\right) \text { and } U_{k}^{\prime \prime}=\mu_{k} \circ \nu_{k}^{-1}\left(U_{k}\right) \quad \text { for } k=1,2
$$

Then, if every fibre of $\mu_{k}$ is connected, there exists a one-to-one correspondence [14]:

$$
Z_{\mathcal{H}}^{n}\left(U_{k}\right) \simeq \mathrm{H}^{1}\left(U_{k}^{\prime \prime}, \mathcal{O}\left(-\alpha_{k} n-\beta_{k}\right)\right),
$$

where $\mathrm{H}^{1}$ denotes the one-dimensional Dolbeault cohomology group,

$$
\mathcal{O}\left(-\alpha_{k} n-\beta_{k}\right)=\mathcal{O}\left([e]^{-\alpha_{k} n-\beta_{k}}\right)
$$

$[e]$ being the canonical effective divisor of $\mathbb{P}^{3}(\mathbb{C})$, while $\alpha_{k}$ and $\beta_{k}$ are positive integers. Moreover,

$$
\alpha_{1}=1, \quad \beta_{1}=2 ; \quad \beta_{2} \geq 2
$$

2.3. Relationship with traditional holomorphy. Consider the holomorphic embeddings

$$
\begin{align*}
& \mathbb{C}^{2} \simeq \mathbb{R}^{4} \xrightarrow{\iota} G(2,4), \quad \mathbb{R}^{4} \ni x \stackrel{\iota}{\longmapsto} \sum_{\alpha=1}^{3} x^{\alpha} S_{\alpha}+x^{4} I_{4},  \tag{5}\\
& \mathbb{C}^{4} \simeq \mathbb{R}^{8} \xrightarrow{\iota} G(8,16), \quad \mathbb{R}^{8} \ni x \stackrel{\iota}{\longmapsto} \sum_{\alpha=1}^{7} x^{\alpha} S_{\alpha}+x^{8} I_{8}, \tag{6}
\end{align*}
$$

where $G(\tau, \nu)$ stands for a $\tau$-dimensional Grassmannian submanifold, while $S_{\alpha}$ and $I_{4}$ or $I_{8}$ are generators of the corresponding algebra, proposed explicitly first in [13], so that they are real parts of holomorphic mappings in the classical sense. The result we are going to quote was first published without specification of the quaternionic or para-quaternionic dependence in [14], [15] and with specifying this dependence - in [7]. In the case $(\sigma-1, \tau)=(0,4)$ resp. $(0,8)$ we are interested, it states that there exists a complex structure $I=I[\iota(\sigma-1, \tau)]$ on the holomorphic embedding (5) resp. (6) with properties

$$
\begin{equation*}
\iota(0,4)=\iota(0,4)(\mathbb{H}), \text { resp. } \iota(0,8)=\iota(0,8)(\widetilde{\mathbb{H}}) \tag{7}
\end{equation*}
$$

and the each embedding concerned is the real part of a holomorphic mapping in the classical sense.

We introduce seven $2 \times 2$-complex matrices which we call atoms:

$$
\begin{gathered}
A_{0}=A_{0}(\mathbb{H})=\left(\begin{array}{cc}
u & v_{\mathbb{H}} \\
-v_{\mathbb{H}} & u
\end{array}\right), \quad A_{1}=\left(\begin{array}{cc}
\hat{u} & \hat{v} \\
v & -u
\end{array}\right), \quad A_{2}=\left(\begin{array}{cc}
-u & -\hat{v} \\
-v & \hat{u}
\end{array}\right), \\
A_{3}=\left(\begin{array}{cc}
w & 0 \\
0 & w
\end{array}\right), \quad A_{4}=\left(\begin{array}{cc}
\hat{w} & 0 \\
0 & \hat{w}
\end{array}\right)
\end{gathered}
$$

$$
A_{5}=A_{5}(\tilde{\mathbb{H}})\left(\begin{array}{cc}
t_{\tilde{\mathbb{H}}} & 0 \\
0 & t_{\tilde{\mathbb{H}}}
\end{array}\right), \quad A_{6}=A_{6}(\tilde{\mathbb{H}})=\left(\begin{array}{cc}
t_{t} \hat{\mathbb{H}} & 0 \\
0 & t \hat{\mathbb{H}}
\end{array}\right)
$$

where $u$ in $A_{0}$ and $v_{\mathbb{H}}$ are given in

$$
u=x_{4}+i x_{3} \in \mathbb{C}, \quad v_{\mathbb{H}}=x_{2}+i x_{1} \in \mathbb{C}, \quad v_{\tilde{\mathbb{H}}}=x_{1}+i x_{2} \in \mathbb{C}
$$

whereas $u$ in $A_{1}, A_{2} ; v, w$, and $t_{\tilde{\mathbb{H}}}$ are given in

$$
\begin{gathered}
u=x_{3}+i x_{8} \in \mathbb{C}, \quad v=x_{1}+i x_{2} \in \mathbb{C}, \quad w=x_{4}+i x_{5} \in \mathbb{C}, \\
t_{\mathbb{H}}=x_{7}+i x_{6} \in \mathbb{C}, \quad t_{\tilde{\mathbb{H}}}=x_{6}+i x_{7} \in \mathbb{C} . \\
\text { Let } \quad \zeta_{\mathbb{H}}=\left(u, v_{\mathbb{H}}\right) \in \mathbb{C}^{2} \text { and } z_{\tilde{\mathbb{H}}}=\left(u, v, w, t_{\tilde{\mathbb{H}}}\right) \in \mathbb{C}^{4} .
\end{gathered}
$$

The atomization method allows us to find the following explicit formulae for the embedding in question:

$$
\iota\left(\zeta_{\text {تII }}\right)=A_{0} \text { for }(0,4), \quad \iota\left(z_{\tilde{\text { Ḧ }}}\right)=\left(\begin{array}{cccc}
A_{1} & A_{3} & A_{5} & 0 \\
A_{4} & A_{2} & 0 & A_{5} \\
A_{6} & 0 & A_{2} & -A_{3} \\
0 & A_{6} & -A_{4} & A_{5}
\end{array}\right) \text { for }(0,8)
$$

2.4. Pseudotwistros of degree 3 vs . those of degree 1. Consider quaternal embeddings, like $i_{\mathbb{A}}=\operatorname{diag}(\mathbb{A}, \mathbb{A}, \mathbb{A}, \mathbb{A}), \mathbb{A}=A_{3}$, acting from $G(2,4)$ to $G(8,16)$, instead of (2), pseudotwistors of degree $k$ with $x$ as in the second formula in (3), and collections $\mathcal{J}^{(k)}$ of all such $x$ with im $x^{2}=0$. Consider the following analogues of (4):

$$
\begin{align*}
& \mathcal{J}^{(k)} \quad \mathcal{J}^{(1)} \\
& \begin{array}{ccccc}
\swarrow & \searrow & k=1,3 ; & \swarrow & \searrow \\
J_{-}^{(k)} & J_{+}^{(k)} & & J_{-\mathbb{A}}^{(1)} & J_{+\mathbb{A}}^{(1)}
\end{array} \tag{8}
\end{align*}
$$

If $k=1$, then for any quaternal embedding $i_{\mathbb{A}}$ of some $V_{\mathbb{A}}$ in $G(2,4)$ to $G(8,16)$ we have

$$
\iota_{\mathbb{A}}^{*} \mathcal{J}^{(1)}=\mathcal{J}_{\mathbb{A}}^{(1)}, \quad \iota_{\mathbb{A}}^{*} \mathcal{J}_{+}^{(1)}=\mathcal{J}_{+\mathbb{A}}^{(1)}, \quad \iota_{\mathbb{A}}^{*} \mathcal{J}_{-}^{(1)}=\mathcal{J}_{-\mathbb{A}}^{(1)}
$$

and the diagram in (7) related with $\mathcal{J}_{\mathbb{A}}^{(1)}$. If $k=3$, we have

$$
\begin{equation*}
\mathcal{J}_{-}^{(3)} \subseteq \underset{\mathbb{A}^{-}}{ } \mathcal{J}_{\mathbb{A}_{-}}^{(1)} \cdot \mathcal{J}_{\mathbb{A}_{+}^{c}}^{(1)}, \quad \mathcal{J}_{+}^{(3)} \subseteq{\underset{\mathbb{A}}{ }}^{\mathcal{J}_{\mathbb{A}_{+}}^{(2)}} \cdot \mathcal{J}_{\mathbb{A}_{+}^{c}}^{(2)} \tag{9}
\end{equation*}
$$

where $\mathbb{A} \cup \mathbb{A}^{c}=\mathbb{A}^{*}$. The addends in (9) depend on the quaternionic or para-quaternionic structure according to dependence of $\mathbb{A}$ expressed in terms of $A_{1}, \ldots, A_{6}$.

## 3. Stochastical relaxation and the specific role of dimension 5

3.1. Setting of the problem. We consider a modified Oguchi equation [25], [4], [11]

$$
\begin{equation*}
\frac{\partial}{\partial t}\langle s(t, \bar{\tau})\rangle=-\frac{1}{\hat{\tau}}\left[\langle s(t, \bar{\tau})\rangle-\langle s(t, \bar{\tau})\rangle_{1 . \mathrm{e} .}\right] \tag{10}
\end{equation*}
$$

where $\bar{\tau}$ is the spin-lattice relaxation time related to a spin on $\mathbf{R}$-site, $\mathbf{R}=$ $\left(x_{1}, \ldots, x_{\tau}\right)$ in $\mathbb{R}^{r}, r=1,2, \ldots ; \bar{\tau}=x_{\tau+1}$ stands for the stochastic variable responsible for the stochastic behaviour of the lattice, describing thermal oscillations of spin, and $\langle s(t, \bar{\tau})\rangle$ denotes the canonical average of $\operatorname{spin} ;\langle s(t, \bar{\tau})\rangle_{1 . e}$. being its local equilibrium value. $\langle s(t, \tau)\rangle$ does not depend on the positions in a fixed layer $x_{\tau}=\hat{x}_{\tau}$. Set

$$
\begin{align*}
& \Gamma=\frac{1}{\hat{\tau}}\left[1-\frac{1}{2}\left(1-4\langle s\rangle^{2}\right) \frac{\hat{x}_{\tau} J}{k_{B} T}\right]  \tag{11}\\
& \Lambda=\frac{a^{2}}{\hat{\tau}} \cdot \frac{1}{2}\left(1-4\langle s\rangle^{2}\right) \frac{\hat{x}_{\tau} J}{k_{B} T} \tag{12}
\end{align*}
$$

where $J$ is the parameter of the theory responsible for the interaction between two neighbouring spins, and $a$ is the lattice constant. The equation (10) can be transformed to

$$
\frac{\partial}{\partial t}\langle s(t, \bar{\tau})\rangle=-\Gamma\langle s(t, \bar{\tau})\rangle+\Lambda\left(\sum_{\nu=1}^{\tau} \frac{\partial^{2}}{\partial x_{\nu}^{2}}-\frac{\hat{a}^{2}}{a^{2}} \frac{\partial^{2}}{\partial \bar{\tau}^{2}}\right)\langle s(t, \bar{\tau})\rangle,
$$

where $\Gamma$ and $\Lambda$ are given by (11) and (12), respectively, while $\hat{a}$ is the amplitude of stochastic movement. Then the substitution $\bar{\tau}=(\hat{a} / a) \tilde{\tau}$ brings the above equation to

$$
\begin{equation*}
\frac{\partial}{\partial t}\langle s(t, \tilde{\tau})\rangle=-\Gamma\langle s(t, \tilde{\tau})\rangle+\Lambda\left(\sum_{\nu=1}^{\tau} \frac{\partial^{2}}{\partial x_{\nu}^{2}}-\frac{\partial^{2}}{\partial \tilde{\tau}^{2}}\right)\langle s(t, \tilde{\tau})\rangle \tag{13}
\end{equation*}
$$

In [4], for solving (13), $\tau=2$ and 3 , the quaternionic approach was used systematically.

By (7), the 8- (resp. 4-)dimensional stochastical relaxation problem may be considered in relation with the pseudotwistors in p (resp. anti-Hurwitz twistors in aH ) in terms of para-quaternions (resp. quaternions) [11]. By restriction of solution of (13) an analogous conclusion holds for the $7-, 6$-, and 5 - (resp. 3-, 2-, and 1-) dimensional stochastical relaxation problems as well as for the 8-, 7-, 6-, and 5- (resp. 4-, 3-, 2-, and 1-) dimensional relaxation problems related with (13)


Figure 2. Applicability of para-quaternions (resp. quaternions) and pseudo-twistors (resp. anti-Hurwitz twistors) for 5-, 6-, 7-, 8- (resp. 1-, 2-, 3-, 4-)dimensional relaxation and stochastical relaxation problems.
for $\langle s(t, \bar{\tau})\rangle=\langle s(t)\rangle,\langle s(t, \bar{\tau})\rangle_{1 \text {.e. }}=0$. The reasoning is illustrated by Figure 2; the family of solutions to (13) for $\tau=8$ is represented by the point $(1,8)$ on the projection plane $\mathbb{C}_{\sigma, \tau}=\{(\sigma, \tau)\}$.

It seems interesting to consider, with help of para-quaternions, the simplest proper case of equation (13), i.e. for $\tau=5$. Let

$$
s(t, \tilde{\tau})=s(x, y, z ; \xi, \eta, \tilde{\tau} ; t), \quad(x, y, z, \xi, \eta, \tilde{\tau}) \in \mathbb{R}^{6} \simeq \mathbb{C}^{3} \quad t \in \mathbb{R}^{+}
$$

Then the equation (13) reads

$$
\begin{align*}
\frac{\partial}{\partial t}\langle s(t, \tilde{\tau})\rangle= & -\Gamma\langle s(t, \tilde{\tau})\rangle \\
& +\Lambda\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}+\frac{\partial^{2}}{\partial z^{2}}+\frac{\partial^{2}}{\partial \xi^{2}}+\frac{\partial^{2}}{\partial \eta^{2}}-\frac{\partial^{2}}{\partial \tilde{\tau}^{2}}\right)\langle s(t, \tilde{\tau})\rangle . \tag{14}
\end{align*}
$$

Mathematically, a specific position of this equation is connected with the fact that $\mathbb{C}^{2} \simeq \mathbb{R}^{4}$ in (5) and $\mathbb{C}^{4} \simeq \mathbb{R}^{8}$ in (6). We are going to discuss the equation (13) in detail.
3.2. Setting of a linearization procedure. As in [4], in relation with (13) we concentrate on the Fokker-Planck type [26] equation

$$
\begin{align*}
& \frac{\partial}{\partial t} s(t)=-\Gamma s_{*}(t)+\Lambda\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}+\frac{\partial^{2}}{\partial z^{2}}+\frac{\partial^{2}}{\partial \xi^{2}}+\frac{\partial^{2}}{\partial \eta^{2}}-\frac{\partial^{2}}{\partial \tilde{\tau}^{2}}\right) s(t) \\
&(x, y, z, \xi, \eta) \in \mathbb{R}^{4}, t \in \mathbb{R}^{+} \tag{15}
\end{align*}
$$

where $s_{*}(t)$ is an arbitrary admissible function; in particular we may take [3]:

$$
\begin{gather*}
s_{*}=s_{0} \equiv-\int_{0}^{t} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \\
\times \exp \left[\frac{\left(x-x^{\prime}\right)^{2}+\left(y-y^{\prime}\right)^{2}+\left(z-z^{\prime}\right)^{2}+\left(\xi-\xi^{\prime}\right)^{2}+\left(\eta-\eta^{\prime}\right)^{2}-\left(\tilde{\tau}-\tilde{\tau}^{\prime}\right)^{2}}{4 \Lambda\left(x^{\prime}, y^{\prime}, z^{\prime}, \xi^{\prime}, \eta^{\prime}, \tilde{\tau}^{\prime}, t^{\prime}\right)\left(t-t^{\prime}\right)}\right] \\
\times \frac{\left(\Gamma s_{0}\right)\left(x-x^{\prime}, y-y^{\prime}, z-z^{\prime}, \xi-\xi^{\prime}, \eta-\eta^{\prime}, \tilde{\tau}-\tilde{\tau}^{\prime}, t-t^{\prime}\right)}{2 \sqrt{\Lambda\left(x^{\prime}, y^{\prime}, z^{\prime}, \xi^{\prime}, \eta^{\prime}, \tilde{\tau}^{\prime}, t^{\prime}\right)\left(t-t^{\prime}\right)}} \\
\times d x^{\prime} d y^{\prime} d z^{\prime} d \xi^{\prime} d \eta^{\prime} d \tilde{\tau}^{\prime} d t^{\prime} . \tag{16}
\end{gather*}
$$

According to [23], [24] we need an 8-dimensional vector

$$
\begin{equation*}
\mathbf{s}=\left(s, s_{0}, s_{1}, \ldots, s_{6}\right) \in \mathbb{R}^{8} \simeq \mathbb{C}^{4} \tag{17}
\end{equation*}
$$

and two bases:

$$
\begin{equation*}
\left(\varepsilon, \varepsilon_{\alpha}\right)=\left(\varepsilon, \varepsilon_{0}, \varepsilon_{1}, \ldots, \varepsilon_{5}\right) \tag{18}
\end{equation*}
$$

say, for the space $S$ of variables $x, y, z, \xi, \eta, \tilde{\tau}, t$, and

$$
\begin{equation*}
\left(e, e_{j}\right)=\left(e, e_{0}, e_{1}, \ldots, e_{6}\right) \tag{19}
\end{equation*}
$$

for the space $V$ of solution (17). Hence, in our case, $\left(\varepsilon_{\alpha}\right)$ consists of complex $8 \times 8$-matrices. They have to satisfy the relations

$$
\varepsilon^{2}=-\varepsilon_{0}, \quad \varepsilon_{\alpha}^{2}=\varepsilon_{0}, \quad \alpha=1, \ldots, 4 ; \quad \varepsilon_{5}^{2}=0
$$

$$
\begin{equation*}
\varepsilon \varepsilon_{\alpha}+\varepsilon_{\alpha} \varepsilon=0, \quad \varepsilon_{\alpha} \varepsilon_{\beta}+\varepsilon_{\beta} \varepsilon_{\alpha}=0, \quad \alpha, \beta=1, \ldots, 5 \tag{20}
\end{equation*}
$$

The explicit formulae for (18) in terms of para-quaternions can be deduced from the corresponding formulae obtained for $\tau=1$ and 2 in [4] (after converting quaternions to para-quaternions) with the use of interaction procedure of [18], formulae (1) and (18), expressed already in terms of para-quaternions. The explicit formulae will be published in a subsequent paper. The algebra determined by the basis (18) satisfying the conditions (20) is known as the Clifford-Grassmann algebra $C l_{1,4}^{* 0}(\mathbb{C})$.

Then we find analogues of the familiar operators $\partial_{\bar{z}}$ and $\partial_{z}: \bar{\partial}$ and $\partial$ (say):

$$
\begin{equation*}
\bar{\partial} \mathbf{s}=P \mathbf{s}-\mathbf{v}, \quad \Lambda \partial(P \mathbf{s})=(\partial / \partial t) \mathbf{s} \quad \text { with } \Lambda \partial \mathbf{v}=-\Gamma \mathbf{s} . \tag{21}
\end{equation*}
$$

Here

$$
\begin{equation*}
\mathbf{v} \in V, \quad \Lambda \partial(P \mathbf{s})=\partial(Q \mathbf{s}) \tag{22}
\end{equation*}
$$

$Q$ being a polynomical of $\varepsilon, \varepsilon_{0}, \varepsilon_{1}, \ldots, \varepsilon_{4}$ :

$$
\begin{align*}
Q \mathbf{s}= & s_{1}^{1} \odot \varepsilon+s_{2}^{1} \odot \varepsilon_{0}+s_{3}^{1} \odot \varepsilon_{1}+\cdots+s_{6}^{1} \odot \varepsilon_{4}+s_{7}^{1} \odot \varepsilon \varepsilon_{0} \\
& +s_{1}^{2} \odot \varepsilon \varepsilon_{1}+\cdots+s_{4}^{2} \odot \varepsilon \varepsilon_{4}+s_{5}^{2} \odot \varepsilon_{0} \varepsilon_{1}+\cdots+s_{7}^{2} \odot \varepsilon_{0} \varepsilon_{3} \\
& +s_{1}^{3} \odot \varepsilon_{0} \varepsilon_{4}+s_{2}^{3} \odot \varepsilon_{1} \varepsilon_{2}+\ldots \\
& +s_{4}^{3} \odot \varepsilon_{1} \varepsilon_{4}+s_{5}^{3} \odot \varepsilon_{2} \varepsilon_{3}+s_{6}^{3} \odot \varepsilon_{2} \varepsilon_{4}+s_{7}^{3} \odot \varepsilon_{3} \varepsilon_{4}, \tag{23}
\end{align*}
$$

where

$$
\begin{equation*}
s_{j}^{k}, j=1, \ldots, 7 ; \quad k=1, \ldots, 4, \text { belong to } V \text { and are } \mathbb{C}^{4} \text {-valued, } \tag{24}
\end{equation*}
$$

while $\odot$ is the multiplication $\odot: V \otimes S \rightarrow V$ in the algebra $C l_{1,4}^{* 0}(\mathbb{C})$. Indeed, from (18) and (19) we infer that

$$
\begin{aligned}
\Lambda \partial \bar{\partial} \mathbf{s} & =\Lambda \partial(P \mathbf{s})-\Lambda \partial \mathbf{v}=\frac{\partial}{\partial t} s-\Gamma s \\
& =\Lambda\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}+\frac{\partial^{2}}{\partial z^{2}}+\frac{\partial^{2}}{\partial \xi^{2}}+\frac{\partial^{2}}{\partial \eta^{2}}-\frac{\partial^{2}}{\partial \tilde{\tau}^{2}}\right) \mathbf{s}
\end{aligned}
$$

so

$$
\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}+\frac{\partial^{2}}{\partial z^{2}}+\frac{\partial^{2}}{\partial \xi^{2}}+\frac{\partial^{2}}{\partial \eta^{2}}-\frac{\partial^{2}}{\partial \tilde{\tau}^{2}}\right) \mathbf{s}=\partial \bar{\partial} \mathbf{s}
$$

with $s$ being in $V$ and $\mathbb{C}^{4}$-valued. Hence by (18)-(20) we arrive at the formulae

$$
\mathbf{s}=s_{1}^{4} \odot \varepsilon+s_{2}^{4} \odot \varepsilon_{0}+s_{3}^{4} \odot \varepsilon_{1}+\cdots+s_{6}^{4} \odot \varepsilon_{4}+s_{7}^{4} \odot \varepsilon \varepsilon_{0}+s_{1}^{5} \odot \varepsilon \varepsilon_{1}+\ldots
$$

$$
\begin{align*}
& +s_{4}^{5} \odot \varepsilon \varepsilon_{4}+s_{5}^{5} \odot \varepsilon_{0} \varepsilon_{1}+\cdots+s_{7}^{5} \odot \varepsilon_{0} \varepsilon_{3}+s_{1}^{6} \odot \varepsilon_{0} \varepsilon_{4}+s_{2}^{6} \odot \varepsilon_{1} \varepsilon_{2}+\ldots \\
& \quad+s_{4}^{6} \odot \varepsilon_{1} \varepsilon_{4}+s_{5}^{6} \odot \varepsilon_{2} \varepsilon_{3}+s_{6}^{6} \odot \varepsilon_{2} \varepsilon_{4}+s_{7}^{6} \odot \varepsilon_{3} \varepsilon_{4}+(Q \mathbf{s}) \odot v \\
& =  \tag{25}\\
& s e+s_{0} e_{0}+s_{1} e_{1}+\cdots+s_{6} e_{6}
\end{align*}
$$

with

$$
\begin{equation*}
s, s_{0}, s_{1}, \ldots, s_{6}, \text { being in } V \text { and } \mathbb{C}^{4} \text {-valued. } \tag{26}
\end{equation*}
$$

3.3. The fundamental solution. In order to find $s$ effectively (in principle we do not need $s, s_{0}, s_{1}, \ldots, s_{6}$ ) we have to find the system of fundamental solutions of the equation (15) and to be able to compare on both sides of (25) the coordinates with respect to $e$. Here we have to remember that

$$
s_{j}^{k}, j=1, \ldots, 7 ; \quad ; k=1, \ldots, 6
$$

are linear combinations of $e, e_{0}, e_{1}, \ldots, e_{6}$, so we need to determine the multiplication scheme for $e \odot \varepsilon_{\alpha}, e_{0} \odot \varepsilon_{\alpha}, e_{j} \odot \varepsilon_{\alpha}$ in the algebra $C l_{1,4}^{* 0}$; the multiplication $\odot$ has to be compatible with the problem of solving the equation (15).

As far as the first question is concerned, we have

$$
\begin{align*}
\mathbf{s}= & c_{1}^{1} \mathbf{s}^{x}+c_{2}^{1} \mathbf{s}^{y}+c_{3}^{1} \mathbf{s}^{z}+c_{4}^{1} \mathbf{s}^{\xi}+c_{5}^{1} \mathbf{s}^{\eta}+c_{6}^{1} \mathbf{s}^{\tilde{\tau}}+c_{1}^{2} \mathbf{s}^{x y}+c_{2}^{2} \mathbf{s}^{x z}+c_{3}^{2} \mathbf{s}^{x \xi} \\
& +c_{4}^{2} \mathbf{s}^{x \eta}+c_{5}^{2} \mathbf{s}^{x \tilde{\tau}}+c_{6}^{2} \mathbf{s}^{y z}+c_{1}^{3} \mathbf{s}^{y \xi}+c_{2}^{3} \mathbf{s}^{y \eta}+c_{3}^{3} \mathbf{s}^{y \tilde{\tau}}+c_{4}^{3} \mathbf{s}^{z \xi}+c_{5}^{3} \mathbf{s}^{z \eta}+c_{6}^{3} \mathbf{s}^{z \tilde{\tau}} \\
& +c_{1}^{4} \mathbf{s}^{\xi \eta}+c_{2}^{4} \mathbf{s}^{\xi \tilde{\tau}}+c_{3}^{4} \mathbf{s}^{\eta \tilde{\tau}}+c_{4}^{4} \mathbf{s}^{x t}+c_{5}^{4} \mathbf{s}^{y t}+c_{6}^{4} \mathbf{s}^{z t}+c_{1}^{5} \mathbf{s}^{\xi t}+c_{2}^{5} \mathbf{s}^{\eta t}+c_{3}^{5} \mathbf{s}^{\tilde{\tau} t} \\
& +c_{4}^{5} \mathbf{s}^{x y t}+c_{5}^{5} \mathbf{s}^{x z t}+c_{6}^{5} \mathbf{s}^{x \xi t}+c_{1}^{6} \mathbf{s}^{x \eta t}+c_{2}^{6} \mathbf{s}^{x \tilde{\tau} t}+c_{3}^{6} \mathbf{s}^{y z t}+c_{4}^{6} \mathbf{s}^{y \xi t}+c_{5}^{6} \mathbf{s}^{y \eta t} \\
& +c_{6}^{6} \mathbf{s}^{y \tilde{\tau} t}+c_{1}^{7} \mathbf{s}^{z \xi t}+c_{2}^{7} \mathbf{s}^{z \eta t}+c_{3}^{7} \mathbf{s}^{z \tilde{\tau} t}+c_{4}^{7} \mathbf{s}^{\xi \eta t}+c_{5}^{7} \mathbf{s}^{\xi \tilde{\tau} t}+c_{6}^{7} \mathbf{s}^{\eta \tilde{\tau} t}, \tag{27}
\end{align*}
$$

where

$$
c_{k}^{j}, j=1, \ldots, 7 ; \quad k=1, \ldots, 6,
$$

are complex constants to be determined from the initial conditions

$$
\begin{align*}
& s_{\mathbf{R}=0}(0)=s_{0}, s(t) \rightarrow \infty \quad \text { as } \quad(\mathbf{R}, \tilde{\tau}, t) \rightarrow\left(\infty, \tilde{\tau}_{0}, t_{0}\right), \\
& s(t) \rightarrow 0 \text { as }(\mathbf{R}, \tilde{\tau}, t) \rightarrow\left(\mathbf{R}_{0}, \tilde{\tau}_{0}, t_{0}\right) \text { for some } \mathbf{R}_{0}, \tilde{\tau}_{0}, t_{0} \tag{28}
\end{align*}
$$

and the boundary conditions, and

$$
\begin{gathered}
\mathbf{s}^{x}, \mathbf{s}^{y}, \mathbf{s}^{z}, \mathbf{s}^{\xi}, \mathbf{s}^{\eta}, \mathbf{s}^{\tilde{\tau}}, \mathbf{s}^{x y}, \mathbf{s}^{x z}, \mathbf{s}^{x \xi}, \mathbf{s}^{x \eta}, \mathbf{s}^{x \tilde{\tau}}, \mathbf{s}^{y z}, \mathbf{s}^{y \xi}, \mathbf{s}^{y \eta}, \\
\mathbf{s}^{y \tilde{\tau}}, \mathbf{s}^{z \xi}, \mathbf{s}^{z \eta}, \mathbf{s}^{z \tilde{\tau}}, \mathbf{s}^{\xi \eta}, \mathbf{s}^{\xi \tilde{\tau}}, \mathbf{s}^{\eta \tilde{\tau}}, \mathbf{s}^{x t}, \mathbf{s}^{y t}, \mathbf{s}^{z t}, \mathbf{s}^{\xi t}, \mathbf{s}^{\eta t}, \mathbf{s}^{\tilde{\tau} t}, \mathbf{s}^{x y t} \\
\mathbf{s}^{x z t}, \mathbf{s}^{x \xi t}, \mathbf{s}^{x \eta t}, \mathbf{s}^{x \tilde{\tau} t}, \mathbf{s}^{y z t}, \mathbf{s}^{y \xi t}, \mathbf{s}^{y \eta t}, \mathbf{s}^{y \tilde{\tau} t}, \mathbf{s}^{z \xi t}, \mathbf{s}^{z \eta t}, \mathbf{s}^{z \tilde{\tau} t}, \mathbf{s}^{\xi \eta t}, \mathbf{s}^{\xi \tilde{\tau} t}, \mathbf{s}^{\eta \tilde{\tau} t},
\end{gathered}
$$

are fundamental solutions of the equation (15). Explicitly, we get

$$
\begin{align*}
& \mathbf{s}^{x}=\left(\partial s_{0}\right) \varepsilon, \quad \mathbf{s}^{x y}=\left(\partial s_{0}\right) \varepsilon \varepsilon_{0}, \mathbf{s}^{y \xi}=\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{2}, \\
& \mathbf{s}^{y}=\left(\partial s_{0}\right) \varepsilon_{0}, \quad \mathbf{s}^{x z}=\left(\partial s_{0}\right) \varepsilon \varepsilon_{1}, \mathbf{s}^{y \eta}=\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{3} \\
& \mathbf{s}^{z}=\left(\partial s_{0}\right) \varepsilon_{1}, \quad \mathbf{s}^{x \xi}=\left(\partial s_{0}\right) \varepsilon \varepsilon_{2}, \mathbf{s}^{y \tilde{\tau}}=\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{4}, \\
& \mathbf{s}^{\xi}=\left(\partial s_{0}\right) \varepsilon_{2}, \quad \mathbf{s}^{x \eta}=\left(\partial s_{0}\right) \varepsilon \varepsilon_{3}, \mathbf{s}^{z \xi}=\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{2}, \\
& \mathbf{s}^{\eta}=\left(\partial s_{0}\right) \varepsilon_{3}, \quad \mathbf{s}^{x \tilde{\tau}}=\left(\partial s_{0}\right) \varepsilon \varepsilon_{4}, \mathbf{s}^{z \eta}=\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{3}, \\
& \mathbf{s}^{\tilde{\tau}}=\left(\partial s_{0}\right) \varepsilon_{4}, \quad \mathbf{s}^{y z}=\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{1}, \mathbf{s}^{z \tilde{\tau}}=\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{4},  \tag{29}\\
& \mathbf{s}^{\xi \eta}=\left(\partial s_{0}\right) \varepsilon_{2} \varepsilon_{3}, \quad \mathbf{s}^{\xi t}=s_{0} \varepsilon_{2}+\left(\partial s_{0}\right) \varepsilon_{2} \varepsilon_{5}, \\
& \mathbf{s}^{\xi \tilde{\tau}}=\left(\partial s_{0}\right) \varepsilon_{2} \varepsilon_{4}, \quad \mathbf{s}^{\eta t}=s_{0} \varepsilon_{3}+\left(\partial s_{0}\right) \varepsilon_{3} \varepsilon_{5}, \\
& \mathbf{s}^{\eta \tilde{\tau}}=\left(\partial s_{0}\right) \varepsilon_{3} \varepsilon_{4}, \quad \mathbf{s}^{\tilde{\tau} t}=s_{0} \varepsilon_{4}+\left(\partial s_{0}\right) \varepsilon_{4} \varepsilon_{5} \text {, } \\
& \mathbf{s}^{x t}=s_{0} \varepsilon+\left(\partial s_{0}\right) \varepsilon \varepsilon_{5}, \quad \mathbf{s}^{x y t}=-s_{0} \varepsilon \varepsilon_{0}+\left(\partial s_{0}\right) \varepsilon \varepsilon_{0} \varepsilon_{5}, \\
& \mathbf{s}^{y t}=s_{0} \varepsilon_{0}+\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{5}, \quad \mathbf{s}^{x z t}=-s_{0} \varepsilon \varepsilon_{1}+\left(\partial s_{0}\right) \varepsilon \varepsilon_{1} \varepsilon_{5}, \\
& \mathbf{s}^{z t}=s_{0} \varepsilon_{1}+\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{5}, \quad \mathbf{s}^{x \xi t}=-s_{0} \varepsilon \varepsilon_{2}+\left(\partial s_{0}\right) \varepsilon \varepsilon_{2} \varepsilon_{5},  \tag{30}\\
& \mathbf{s}^{x \eta t}=-s_{0} \varepsilon \varepsilon_{3}+\left(\partial s_{0}\right) \varepsilon \varepsilon_{3} \varepsilon_{5}, \quad \mathbf{s}^{z \xi t}=-s_{0} \varepsilon_{1} \varepsilon_{2}+\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{2} \varepsilon_{5}, \\
& \mathbf{s}^{x \tilde{\tau} t}=-s_{0} \varepsilon \varepsilon_{4}+\left(\partial s_{0}\right) \varepsilon \varepsilon_{4} \varepsilon_{5}, \quad \mathbf{s}^{z \eta t}=-s_{0} \varepsilon_{1} \varepsilon_{3}+\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{3} \varepsilon_{5}, \\
& \mathbf{s}^{y z t}=-s_{0} \varepsilon_{0} \varepsilon_{1}+\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{1} \varepsilon_{5}, \quad \mathbf{s}^{z \tilde{\tau} t}=-s_{0} \varepsilon_{1} \varepsilon_{4}+\left(\partial s_{0}\right) \varepsilon_{1} \varepsilon_{4} \varepsilon_{5}, \\
& \mathbf{s}^{y \xi t}=-s_{0} \varepsilon_{0} \varepsilon_{2}+\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{2} \varepsilon_{5}, \quad \mathbf{s}^{\xi \eta t}=-s_{0} \varepsilon_{2} \varepsilon_{3}+\left(\partial s_{0}\right) \varepsilon_{2} \varepsilon_{3} \varepsilon_{5}, \\
& \mathbf{s}^{y \eta t}=-s_{0} \varepsilon_{0} \varepsilon_{3}+\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{3} \varepsilon_{5}, \quad \mathbf{s}^{\xi \tilde{\tau} t}=-s_{0} \varepsilon_{2} \varepsilon_{4}+\left(\partial s_{0}\right) \varepsilon_{2} \varepsilon_{4} \varepsilon_{5}, \\
& \mathbf{s}^{y \tilde{\tau} t}=-s_{0} \varepsilon_{0} \varepsilon_{4}+\left(\partial s_{0}\right) \varepsilon_{0} \varepsilon_{4} \varepsilon_{5}, \quad \mathbf{s}^{\eta \tilde{\tau} t}=-s_{0} \varepsilon_{3} \varepsilon_{4}+\left(\partial s_{0}\right) \varepsilon_{3} \varepsilon_{4} \varepsilon_{5}, \tag{31}
\end{align*}
$$

where $s_{0}$ is determined by (16).
As far as second question is concerned, we have the multiplication rules

$$
\begin{gather*}
e_{j} \odot \varepsilon_{\alpha}=\left(e, e_{j} \odot \varepsilon_{\alpha}\right) e+\sum_{k=0}^{6}\left(e_{k}, e_{j} \odot \varepsilon_{\alpha}\right) e_{k}, \quad e_{k}=\left(e, e_{k}\right) e+\sum_{j=0}^{6}\left(e_{j}, e_{k}\right) e_{j}, \\
{\left[\left(e^{j} e^{k}\right)\right]=\left[\left(e_{j}, e_{k}\right)\right]^{-1}, j, k=0, \ldots, 6 ; \quad \alpha=0, \ldots, 5} \tag{32}
\end{gather*}
$$

and analogous rules for $(e, e),\left(e, e_{j}\right)$ and $\left(e_{k}, e\right)$.
Here $\left[\left(e_{j}, e_{k}\right)\right]$ denotes the matrix of all elements $\left(e_{j}, e_{k}\right)$ including $(e, e)$, $\left(e_{j}, e\right)$ and $\left(e, e_{k}\right)$-the scalar product of $e j$ and $e_{k}$ etc., where we follow the convection (19).
3.4. Concluding the proof. Formulation of the result. Thanks to Sections 3.2 and 3.3 we have proved

Theorem 1. Let $s=s(t)$ be a solution of the Fokker-Planck type equation (15), where $\Gamma$ and $\Lambda$ are $C^{1}$-scalar functions of $\mathbf{R}=(x, y, z, \xi, \eta) \in \mathbb{R}^{5}, \tau \in \mathbb{R}$, and $t \in \mathbb{R}^{+}$. Consider the space $S$ of variables $x, y, z, \xi, \eta, \tilde{\tau}, t$ with a basis (18) of complex $8 \times 8$-matrices specified the relations (20) and the space $V$ of solutions (17) forming the algebra $C l_{1,4}^{* 0}(\mathbb{C})$, with a basis (19) of the linearized problem

$$
\begin{equation*}
\bar{\partial} \mathbf{s}=P \mathbf{s}-\mathbf{v}, \quad \Lambda \partial(P \mathbf{s})=(\partial / \partial t) \mathbf{s}, \quad \text { with } \quad \Lambda \partial \mathbf{v}=-\Gamma \mathbf{s} \tag{33}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathbf{v} \in V, \quad \Lambda \partial(P \mathbf{s})=\partial(Q \mathbf{s}) \tag{34}
\end{equation*}
$$

and $Q$ being a polynomial of $\varepsilon, \varepsilon_{0}, \varepsilon_{1}, \ldots, \varepsilon_{4}$, where $s$ is related to $\mathbf{s}$ by (17).
(a) Explicitly, a solution $\mathbf{s}$ of (33) can be expressed by (25) with coefficients as in (26) and (23), and the multiplication $\odot: V \times S \rightarrow V$ in the algebra $C l_{1,4}^{* 0}(\mathbb{C})$, which has to satisfy the rules (32). The polynomial $Q$ is given by (23) and the matrices (18) can be satisfied according to (20) in the terms of para-quaternions.
(b) Then the general solution of the system (33) is a linear combination (27) with complex coefficients of 42 fundamental solutions which, in the case of (16), are explicitly given by the formulae (29)-(31).

Differently speaking, we have an equivalent
Theorem 2. (i) Let $Q$ be a polynomial of $\varepsilon, \varepsilon_{0}, \varepsilon_{1}, \ldots, \varepsilon_{4}$, given by (23), where (18) are complex $8 \times 8$-matrices satisfying the relations (20) and forming a basis of the space $V$ of variables $x, y, z, \xi, \eta, \tilde{\tau}, t$ with $P$ as in (34), where $V$ is the space of solutions (17) forming the algebra $C l_{1,4}^{* 0}(\mathbb{C})$ with a basis (19), of the linearized problem (33), corresponding to the Fokker-Planck equation (15), $\Gamma$ and $\Lambda$ are $C^{1}$-scalar functions of $\mathbf{R}=(x, y, z, \xi, \eta) \in \mathbb{R}^{5}, \tau \in \mathbb{R}$, and $t \in \mathbb{R}^{+}$, and a solution $s=s(t)$ of (15) is related to $\mathbf{s}$ by (17). The multiplication $\odot: V \times S \rightarrow V$ in algebra $C l_{1,4}^{* 0}(\mathbb{C})$ has to satisfy the rules (32).
(ii) Then a solution $\mathbf{s}$ of (33) can be expressed as in (25) with coefficients as in (26) and (24), and the matrices (18) can be specified according to (20) in terms of para-quaternions. Moreover, the general solution of the system (33) is a linear combination (27) with complex coefficients of 42 fundamental solutions which, in the case of (16), are given explicitly by the formulae (29)-(31), where $s_{0}$ is determined by (16).

The results obtained have a clear physical significance [2], [5], [9], [11], [16], [17], [25], [26].

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