

Finsler connection transformations associated to a general Finsler metrical structure of Miron type (II)

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1. Introduction

Let M be an n -dimensional differentiable manifold of class C^∞ , (TM, π, M) its tangent bundle, (x^i, y^i) the local coordinates of a point $u \in TM$ in a local map, and let $\{\delta/\delta x^i, \partial/\partial y^i\}$ be an adapted basis, where $\delta/\delta x^i = \partial/\partial x^i - N_i^k \partial/\partial y^k$, N_i^k being the coefficients of a fixed non-linear connection N . Let $\mathcal{T}$ be the general group of Finsler connection transformations [6]: $t: F\Gamma(N) = (N_j^i, F_{jk}^i, C_{jk}^i) \rightarrow F\bar{\Gamma}(\bar{N}) = (\bar{N}_j^i, \bar{F}_{jk}^i, \bar{C}_{jk}^i)$ of the form:

$$(1.1) \quad \bar{N}_j^i(x, y) = N_j^i - A_j^i; \quad \bar{F}_{jk}^i = F_{jk}^i + C_{jk}^a A_a^i + B_{jk}^i; \quad \bar{C}_{jk}^i = C_{jk}^i + D_{jk}^i$$

where $A \in Z_1^1(M)$ and $B, D \in Z_2^1(M)$ are arbitrary Finsler tensors; and $\mathcal{T}_N = \{t \in \mathcal{T}, t = t(0, B, D)\}$ the subgroup of $\mathcal{T}$ formed by transformations $t: (N, F, C) \rightarrow (N, \bar{F}, \bar{C})$, which preserve the non-linear connection N . In a previous paper [12] we have introduced a classification method for the Finsler connection transformations $t \in \mathcal{T}_N$, using a metrical Finsler structure of Miron type $g = (g_{ij})$. In the present paper a generalization of this method for the case of the general group $\mathcal{T}$ of the Finsler connection transformations is given.

The notions and notations of M. MATSUMOTO [5] and R. MIRON [6] are used.

2. t_g and $t_{\text{non } g}$ transformations

Definition 2.1. A Finsler connection transformation $t \in \mathcal{T}$ is called a t_g transformation if and only if we have:

$$(2.1) \quad g_{aj||k} - \bar{N}_k^s g_{aj}||_s = g_{aj|k} - N_k^s g_{aj}|_s; \quad g_{aj}||_k = g_{aj}|_k$$

where $|, |$ and $||, ||$ denote the h - and v -covariant derivatives relative to (N, F, C) and $(\bar{N}, \bar{F}, \bar{C})$ respectively.

Definition 2.2. A Finsler connection transformation $t \in \mathcal{T}$ is called a $t_{\text{non } g}$ transformation if and only if at least one of the conditions (2.1) is not satisfied.

If $\bar{N} = N$, then $t \in \mathcal{T}_N$ and we obtain the Definitions 2.1 and 2.2 from [12].

We denote:

$$(2.2) \quad G_{jk}^i = \frac{1}{2} g^{ir} (g_{rj|k} + g_{rk|j} - g_{jk|r})$$

$$(2.3) \quad H_{jk}^i = \frac{1}{2} g^{ir} (g_{rj|k} + g_{rk|j} - g_{jk|r})$$

$$(2.4) \quad N_{jk}^i = \frac{1}{2} g^{ir} (g_{rj|a} N_k^a + g_{rk|a} N_j^a - g_{jk|a} N_r^a)$$

and analogously $\bar{G}_{jk}^i, \bar{H}_{jk}^i$ and $\bar{N}_{jk}^i$ for $F\bar{\Gamma}(\bar{N})$.

From (2.1), (2.2), (2.3) and (2.4) follow the invariants:

$$(2.5) \quad \bar{G}_{jk}^i + \bar{N}_{jk}^i = G_{jk}^i + N_{jk}^i; \quad \bar{H}_{jk}^i = H_{jk}^i.$$

Thus we have:

Theorem 2.1. If $t \in \mathcal{T}$ is a t_g -transformation then (2.5) are invariants of this transformation.

Example 2.1. Any $t(A, 0, 0) \in \mathcal{T}$ transformation i.e. (1.1) transformation with $B = D = 0$, is a t_g -transformation.

If we denote:

$$(2.6) \quad U_{jk}^{*i} = \frac{1}{2} (U_{jk}^i + g_{sj} g^{ir} U_{kr}^s + g_{sk} g^{ir} U_{jr}^s); \quad U_{jk}^i \in Z_2^1(M)$$

then, using the method from [12], from (1.1), (2.2) and (2.3) it follows the:

Theorem 2.2. A Finsler connection transformation $t \in \mathcal{T}$ is a t_g -transformation if and only if it is of the form:

$$(2.7) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; \\ \bar{F}_{jk}^i = F_{jk}^i + C_{ja}^i A_k^a + \bar{T}_{jk}^{*i} - \bar{T}_{jk}^i - \bar{\Theta}_{jk}^{*i} \\ \bar{C}_{jk}^i = C_{jk}^i + \bar{S}_{jk}^{*i} - \bar{S}_{jk}^i \end{cases}$$

where $\bar{T}^*$ is equal to $\bar{U}^*$ if $U = \bar{T}$; $\bar{T}$ is equal to $\bar{U}$ if $U = T$; $\bar{\Theta}$ is equal to $\bar{U}$ if $U_{jk}^i = C_{ja}^i A_k^a - C_{ka}^i A_j^a$; $\bar{S}$ is equal to $\bar{U}$ if $U = \bar{S}$ and $\bar{S}$ is equal to $\bar{U}$ if

$U = S$; $A_j^a \in Z_1^1(M)$ is an arbitrary Finsler tensor, T, S and $\bar{T}, \bar{S}$ are the h - and v -torsions of $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$ respectively.

Theorem 2.3. *The set of all Finsler connections $F\bar{\Gamma}(\bar{N})$ obtained from a fixed Finsler connection $F\Gamma(N)$ by a t_g -transformation is given by (2.7), where $A_k^a \in Z_1^1(M)$ is an arbitrary Finsler tensor; $\bar{T}, \bar{S}$ are arbitrary skewsymmetric tensors: $\bar{T}_{jk}^i = -\bar{T}_{kj}^i$; $\bar{S}_{jk}^i = -\bar{S}_{kj}^i$ and T, S are the h - and v -torsions of the fixed Finsler connection $F\Gamma(N)$.*

It follows that the transformations (2.7) are characterized by the invariants (2.1) or (2.5).

Corollary 2.1. *If $A_j^i = 0$, then $\bar{N} = N$ and we obtain the g transformations $t_g \in \mathcal{T}_N$ from [12].*

We denote:

$$(2.8) \quad A_{jk}^i = \frac{1}{2} g^{ia} (g_{aj}|_b A_k^b + g_{ak}|_b A_j^b - g_{jk}|_b A_a^b)$$

If $t \in \mathcal{T}$ is a $t_{\text{non } g}$ -transformation, then using the method from [12] it follows from (1.1) the:

Theorem 2.4. *A Finsler connection transformation $t \in \mathcal{T}$ is a $t_{\text{non } g}$ -transformation if and only if it is of the form:*

$$(2.9) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; \\ \bar{F}_{jk}^i = F_{jk}^i + C_{ja}^i A_k^a + \bar{T}_{jk}^{*i} - \bar{T}_{jk}^{*i} - \bar{\Theta}_{jk}^{*i} + G_{jk}^i - \bar{G}_{jk}^i + A_{jk}^i \\ \bar{C}_{jk}^i = C_{jk}^i + \bar{S}_{jk}^{*i} - \bar{S}_{jk}^{*i} + H_{jk}^i - \bar{H}_{jk}^i \end{cases}$$

and:

Theorem 2.5. *Let $F\Gamma(N)$ be a fixed Finsler connection with the h -torsion T and v -torsion S . Then any other Finsler connection $F\bar{\Gamma}(\bar{N})$ which does not possess the property (2.1) is given by (2.9), where $\bar{T}, \bar{S}$ are arbitrary skewsymmetric Finsler tensors; $\bar{G}, \bar{H}$ are arbitrary symmetric Finsler tensors: $\bar{G}_{jk}^i = \bar{G}_{kj}^i$; $\bar{H}_{jk}^i = \bar{H}_{kj}^i$; $A_j^i \in Z_1^1(M)$ is an arbitrary Finsler tensor and $\bar{H} \neq H$ or $G_{jk}^i - \bar{G}_{jk}^i + A_{jk}^i \neq 0$.*

If we fix $\bar{T}, \bar{S}, \bar{G}, \bar{H}$ and A_j^i , then we obtain a Finsler connection $F\bar{\Gamma}(\bar{N})$ which has the h -torsion $\bar{T}$, the v -torsion $\bar{S}$ and $\bar{G}, \bar{H}$ satisfies the relations:

$$(2.10) \quad \begin{aligned} \bar{G}_{jk}^i &= \frac{1}{2} g^{ir} (g_{rj}||_k + g_{rk}||_j - g_{jk}||_r); \\ \bar{H}_{jk}^i &= \frac{1}{2} g^{ir} (g_{rj}||_k + g_{rk}||_j - g_{jk}||_r) \end{aligned}$$

From (2.9) follow also special cases of $t_{\text{non-}g}$ -transformations.

We obtain the:

Theorem 2.6. (*Separation Theorem*). Any Finsler connection transformation $t \in \mathcal{T}$ is a t_g -transformation ($t \in \mathcal{T}_g$), or a $t_{\text{non-}g}$ -transformation ($t \in \mathcal{T}_{\text{non-}g}$) and we have: $\mathcal{T} = \mathcal{T}_g \cup \mathcal{T}_{\text{non-}g}$; $\mathcal{T}_g \cap \mathcal{T}_{\text{non-}g} = \emptyset$.

If in (2.9) we give up one, or both of the conditions $\bar{H} \neq H$ and $G_{jk}^i - \bar{G}_{jk}^i + A_{jk}^i = 0$, then we obtain the:

Theorem 2.7. (*General Theorem*). Any Finsler connection transformation $t \in \mathcal{T}$ is of the form (2.9).

This Theorem is important, since it is expressed solely in the terms of the two Finsler connections $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$ and thus we have the direct interpretation of the terms $\bar{T}, T; \bar{S}, S; \bar{G}, G; A$, for every definiteness of the connections. Consequently the invariants of these transformations can be studied elegantly in the special cases.

Corollary 2.3. Any Finsler connection transformation $t \in \mathcal{T}_N$ is of the form:

$$(2.11) \quad \begin{aligned} \bar{N}_j^i &= N_j^i; \quad \bar{F}_{jk}^i = F_{jk}^i + \bar{T}_{jk}^i - \bar{T}_{jk}^i + G_{jk}^i - \bar{G}_{jk}^i; \\ \bar{C}_{jk}^i &= C_{jk}^i + \bar{S}_{jk}^i - \bar{S}_{jk}^i + H_{jk}^i - \bar{H}_{jk}^i \end{aligned}$$

In this way the result of [12] is obtained.

3. Special classes of $t \in \mathcal{T}$ transformations

In the theory of linear connections the Schouten tensor play a prominent part. In the theory of Finsler connections we can define two Finsler-Schouten tensors:

$$(3.1) \quad I_{jk}^i = T_{jk}^i - \frac{1}{n-1}(\delta_j^i T_k - \delta_k^i T_j); \quad \bar{I}_{jk}^i = S_{jk}^i - \frac{1}{n-1}(\delta_j^i S_k - \delta_k^i S_j)$$

where $T_k = T_{ik}^i$, $S_k = S_{ik}^i$ and analogously two tensors $\bar{I}_1$ and $\bar{I}_2$ for $F\bar{\Gamma}$. Since we have:

$$(3.2) \quad \bar{T}_{jk}^i = \bar{T}_{jk}^i = \alpha_j \delta_k^i - g_{jk} \alpha^i; \quad \bar{S}_{jk}^i = \bar{S}_{jk}^i = \beta_j \delta_k^i - g_{jk} \beta^i$$

where $\alpha_j = \frac{1}{n-1}(T_j - \bar{T}_j)$; $\beta_j = \frac{1}{n-1}(S_j - \bar{S}_j)$, in case of $\bar{I}_1 = I_1$, $\bar{I}_2 = I_2$ we arrive to the following theorems:

Theorem 3.1. Any t_g -transformation, which admits the invariants $\bar{I}_1 = I_1$ and $\bar{I}_2 = I_2$ is of the form:

$$(3.3) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; & \bar{F}_{jk}^i = F_{jk}^i + C_{jr}^i A_k^r - \bar{\Theta}_{jk}^i + \alpha_j \delta_k^i - g_{jk} \alpha^i \\ \bar{C}_{jk}^i = C_{jk}^i + \beta_j \delta_k^i - g_{jk} \beta^i \end{cases}$$

Theorem 3.2. Any $t_{\text{non } g}$ -transformation, which admits the invariants $\bar{I}_1 = I_1$ and $\bar{I}_2 = I_2$ is of the form:

$$(3.4) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; \\ \bar{F}_{jk}^i = F_{jk}^i + C_{jr}^i A_k^r - \bar{\Theta}_{jk}^i + G_{jk}^i - \bar{G}_{jk}^i + A_{jk}^i + \alpha_j \delta_k^i - g_{jk} \alpha^i \\ \bar{C}_{jk}^i = C_{jk}^i + H_{jk}^i - \bar{H}_{jk}^i + \beta_j \delta_k^i - g_{jk} \beta^i \end{cases}$$

If $A_j^i = 0$, then $\bar{N} = N$ and we obtain the corresponding theorems from [12].

Particularly we obtain:

Theorem 3.3. Any t_g -transformation of semisymmetric ($I_1 = 0$, $I_2 = 0$) Finsler connections is of the form (3.3).

Theorem 3.4. Any $t_{\text{non } g}$ -transformation of semisymmetric Finsler connections is of the form (3.4).

If $FT(N)$ is a metrical Finsler connection, then $g_{ij|k} = 0$, $g_{ij}|_k = 0$ and it follows:

Theorem 3.5. Any transformation $t \in \mathcal{T}$ of metrical Finsler connections is a t_g -transformation.

Theorem 3.6. Any transformation $t \in \mathcal{T}$ which transforms a non-metrical Finsler connection $FT(N)$ in a metrical Finsler connection $F\bar{\Gamma}(\bar{N})$ is a $t_{\text{non } g}$ -transformation of the form:

$$(3.5) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; \\ \bar{F}_{jk}^i = F_{jk}^i + C_{jr}^i A_k^r + \bar{T}_{jk}^i - T_{jk}^i - \bar{\Theta}_{jk}^i + G_{jk}^i + A_{jk}^i \\ \bar{C}_{jk}^i = C_{jk}^i + \bar{S}_{jk}^i - S_{jk}^i + H_{jk}^i \end{cases}$$

This transformation solves the metrization problem of KAWAGUCHI. From the Theorems 3.1 and 3.5 follow the results of [9], [10].

Obviously any other conformal transformation compatible with a complex structure is obtained from (2.7) or (2.9) by particularization.

In [6], [7], [8] R. MIRON establishes the following metrizations:

Theorem. If $F\Gamma(N) = (N, F, C)$ is a fixed non-metrical Finsler connection, then any other metrical Finsler connection is given by:

$$(3.6) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; \\ \bar{F}_{jk}^i = F_{jk}^i + C_{jr}^i A_k^r + \frac{1}{2} g^{ir} (g_{rj|k} + g_{kj|a} A_k^a) + \Omega_{sj}^{ir} X_{rk}^s \\ \bar{C}_{jk}^i = C_{jk}^i + \frac{1}{2} g^{ir} g_{rj|k} + \Omega_{sj}^{ir} Y_{rk}^s \end{cases}$$

where $X, Y \in Z_2^1(M)$ are arbitrary Finsler tensor fields and $\Omega_{sj}^{ir} = \frac{1}{2}(\delta_s^i \delta_j^r - g_{sj} g^{ir})$ is the Obata operator $F\Gamma(N)$.

The transformations (3.6) are very important, since for any definiteness of $X, Y \in Z_1^1(M)$ a class of metrical Finsler connections $F\bar{\Gamma}(\bar{N})$ obtained from a non-metrical Finsler connection $F\Gamma(N)$ follows. It is an elegant generalization of the Kawaguchi metrizations method. By definiteness of $A_j^i \in Z_1^1(M)$ we obtain actually the metrical connection $F\bar{\Gamma}(\bar{N})$.

We shall solve now the inverse problem: Let $F\Gamma(N)$ be a fixed non-metrical Finsler connection and $F\bar{\Gamma}(\bar{N})$ an another given metrical Finsler connection. Which relations hold between $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$? What form has the transformation $t : F\Gamma(N) \rightarrow F\bar{\Gamma}(\bar{N})$?

Between $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$ obviously exist the relations (3.6), but in what extent are X and Y arbitrary? This is the problem, which has to be solved. From (3.6) it follows:

$$(3.7) \quad \begin{aligned} \bar{T}_{jk}^i = & T_{jk}^i + C_{jr}^i A_k^r - C_{kr}^i A_j^r + \frac{1}{2} g^{ir} (g_{rj|k} - g_{rk|j}) + \\ & + \frac{1}{2} g^{ir} (g_{rj|a} A_k^a - g_{rk|a} A_j^a) + \Omega_{sj}^{ir} X_{rk}^s - \Omega_{sk}^{ir} X_{rj}^s \end{aligned}$$

$$(3.8) \quad \bar{S}_{jk}^i = S_{jk}^i + \frac{1}{2} g^{ir} (g_{rj|k} - g_{rk|j}) + \Omega_{sj}^{ir} Y_{rk}^s - \Omega_{sk}^{ir} Y_{rj}^s$$

Consequently we obtain a system of tensor equations of the form:

$$(3.9) \quad \Omega_{sj}^{ir} X_{rk}^s - \Omega_{sk}^{ir} X_{rj}^s = \sigma_{jk}^i$$

$$(3.10) \quad \Omega_{sj}^{ir} Y_{rk}^s - \Omega_{sk}^{ir} Y_{rj}^s = \sigma_{jk}^i$$

where:

$$(3.11) \quad \begin{aligned} \sigma_{jk}^i = & (\bar{T}_{jk}^i - T_{jk}^i) - (C_{jr}^i A_k^r - C_{kr}^i A_j^r) - \\ & - \frac{1}{2} g^{ir} (g_{rj|k} - g_{rk|j}) - \frac{1}{2} g^{ir} (g_{rj|a} A_k^a - g_{rk|a} A_j^a) \end{aligned}$$

$$(3.12) \quad \sigma_{jk}^i = (\bar{S}_{jk}^i - S_{jk}^i) - \frac{1}{2}g^{ir}(g_{rj}|_k - g_{rk}|_j)$$

The general solution of a systems of the form (3.9)–(3.10) is given in [13] using the theory of fixed points. Here we give a direct solution by comparison of (3.6) and (3.5). It follows that a general solution is of the form:

$$(3.13) \quad \begin{aligned} \Omega_{sj}^{ir} X_{rk}^s &= \bar{T}_{jk}^i - T_{jk}^i - \bar{\Theta}_{jk}^i + \frac{1}{2}g^{ir}(g_{rk}|_j - g_{jk}|_r) + \\ &+ \frac{1}{2}g^{ir}(g_{rk}|_a A_j^a - g_{jk}|_a A_r^a) \end{aligned}$$

$$(3.14) \quad \Omega_{sj}^{ir} Y_{rk}^s = \bar{S}_{jk}^i - S_{jk}^i + \frac{1}{2}g^{ir}(g_{rk}|_j - g_{jk}|_r)$$

Denoting the right-hand member of (3.13) and (3.14) by B_{jk}^i and D_{jk}^i respectively, we have:

$$(3.15) \quad \bar{\Omega}_{sj}^{ir} B_{rk}^s = 0; \quad \bar{\Omega}_{sj}^{ir} D_{rk}^s = 0$$

where $\bar{\Omega}_{sj}^{ir} = \frac{1}{2}(\delta_s^i \delta_j^r + g^{ir} g_{sj})$ is the Obata operator.

From (3.15) it follows the compatibility of the system (3.13)–(3.14) and it has the solution:

$$(3.16) \quad X_{jk}^i = B_{jk}^i + \bar{\Omega}_{rj}^{is} U_{sk}^r$$

$$(3.17) \quad Y_{jk}^i = D_{jk}^i + \bar{\Omega}_{rj}^{is} V_{sk}^r$$

where $U, V \in Z_2^1(M)$ are arbitrary and B_{jk}^i, D_{jk}^i are given by the right-hand members of (3.13) and (3.14) respectively.

Consequently we have the:

Theorem 3.7. *Between a non-metrical and a metrical Finsler connections $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$, there exists the relation (3.6), where X, Y are arbitrary up to a transformation of form (3.16)–(3.17).*

Consequently X, Y are not completely arbitrary. They must be chosen of the form (3.16)–(3.17) in order to satisfy the equations (3.6).

In case when $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$ are both metrical we obtain from [1] and [8] the results:

$$(3.18) \quad \begin{cases} \bar{N}_j^i = N_j^i - A_j^i; & \bar{F}_{jk}^i = F_{jk}^i + C_{ja}^i A_k^a + \Omega_{sj}^{ir} X_{rk}^s \\ \bar{C}_{jk}^i = C_{jk}^i + \Omega_{sj}^{ir} Y_{rk}^s \end{cases}$$

From (3.16) and (3.17) follows the general solution:

$$(3.19) \quad X_{jk}^i = \bar{T}_{jk}^i - T_{jk}^i - \bar{\Theta}_{jk}^i + \bar{\Omega}_{sj}^{ir} U_{rk}^s$$

$$(3.20) \quad Y_{jk}^i = \bar{S}_{jk}^i - S_{jk}^i + \bar{\Omega}_{sj}^{ir} V_{rk}^s$$

where $U, V \in Z_2^1(M)$. Thus we have:

Theorem 3.8. *Between two given metrical Finsler connections $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$ the relations (3.18) exist, where X and Y are given by (3.19) and (3.20).*

Consequently neither in this case are X, Y completely arbitrary, only up to a transformation (3.19)–(3.20).

Summary

1. The Miron-Hashiguchi transformations are used if we wish to determine all metrical Finsler connections $F\bar{\Gamma}(\bar{N})$ from a fixed Finsler connection $F\Gamma(N)$.

2. The transformations (3.5) (or equivalently (3.6), (3.16), (3.17)) are used if we wish to determine metrical Finsler connections $F\bar{\Gamma}(\bar{N})$ with special properties (for example: $\bar{I}_1 = I_1$, $\bar{I}_2 = I_2$ or $\bar{I}_1 = 0$, $\bar{I}_2 = 0$) starting from a fixed non-metrical Finsler connection $F\Gamma(N)$.

3. The transformations (3.18) are used if we wish to determine arbitrary metrical Finsler connections $F\bar{\Gamma}(\bar{N})$, starting from a fixed metrical Finsler connection $F\Gamma(N)$.

4. The transformations (2.7) are used if we wish to determine Finsler connections with the properties (2.1) (particularly also metrical Finsler connections) whose torsions $\bar{T}, \bar{S}$ have given properties (for example: $\bar{I}_1 = I_1$, $\bar{I}_2 = I_2$ or $\bar{I}_1 = 0$, $\bar{I}_2 = 0$, and so on).

If $F\Gamma(N)$ and $F\bar{\Gamma}(\bar{N})$ are metrical we can start from (3.18), (3.19), (3.20).

5. The Finsler connection transformations $t : F\Gamma(N) \rightarrow F\bar{\Gamma}(\bar{N})$ compatible with a metrical structure or with other structures (complex, symplectic, etc.) studied by G. ATANASIU [1], [2], [3] can be obtained explicitly from (2.7) by imposing of the corresponding conditions.

6. The conformal Finsler connection transformations $t : F\Gamma(N, \omega) \rightarrow F\bar{\Gamma}(\bar{N}, \bar{\omega})$ [4] are obtained from (2.9) in an explicit form, without the indetermination of ΩX and ΩY .

7. In the general case, when we have no information relative to the relations between these connections and g , then the general transformations from the Theorem 2.7 are used, imposing the desired conditions.

In this way a *synthesis* is obtained in the study of Finsler connection transformations.

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