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# On completely integrable systems

By Y. VILLARROEL (Caracas)

The objective of this paper is to give a geometric formulation, using contact theory, for differential systems of order k and dimension n over a differentiable manifold. In the case k = 1 we obtain the classical Frobenius theorem.

Let  $(M, N, \pi)$  be a fibred manifold and  $J^k M$  the k-jets bundle of cross-sections of  $(M, N, \pi)$ . Two functions defined on a neighborhood of  $X \in J^k M$  are and identified, and the equivalence class is called a germ of functions at X. The set of all germs at X is denoted by  $\Omega_X J^k M$ . Given an open set  $\mathbf{U} \subset J^k M$ , let  $\Omega \mathbf{U} = \bigcap \{\Omega_X, X \in \mathbf{U}\}.$ 

A System of Partial Differential Equations (P.D.E.) of order k in  $(M, N, \pi)$  is defined as an open set **U** in  $J^k M$ , together with a locally, finitely generated, subsheaf of ideals  $\Phi$  of  $\Omega$ **U** [3]. The set **U** is called the domain of the S.P.D.

A cross-section f of  $(M, N, \pi)$  is said to be a solution of the equation  $\Phi = 0$  (or a solution of  $\Phi$ , for simplicity) if and only if, for any  $x \in \text{Dom } f$ , the jet  $j_x^k f$  is in the domain of  $\Phi$  and  $F(j_x^k f) = 0$ , for any F belonging to  $\Phi$ . If  $j_{x_0}^k f = X_0$  we say that f is a solution at  $X_0$ .

An integral jet X of a S.P.D.  $\Phi$ , with domain **U**, and order k is a k-jet  $X \in \mathbf{U}$  such that F(X) = 0, for all F belonging to  $\Phi x$ . The set of all the integral jets of  $\Phi$  is denoted by  $J\Phi$ . A cross-section f of  $(M, N, \pi)$  is then a solution of  $\Phi$  if and only if  $j_x^k f \in J\Phi$ , for all  $x \in \text{Dom } f$ .

A system  $\Phi$  of order k defined on a fibred manifold  $(M, N, \pi)$  is said to be completely integrable at  $X_0 \in J\Phi$  if there exists a solution f of  $\Phi$ at  $X_0$ .

Denote by  $C^{k,n}M$ , the contact bundle of order k of n-dimensional submanifolds in M, and by  $C_x^k S$  the contact element of order k at  $x \in S \subset M$  [2].

Given an imbedded submanifold  $W \subset C^{k,n}M$ , we will define an associated system of partial differential equations  $\Phi$  in  $(V, U, \pi)$ , where  $V \subset M$ is an open subset fibered over the open set  $U \subset \Re^n$ . We will give sufficient conditions on W for the complete integrability of  $\Phi$ . Moreover, if  $X_0 \in W$  and  $S \subset M$  is an *n*-submanifold such that  $C_x^k S \in W$ , for all  $x \in S$  and  $C_{x_0}^k S = X_0$  then, we can obtain a solution of  $\Phi$  using a local parametrization of S in a neigborhood of  $x_0$ .

This allows us to give a geometrical interpretation of a completely integrable system of order k, using contact theory.

For k = 1, the submanifold W defines a integrable distribution on M, yielding the classical Frobenius Theorem.

### 1. Jet theory and completely integrable systems

Let  $(M, N, \pi)$  be a fibred manifold, and f, g two cross-sections whose domains contain  $x_0 \in N$ . Let k be an integer,  $k \geq 0$ . We say that f and g are k-equivalent at  $x_0$  if the following condition is satisfied:

For any fibred chart (x, y), where the domain of (x) contains  $x_0$ , and for any partial derivative  $\partial^l$  in (x) of order  $l \leq k$  we have:  $\partial^l f^j(x_0) = \partial^l g^j(x_0)$ , where  $f^j = y^j \circ f$  (resp.  $g^j = y^j \circ g$ ) is the expression of f (resp. of g) in terms of (x, y).

If f is a cross-section whose domain contains  $x_0$ , the equivalence class containing f is called k-jet of f at  $x_0$  and will be denoted by  $j_{x_0}^k f$ . Denote by  $J_x^k(M, N, \pi)$  the set of all k-jets at x of cross-sections of  $(M, N, \pi)$ , and by  $J^k(M, N, \pi)$  the set of all k-jets of cross-sections of  $(M, N, \pi)$ . We shall write  $J_x^k M$  (resp.  $J^k M$ ) when there is no possibility of confusion.

If  $X = j_x^k f$ , we set  $\alpha(X) = x$  and  $\beta(x) = f(x)$ , thus  $\alpha$  (resp.  $\beta$ ) is a map of  $J^k M$  into N (resp. N), which is called the source map (resp. target map).

Denote by  $I_l = (i_1, \dots, i_l)$  an ordered *l*-uple of integers  $1, \dots, n$ , with  $n = \dim N$ .

Let  $(x_i, y^j)$  be a fibred chart defined on  $U \subset N$ . If  $X = j_{x_0}^l f$  is in  $\beta^{-1}(U)$  and  $f^j(x)$  is the expression of f, then  $(x, y, p_{I^l}^j(X)), 1 \leq l \leq k$ , will be called the chart of  $J^k M$  associated with (x, y), where

$$p_{I^l}^j(X) = \frac{\partial^l}{\partial x_{i_1} \cdots \partial x_{i_l}} f^j(x_0).$$

We consider the manifold structure on  $J^k M$  given by these charts. We have that  $(J^k M, N, \alpha)$  and  $(J^k M, N, \beta)$  are fibred manifolds. For  $l \leq k$ , consider the map

$$\pi_l^k : j_x^k f \in J^k M \longmapsto j_x^l f \in J^l M,$$

then  $(J^k M, J^l M, \pi_l^k)$  is also a fibred manifold [1].

Two functions defined on a neighborhood of  $w \in M$  are identified if they coincide in some neighborhood of w. The equivalence class is called germ of functions at w. The germ of a function  $\phi$  at w will be denoted by  $[\phi]_w$ . The set of germs of functions at w is a ring, and will be denoted by  $\Omega_w M$ .

We set  $\Omega M = \bigcup \{\Omega_w M; w \in M\}$ . If  $\Phi$  is a subset of  $\Omega M$ , we set  $\Phi_w = \Phi \cap \Omega_w M$ .

A function  $\phi$  defined on an open set  $U \subset M$  is said to be in  $\Phi$  (denoted  $\phi \in \Phi$ ) if  $[\phi]_w \in \Phi$ , for any  $w \in U$ .

The set  $\Phi$  is called a subsheaf of  $\Omega M$  if the following two conditions are satisfied for any  $w \in M$ :

1)  $\Phi$  is not empty,

2) For any  $a \in \Phi_w$  we can find a function  $\phi$  defined on a neighborhood of w such that  $a = [\phi]_w$  and  $\phi \in \Phi$ .

If U is an open subset of M and  $\Phi$  is a subsheaf,  $\bigcup \{\phi_x; w \in U\}$  is a subsheaf of  $\Omega U$  and is called the restriction of  $\Phi$  to U. A subsheaf  $\Phi$ of  $\Omega M$  is called a subsheaf of ideals when  $\Phi_w$  is an ideal of  $\Omega_w M$  for any  $w \in M$ .

Let  $F_1, \ldots, F_s$  be a finite set of functions defined on an open set  $U \in M$ , and  $\Phi_w, w \in U$ , the ideal of  $\Omega_w M$  generated by  $[F_1]_w, \ldots, [F_s]_w$ . Then  $\Phi = \bigcup \{\phi_w; w \in U\}$  is a subsheaf of ideals of  $\Omega U$  which is said to be generated by  $\Omega U$ .

A subsheaf of ideals is said to be locally finitely generated when its restiction to an open neighborhood of each point is finitely generated.

A system of partial differential equations (P.D.E.) of order k in  $(M, N, \pi)$  is an open set  $\mathbf{U} \in J^k M$ , together with a locally finitely generated subsheaf of ideals of  $\Omega \mathbf{U}$ . The set  $\mathbf{U}$  is called the domain of the P.D.E. .

An integral jet of a P.D.E.  $\Phi$ , with domain **U**, of order k, is a k-jet  $X \in \mathbf{U}$  such that F(X) = 0, for all  $F \in \Phi$ . We denote by  $J\Phi$  the set of integral jets of  $\Phi$ .

A a solution of  $\Phi$  is a cross-section f of  $(M, N, \pi)$ , defined over an open set  $U \subset \alpha(\mathbf{U})$  such that, for any  $x \in U$ , the jet  $j_x^k f \in \mathbf{U}$ . If  $X_0 \in \mathbf{U}$ and  $j_{x_0}^k f = X_0$ , with  $x_0 \in U$ , we say that f is a solution of  $\Phi$  at  $x_0$ .

Let  $F_1, \ldots, F_s$  be a finite set of functions on an open set  $\mathbf{U} \in J^k M$ . Then the subsheaf  $\Phi$  of ideals of  $\Omega \mathbf{U}$  generated by  $F_1, \ldots, F_s$  is a S.P.D. of order k.

Assume that **U** is contained in the domain of the chart  $(x, y, p_{I^l}^j)$  associated with a fibred chart (x, y). Then a cross-section  $f = (x, f^j)$  is a solution of the equation  $\Phi = 0$  if  $f^j(x)$  is a solution of the system of partial differential equations

$$F_r(j_x^k f) = 0, \quad 1 \le r \le s.$$

The system  $\Phi$  is *complete* at  $X \in \mathbf{U}$  if for any function F, defined on an open set  $\mathbf{V} \subset U$ , which vanishes on  $J\Phi \cap \mathbf{V}$ , the restriction of F to an open neighborhood of X belongs to  $\Phi$ .

Let F be a function defined on an open set  $\mathbf{U} \subset J^k M$  and  $\theta$  a vector field on  $\alpha(\mathbf{U}) \subset N$ . The formal derivative of F with respect to  $\theta$ , denoted by  $\partial_{\theta}^{\#} F$ , is a function on  $(\pi_k^{k+1})^{-1}(\mathbf{U})$  defined as follows:

$$\partial_{\theta}^{\#}F: j_{x_0}^{k+1}f \longmapsto \theta_{x_0}(F \circ j^k f),$$

where  $j^k f : \text{Dom } f \longrightarrow J^k M$  is defined by  $x \longmapsto j_x^k f$ . This definition is independent of the choice of representative f [3].

Let  $\Phi$  be a P.D.E. with domain  $\mathbf{U} \subset J^k M$ . For any  $X^{k+1} \in (\pi_k^{k+1})^{-1}(\mathbf{U}) = \mathbf{U}'$ , let  $(p\Phi)_{X^{k+1}}$  be the ideal of germs at  $X^{k+1}$  generated by

$$\{F \circ \pi_k^{k+1}, \ \partial_{\theta}^{\#} F; \quad F \in \Phi_{X^k}, \ \theta \in \chi(\alpha(\mathbf{U}))\}.$$

The subsheaf of ideals of  $\Omega \mathbf{U}'$  generated by  $(p\Phi)_{X^{K+1}}$ , with  $X^{k+1} \in \mathbf{U}'$ , is called the prolongation of  $\Phi$  and denoted by  $P\Phi$ .

Given  $X^k \in J^k M$  denote by  $Q_{X^k} J^k M$  (or  $Q_{X^k}$  when there is no possibility of confusion) the set,

$$Q_{X^k} = \text{kernel } \{ d\pi_{k-1}^k : T_{X^k} J^k M \longrightarrow T_{X^{K-1}} J^{k-1} M \}$$

and  $C_{X^k}\Phi$  the vector subspace defined by

$$C_{X^k}\Phi = \{ v \in T_{X^k}Q_{X^k} : v(F) = 0; \ F \in \Phi_{X^k} \}.$$

This subspace is called the Symbol of  $\Phi$  at  $X^k$ .

A system of partial differential equations  $\Phi$  is said to be completely integrable at  $X \in J\Phi$  if the following conditions are satisfied:

1)  $C_X \Phi = 0$ ,

- 2) The image of  $J(P\Phi)$  by  $\pi_k^{k+1}$  is a neighborhood of X in  $J\Phi$ ,
- 3)  $\Phi$  is complete at X.

**Theorem 1.** Assume that a P.D.E.  $\Phi$  of order k is completely integrable at  $X \in J\Phi$ . Then there is a solution f of  $\Phi$  at X; moreover, the germ of f at  $\alpha(X)$  is uniquely determined.

Proof. (see [3]).

A system of partial differential equations  $\Phi$ , with domain **U**, is *regular* at  $X \in \Phi$  if:

i)  $J\Phi$  is a submanifold on a neighborhood of X,

ii) there exist functions  $\{F_1, \dots, F_s, F_i \in \Phi\}$ , where  $s + \dim J\Phi = \dim \mathbf{U}$ , such that,  $\{dF_1, \dots, dF_s\}$  are linearly independent at X (as elements in  $T_X^*\mathbf{U}$ ).

**Proposition 1.** Let  $\Phi$  be a regular S.P.D. defined on an open set  $\mathbf{U} \subset J^k M$ . Suppose that  $J\Phi$  is a regular submanifold in  $J^k M$ , fibered on  $U \subset N$  by  $\alpha$ , then

$$J(P\Phi) = J^{k+1}M \cap J^1(J\Phi, U, \alpha).$$

PROOF. Let  $X \in J(P\Phi)$  be an integral jet of the prolongation of  $\Phi$ , defined by  $X = j_u^{k+1} f$  and

$$H_X = T_u(j^k f)(T_u U).$$

It is clear that if  $Y \in J(P\Phi)$  then,

$$X = Y \Longleftrightarrow H_X = H_Y,$$

then X can be identified with the subspace  $H_X$ . Moreover,  $X \in J(P\Phi)$  if and only if  $H_X \subset T_{\pi_{\iota}^{k+1}(X)}J\Phi$ , indeed:

$$\begin{aligned} X \in J(P\Phi) \Leftrightarrow F(X) &= 0, \text{ and } \partial_{x_i}^{\#} (F \circ J^k f)|_X = 0, \quad F \in \Phi \\ \Leftrightarrow \frac{\partial}{\partial x_i}\Big|_u (F \circ j^k f) &= 0 \quad \& \quad F(X) = 0, \quad F \in \Phi \\ \Leftrightarrow T_u(j^k f) \left(\frac{\partial}{\partial x_i}(F)\right) &= 0 \quad \& \quad F(X) = 0 \\ \Leftrightarrow T_u(j^k f) \left(\frac{\partial}{\partial x_i}\right) \in T_X(J\Phi). \end{aligned}$$

On the other hand, a (k+1)-jet  $X \in P\Phi$  if and only if there exists a section  $\sigma: U \longrightarrow J\Phi$  such that  $X = j^1_{\alpha(X)}\sigma$ . This is clear because, as we

have shown,  $H_X \in T_{\pi_k^{k+1}(X)} J\Phi$ . In consequence, we have:

$$\begin{split} X \in J(P\Phi) \Leftrightarrow X = j_u^{k+1} f, \quad f: U \longrightarrow V \subset M \quad \text{section} \\ \& \quad X = j_u^1 \sigma, \quad \sigma: U \longrightarrow J\Phi \quad \text{section} \\ \Leftrightarrow X \in J^{k+1} M \cap J^1(J\Phi, U, \alpha). \quad \Box \end{split}$$

## 2. Contact manifolds and jet theory

Let M be a smooth (n+m)-dimensional manifold, k an integer,  $k \ge 0$ , and  $\tilde{J}_0^k(\mathfrak{R}^n, M)$  be the k-jets at 0 of maximal rank maps from  $\mathfrak{R}^n$  into M.

Given  $X_1, X_2 \in \tilde{J}_0^k(\mathfrak{R}^n, M)$  with  $\beta(X_1) = \beta(X_2) = x \in M$ . We say that  $X_1$  and  $X_2$  are equivalent at  $x \in M$  if there exist  $Y \in \tilde{J}_0^k(\mathfrak{R}^n, \mathfrak{R}^n)$ such that  $X_2 = X_1 \circ Y$ .

A class of this equivalence relation is called the contact element of order k and dimension n at x, denoted by  $[j_x^k f]$ . Let  $C_x^{k,n}M$  denote the set of all contact elements of order k at x, and  $C^{k,n}M$  the set of all kcontact elements of dimension n on M.

Let  $S \subset M$  be an imbedded *n*-dimensional submanifold and f, g, two local parametrizations of S at  $x \in M$  over a neighborhood  $V \subset M$ , with f(0) = g(0) = x, then

$$g^{-1}|_{V\cap S}: V\cap S \longrightarrow \mathfrak{R}^n$$

is a local diffeomorphism and

$$h = g^{-1} \circ f : A \subset \mathfrak{R}^n \longrightarrow B \subset \mathfrak{R}^n$$

is a local diffeomorphism such that  $j_0^k f = j_0^k g \circ j_0^k h$ , thus  $[j_0^k f] = [j_0^k g]$ .

The equivalence class  $[j_0^k f]$  is called the contact element of order k of S at  $x \in S$  and denoted  $C_x^k S$ .

Two imbedded submanifolds  $S_1$ ,  $S_2$  have contact of order k at  $x \in S_1 \cap S_2$  if there exist local parametrizations given by imbeddings

$$f_1, f_2: U \subset \mathfrak{R}^n \longrightarrow M$$

and a local coordinate system  $(V, y^j)$ ,  $1 \leq j \leq m$ , about  $x \in M$  such that  $f_1(0) = f_2(0) = x$  and the partial derivatives at 0 of  $y^j \circ f_1$  and  $y^j \circ f_2$  are equal up to order k.

Remarks.

1. Cleary  $C_x^1 S_1 = C_x^1 S_2$  if and only if  $T_x S_1 = T_x S_2$ .

2. Given a map  $f : U \subset \mathfrak{R}^n \longrightarrow M$  of maximal rank defined on a neighborhood  $U \subset \mathfrak{R}^n$ , with  $f(u) = x \in M$ , and  $\tau_u$  the traslation in  $\mathfrak{R}^n$ such that  $\tau_u(0) = u$ . Then,

$$j_0^k(f \circ \tau_u) \in \tilde{J}_0^k(\mathfrak{R}^n, M) \quad \& \quad [j_0^k(f \circ \tau_u)] \in C_x^{k,n} M.$$

Let  $X \in C^{k,n}M$  and  $f: U_f = \text{Dom } f \longrightarrow V \subset M$  such that  $[j_0^k f] = X$ .

Consider a local coordinate system  $(V, \varphi = (x^i, y^j)), 1 \leq i \leq n,$  $1 \leq j \leq m$ , such that:

 $x^i \circ f = \xi$ , the canonical coordinates in  $\mathfrak{R}^n$ .

Denote by  $\pi: \mathfrak{R}^{n+m} \longrightarrow \mathfrak{R}^n$  the canonical projection.

Then  $(V, U_f, \rho)$ , with  $\rho = \pi \circ \varphi$ , is a fibred manifold, said to be associated to X, and f is a cross-section.

Define a neighborhood  $\mathbf{V}$  of X as:

$$\mathbf{V} = \{ Y = C_u^k h(U) \in C^{k,n} V : h : U \longrightarrow V \text{ section}, \ u \in U \}$$

Let

$$\Psi: J^k(V, U, \rho) \longrightarrow \mathbf{V}$$

given by

$$\Psi(j_u^k f) = [j_0^k (f \circ \tau_u)],$$

this map is a bijection and will be denoted by  $\Psi$ , when there is no possibility of confusion.

A coordinate neighborhood at  $X = [j_0^k f]$  is given by:

$$(\Psi^{-1}(\mathbf{U}), \eta \circ \Psi^{-1}),$$

where  $(\mathbf{U}, \eta)$  is a coordinate neighborhood at  $j_0^k f \in J^k V$ . Consider the manifold structure in  $C^{k,n}M$  given by all coordinate neighborhoods defined above.

With this differential structure the natural projections,

$$\rho_0^k: C_x^k S \in C^{k,n} M \longmapsto x \in M, \quad \& \quad \rho_l^k: C_x^k S \longmapsto C_x^l S \in C^{l,n} M$$

are submersions, and the natural injections,

$$i^k: x \in S \longmapsto C^k_x S \in C^{k,n} M$$

and

$$i^{k+1}: C_x^{k+1}S \in C^{k+1,n}M \longmapsto C^1_{C_x^kS}(C^kS) \in C^{1,n}(C^{k,n}M)$$

are immersions.

Moreover we have the differential map

$$\Psi^{1,k}: J^1(J^kV, \alpha, U) \longrightarrow C^{1,n}(C^{k,n}V)$$

defined by

$$j_u^1(\sigma) \longmapsto C^1_{\sigma(u)}(\Psi(\sigma(U)).$$

### **3.** Differential systems of order k and dimension n

Definitions. By a differential system of order k and dimension n in M we mean an imbedded submanifold  $W \subset C^{k,n}M$ .

A solution of a differential system W at  $X \in W$ , is a *n*-dimensional imbedded submanifold  $S \subset M$ , with  $x = \rho_0^k(X) \in S$ , such that  $C^k S \subset W$ and  $C_x^k S = X$ .

*Example.* Let D be a differentiable distribution of n-planes defined on M. By Remark 1, we can identify a plane  $D_x \in D$  with a contact element  $D_x \in C^{1,n}M$ . Consider the map,

$$\vartheta: x \in M \longmapsto D_x \in C^{1,n}M.$$

If D is a differentiable distribution, then this map is an imbedding, and  $\vartheta(M)$  is a differential system of order 1 and dimension n in M.

Moreover, if D is an involutive distribution, then the differential system W has solution.

Definition [5]. The first prolongation of a submanifold  $W \subset C^{k,n}M$  is defined as:

$$PW = C^{1,n}W \cap C^{k+1,n}M,$$

where  $C^{k+1,n}M$  is identified with its image by  $i^{1,k}$  in  $C^{1,n}(C^{k,n}M)$ .

**Theorem.** Let  $W \subset C^{k,n}M$  be an imbedded submanifold such that the following conditions are satisfied:

1)  $\rho_{k-1}^k : W \longrightarrow C^{k-1,n}M$ , is a local immersion in a neighborhood of  $X \in W$ .

2)  $\rho_k^{k+1}: PW \longrightarrow W$  is a local submersion in a neighborhood of X,

then there exists a solution  $S \subset M$  of the differential system W passing through X. Moreover, if  $\tilde{S}$  is another submanifold of W passing through X, then there exists an open set  $A \subset M$ ,  $x = \rho_0^k(X) \in A$ , such that  $S \cap A = \tilde{S} \cap A$ .

PROOF. Let  $f : U \subset \mathfrak{R}^n \longrightarrow V \subset M$ ,  $x \in V$  be an immersion such that  $X = [j_0^k f]$ , and  $(V, U, \rho)$  the fibered manifold associated to X given above.

Let

$$\Psi: \mathbf{U} \subset J^k V \longrightarrow \mathbf{V} \subset C^{k,n} V$$

be the local diffeomorphism defined above.

Let  $F_1, \dots, F_s$  be differentiable functions defined in a neighborhood of X (also written **V**), such that:

$$\mathbf{V} \cap W = \{ X \in \mathbf{V} : F_1 = \dots = F_s = 0 \}.$$

Consider the system of partial differential equations  $\Phi$  of order k in  $(V, U, \rho)$  with domain  $\mathbf{U} = \Psi^{-1}(\mathbf{V})$ , generated by  $\{G_j = F_j \circ \Psi\}$ . Let  $Y = \Psi^{-1}(X)$ .

We will verify that  $\Phi$  satisfies the hypothesis of Theorem 1.

First, we observe that the integral jets  $J\Phi$  are given by  $\Psi^{-1}(W)$ . Indeed:

$$Y \in J\Phi \Leftrightarrow G_j(Y) = 0 \Leftrightarrow (F_j \circ \Phi)(Y) = 0 \Leftrightarrow \Phi(Y) \in W.$$

Now, by hypothesis  $\rho_{k-1}^k : (W \cap \mathbf{V}) \longrightarrow C^{k-1}V$  is an immersion, then

$$\pi_{k-1}^k:(J\Phi\cap {\bf U})\longrightarrow J^{k-1}V,$$

is also an immersion and the kernel of  $T_Y \pi_{k-1}^k$  vanishes, i.e.

$$T_Y \pi_{k-1}^k (T_Y Q_Y) = 0,$$

where  $Q_Y$  is defined above.

Then

$$T_Y \pi_{k-1}^k (T_Y J \Phi \cap T_Y Q_Y) = T_Y \pi_{k-1}^k (C_Y (\Phi)) = 0,$$

in consequence, the symbol  $C_Y(\Phi)$  of  $\Phi$  at  $Y \in J\Phi$  vanishes, and condition 1) of Theorem 1 is verified.

To verify that  $\pi_k^{k+1}: J(P\Phi) \longrightarrow J\Phi$  is a local submersion we consider the commutative diagram:

$$C^{1,k}V \xrightarrow{i^{1,k}} C^{1}(C^{k}V)$$

$$\Psi^{k+1} \uparrow \qquad \qquad \uparrow \Psi^{1,k}$$

$$J^{k+1}V \xrightarrow{\tilde{i}^{1,k}} J^{1}(J^{k}V)$$

where,

$$\tilde{i}^{1,k}: j_u^{k+1}g \in J^{k+1}V \longmapsto j_{j_u^kg}^1(j^kg) \in J^1(J^k, U, \alpha)$$

is the natural immersion [4].

Now using Proposition 1 we have,

$$Z \in J(P\Phi) \Leftrightarrow \Psi^{1,k}(Z) \in C^{1,n}W \cap C^{k+1,n}V = PW.$$

Hence  $\Psi^{1,k}(J\Phi) = PW$ . Now, by hypothesis:

$$\rho_k^{k+1}: PW \longrightarrow W$$

is a local submersion and

$$\Psi^k \circ \pi_k^{k+1} = \rho_k^{k+1} \circ \Psi^{k+1}.$$

Consequently:

$$\pi_k^{k+1}: P(J\Phi) \longrightarrow J\Phi,$$

is a local submersion, and condition 2) of Theorem 1 is satisfied.

Finally,  $\Phi$  is complete in Y because it is a sheaf of ideals generated by functions which vanish on the regular manifold  $(\Psi)^{-1}(W \cap \mathbf{V})$ .

It follows that  $\Phi$  is a completely integrable system of partial differential equations. Hence, there exists a solution  $\gamma$  of  $\Phi$  such that:

$$\gamma(0) = x, \quad j_0^k \gamma = X, \quad \& \quad j_u^k \gamma \in J\Phi, \quad u \in U_\gamma.$$

Let  $S = \gamma(U_{\gamma})$ , then clearly S verifies:

$$x \in S, \quad C_x^k S = X, \quad C^k S \subset W,$$

in consequence S is a solution of W at  $X \in W$ .

If  $\tilde{S}$  is another solution of W at X, then  $C_x^k S = C_x^k \tilde{S}$ .

In particular  $T_x S = T_x \tilde{S}$  and therefore there are a fibred manifold  $(V, U, \rho)$ , associated to X, and parametrizations  $\gamma$ ,  $\tilde{\gamma}$  of S and  $\tilde{S}$ , respectively, which are sections of the fibred manifold  $(V, U, \rho)$ .

Since S (resp.  $\tilde{S}$ ) is solution of W at X we have:  $j^k \gamma \subset J\Phi$  (resp.  $j^k \tilde{\gamma} \subset J\Phi$ ), and  $j_0^k \gamma = j_0^k \tilde{\gamma}$ . Then by uniqueness of germ solutions of completely integrable systems, there exits an open set  $B \subset \Re^n$  such that  $\gamma|_B = \tilde{\gamma}|_B$ .

Let  $A = \rho^{-1}(B)$ , then  $S \cap A = \tilde{S} \cap A$ .  $\Box$ 

Remark. For k=1 the submanifold W defines a Frobenius system. Indeed:

By condition 1)  $\rho_0^1 : \longrightarrow M$  is a local immersion in a neighborhood **V** of X.

Then it is possible to define a section  $\sigma = (\rho_0^1|_{W \cap \mathbf{V}})^{-1}$ . Also we can find coordinate neighborhoods  $(V, x_i, j^j)$  and  $(\mathbf{V}, x_i, y^j, p_i^j)$  of x and X respectively, such that the section  $\sigma$  can be expressed as,

$$\sigma(x_i, y^j) = (x_i, y^j, F_i^j(x_i, y^j)), \quad \text{with} \quad F_j^i : \mathbf{V} \longrightarrow \mathfrak{R}.$$

Then the manifold W defines a differentiable distribution D generated by:

$$L_i = \frac{\partial}{\partial x_i} + \sum F_i^j \frac{\partial}{\partial y^j} \; .$$

This distribution is involutive if and only if:

$$\frac{\partial F_i^j}{\partial x^k} + \sum_{l=1}^m \frac{\partial F_i^j}{\partial y^l} F_k^l = \frac{\partial F_k^j}{\partial x^i} + \sum_{l=1}^m \frac{\partial F_k^j}{\partial y^l} F_i^l \ .$$

By condition 2) we have:

$$\rho_1^2: C^{1,n}W \cap C^{2,n}M \longrightarrow W.$$

is a local submersion.

Then given  $Z \in W$ , there exits  $Z^2 \in C^{1,n}W \cap C^{2,n}M$  such that  $\rho_1^2(Z^2) = Z$ .

Since  $Z \in C^2 M$  we have:

$$p_{ik}^j(Z) = p_{ki}^j(Z)$$

Moreover,  $Z \in C^{1,n}W$  then we have:

$$Z^{2} = (x_{i}, y^{j}, F_{i}^{j}, \partial_{x_{k}}^{\#} F_{i}^{j}), \quad \partial_{x_{k}}^{\#} F_{i}^{j} = \frac{\partial F_{i}^{j}}{\partial x_{k}} + \sum_{l=1}^{m} \frac{\partial F_{i}^{j}}{\partial y^{l}} F_{k}^{l}$$

In consequence,

$$p_{ik}^{j}(Z^{2}) = \partial_{x_{k}}^{\#} F_{i}^{j}(x_{i}, y^{j}) = \partial_{x_{i}}^{\#} F_{k}^{j}(x_{i}, y^{j}) = p_{ki}^{j}(Z^{2}),$$

and the involutivity of the distribution D defined above is verified.

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Y. VILLARROEL DEPARTAMENTO DE MATEMÁTICAS FACULTAD DE CIENCIAS UNIVERSIDAD CENTRAL DE VENEZUELA CARACAS VENEZUELA

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